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\*We reserve the right to change the information in this manual without prior notice



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# HMI-WPLSoft Instruction Manual



www.delta.com.tw/industrialautomation

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# Chapter 1 Getting Started

Delta Extension Digital I/O Module, DOP-EXIO14RAE and DOP-EXIO28RAE (hereinafter called "DOP-EXIO series") provided for DOP-AE series HMI only. Therefore, before using Delta Extension Digital I/O Module, the user has to open the ScrEdit (Screen Editor) programming software, click "File" > "New" to open a new project, and select the type of DOP-AE series HMI being used (see Fig. 1.1).

New Project		×
Project Name		
HMI		
Screen Name		
Screen_1		
Screen No		
1		
HMI		
DOP-AE10THTD 65536 Colors	*	
Base Port Controller		
Delta DVP PLC	*	
Printer		OK
🖨 NULL	*	Cancel

Fig. 1.1 New project dialog box

After selecting the type of DOP-AE series HMI, press OK button to complet the setting. Then, click "Options > "Configuration" to enter into "Other" tab in Configuration option (see Fig. 1.2). Check the box next to "Enable EXIO (Compile Ladder)" to activate the function of Delta Extension Digital I/O Module. The user can also select the digital input and output points here by using the drop down list right below the "Enable EXIO (Compile Ladder)" option (see Fig. 1.3).

#### Chapter 1 Getting Started | DOP-EXIO Series

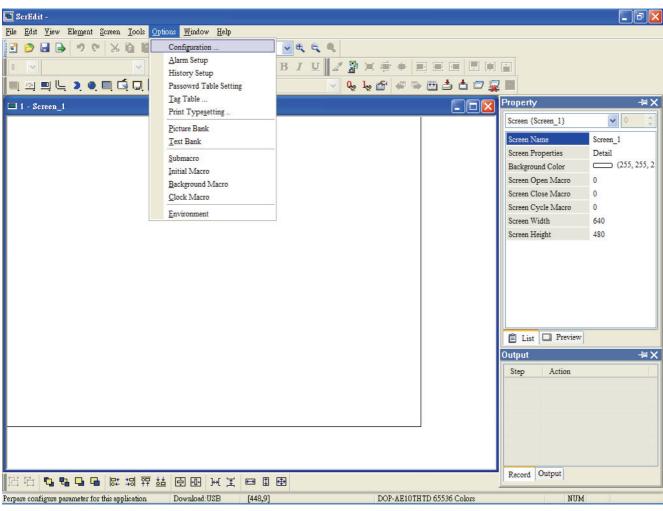


Fig. 1.2 Configuration option

Configuration						×
Standard Commun	nication Print Default	Other				_
Enable Screen	Saver	ScreenSæ	ver Time(M	in.) 0	*	
Read Control	ller Address	N	one			
Transition tit	me	1		(s	)	
When screen	saver ends		Return to C			
		<b>-</b> . ()	Choose scr	een		
- Multi-Language						
Number	Language Name		Value	En	New	
<b>♥</b> 1 (*)	Default		0	Yes	Enable	
					Remove	
					Modify	
Enable Edit 1	Multi-Language User Interf	face			Default	
-EXIO Setting						
-	O (Compile Ladder)					
		8 In / 6 Out		~		
				OK	Cancel	

Fig. 1.3 Other tab

When "Enable EXIO (Compile Ladder)" option is selected, the "Ladder Editor" icon will appear and be available for use on the toolbar (See Fig. 1.4 and 1.5). The user can click this icon and start ladder diagram editing directly or click "Tool" > "Ladder Editor" command from the menu (See Fig. 1.6).



Fig. 1.4 Toolbar before "Enable EXIO (Compile Ladder)" option is selected

2	2					Þ	i		-
$\mathbb{Z}$	0.,	1 <sub>68</sub>	6	42	<b>**</b>	<b>_</b>	đ	-	9 <u>1</u>

Fig. 1.5 Toolbar after "Enable EXIO (Compile Ladder)" option is selected

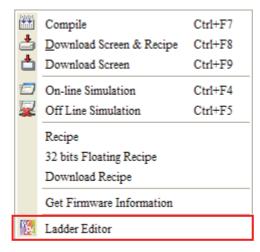


Fig. 1.6 Ladder Editor option

# Chapter 2 HMI-WPLSoft Introduction

Clicking the "Ladder Editor" is icon can open HMI-WPLSoft editing window immediately (see Fig. 2.1). At the same time, the window of ScrEdit (Screen Editor) will zoom out and hide automatically. Please note that HMI-WPLSoft and ScrEdit programming software cannot be used simultaneously. When the user is editing a ladder diagram and in the meantime the user wants to edit a HMI program, the user must close the window of HMI-WPLSoft and then it is possible for the user to edit a HMI program in the environment of ScrEdit programming software successfully. There is no Open and Save option provided in the ladder diagrm editing window. When the ladder diagrm editing window is closed, the ladder diagrm editing program is saved automatically.

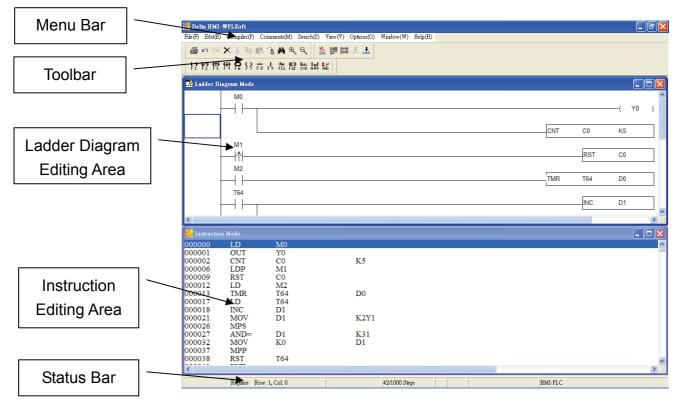


Fig. 2.1 HMI-WPLSoft editing window

There are five parts in the following for the window of HMI-WPLSoft.

Menu bar

🙀 File(F) Edit(E) Compiler(P) Comments(M) Search(S) View(V) Options(O) Window(W) Help(H)

There are nine functions for selection: File(F), Edit(E), Compiler(P), Comments(M), Search(S), View(V), Options(O), Window(W), and Help(H). Each option has a pull-down menu.

### Toolbar

There are many icons provided for the user to execute functions by clicking the mouse directly. The followings are the available toolbar on HMI-WPLSoft.

#### 1. Standard Toolbar

🎒 🗠 🗠 🗙 🐰 🖻 🖻 🔒 🖊 🔍 🍭

2. HMI-WPLSoft Toolbar

3. Ladder diagram Toolbar (display in Ladder Diagram Mode only)

#### ■ Ladder Diagram Editing Area

This is the area for designing the editing the ladder diagram by requirement.

Instruction Editing Area

This is the area for designing the editing the instructions by requirement.

Status Bar

It is used to display messages, including replace/insert mode, the coordinate of the editing diagram or object, etc.

Replace	Row: 3, Col: 2	42/1000 Steps		HMI-PLC
-	· · · · · · · · · · · · · · · · · · ·	-		

### 2.1 File

The "File" function is shown as follows, including pull-down menu options:

🎆 Delta HMI-WPLSoft	
File(F) Edit(E) Compiler(P)	Comments(M) Search(S) View(V) Options(O) Window(W) Help(H)
Print(P) Ctrl+P Printer Setup(Q) Ctrl+Q	
Exit(X) Alt+X	
- 📑 Ladder Diagram Mode	
M0	
м1	

- Print(P) ⇒ Print current file (only print current window, i.e. one of ladder diagram or instruction mode).
  - Method 1: Click "File(F)" > "Print (P)".

  - Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (P).

After the editing is completed, the user can use the icon a or click "File" > "Print (P)" to print the editing program or instrucation and relevant data. In the different editing window, the user can use Print(P) function to print the ladder diagram or instruction data. Please refer to the following descriptions.

Print Ladder Diagram

In Ladder Diagram Mode (when the ladder diagram editing window is opened), click the icon in toolbar or choose "Print(P)" command from the "File" menu, the print selection dialog box will open allowing the user to set the print options, configure printed diagrams layout and print the ladder diagrams shown on the screen. When the print selection dialog box is opened, the user can choose "Whole Range" to print all ladder diagrams displayed on the screen or choose "Step Range Specification" to print the range specified by the user (Start and End). Also, the user can determine if the title, page numbers and cover are printed or not. Click "Preview" button is to show the ladder diagrams as they would look if printed. Click "Printer setup" button is to setup the printer and configure the layout of the printed ladder diagrams.

The ladder diagrams displayed in the ladder diagram editing window is the same as the printed file. It indicates that the comments will be printed also if there are comments displayed on the ladder diagrams.

### Print Instruction

In Instruction Mode (when the instruction editing window is opened), click the icon in toolbar or choose "Print(P)" command from the "File" menu, the print selection dialog box will open allowing the user to set the print options, configure printed instruction layout and print the instructions. When the print selection dialog box is opened, the user can choose "Whole Range" to print all instructions displayed on the screen or choose "Step Range Specification" to print the range specified by the user (Start and End). Also, the user can determine if the title, page numbers and cover are printed or not. Click "Preview" button is to show the instructions as they would look if printed. Click "Printer setup" button is to setup the printer and configure the layout of the printed instructions.

Selection						
Selection	Margins					
Whole Range	U 0 Cm					
Step Range Specification	B 0 Cm					
Start	L 0 Cm					
End	R 0 Cm					
Title	Print Setup					
🖵 Page						
Cover	Preview					
Frame	Cancel					

- Printer Setup(Q) ⇒ Select and set printer.
  - Method 1: Click "File" > "Printer Setup(Q)".
  - ♦ Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (Q).
- Exit(X)  $\Rightarrow$  End HMI-WPLSoft
  - Method 1: Click "File(F)" > "Exit(X)".
  - ♦ Method 2: Click the icon imes at the right upper corner of the window.
  - ♦ Method 3: Use keyboard shortcuts by pressing keys (Alt) + (X).

#### File Explanation:

There are six saved files which each one of them has different extension names created simutaneously after finishing program editing and compiler. If the user wants to copy a complete program (including all comments and settings in the program) to other disk or another directory, it is recommended to copy all six saved files with different extension names. If the user wants to make a complete backup copy of the program file, the following six different files should be saved all together.

	Extension Name		Explanation
1	* .DLP	⇔	The instruction file for DOP-EXIO series.
2	* .LAD	⇔	Ladder diagram file
3	* .L <b>MT</b>	⇒	The file used to record ladder diagram segment comments.
4	* .LAB	⇒	The file used to record label P and I.

Extension Name

Explanation

- 5 \* .**RCM**  $\Rightarrow$  The default comment file for special D/special M.

### 2.2 Edit

The "Exit" function is shown as follows, including pull-down menu options:

File(F)	ta HMI-WPLSoft Edit(E) Compiler(P)	Comments(M)	Search(S) View(V) Options(O) Window(W) Help(H)
6	⊷ Undo(U) ⇔ Redo(R)	Ctrl+Z Ctrl+Alt+Z	
<b>4 6</b> ·	Select All(A)	Ctrl+A	
🛃 La	δ Cut(I)	Ctrl+X	
	E Copy(C) C Paste (P)	Ctrl+C Ctrl+V	
	Insert Block(O) Insert Row(I) Delete Row(L) Delete Vertical Line	Ctrl+Ins Ctrl+I Ctrl+Y e(D) Ctrl+D	
	Program Title(S)	Ctrl+Alt+T	

- Undo(U) ⇒ Undo the most recent actions (the system allows the user to perform undo action for max. 10 times)
  - Method 1: Click "Edit(E)" > "Undo(U)".
  - ♦ Method 2: Click the icon ☐ on the toolbar.
  - ♦ Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (Z).
  - Method 4: Right click the mouse to get a pop-up menu and select "Undo" in the pop-up menu.
- Redo(R)  $\Rightarrow$  Redo the undo action.
  - Method 1: Click "Edit(E)" > "Redo(R)".
  - ♦ Method 2: Click the icon ☐ on the toolbar.
  - ♦ Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (Alt) + (Z).

Method 4: Right click the mouse to get a pop-up menu and select "Redo" in the pop-up menu.

- Select All(A)  $\Rightarrow$  Select everything in a program file.
  - Method 1: Click "Edit(E)" > "Select All (A)".
  - ♦ Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (A).
- Delete 
  ⇒ Delete a selection (selected block or data) where the cursor is.
  - ♦ Method 1: Click "Edit(E)" > "Delete".
  - $\otimes$  Method 2: Click the icon  $\mathbf{X}$  on the toolbar.
  - ♦ Method 3: Use keyboard shortcuts by pressing key (Delete).
  - Method 4: Right click the mouse to get a pop-up menu and select "Delete" in the pop-up menu.
- $Cut(T) \Rightarrow Cut$  a selection (selected block or data) in a program file.
  - Method 1: Click "Edit(E)" > "Cut(T)".
  - ♦ Method 2: Click the icon <sup>™</sup> on the toolbar.
  - ♦ Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (X).
  - Method 4: Right click the mouse to get a pop-up menu and select "Cut" in the pop-up menu.
- Copy(C)  $\Rightarrow$  Copy a selection (selected block or data) from a program file.
  - Method 1: Click "Edit(E)" > "Copy(C)".
  - ♦ Method 2: Click the icon <sup>➡</sup> on the toolbar.
  - ♦ Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (C).
  - Method 4: Right click the mouse to get a pop-up menu and select "Copy" in the pop-up menu.
- Paste(P)  $\Rightarrow$  Paste a selection (selected block or data) on a program file.
  - Method 1: Click "Edit(E)" > "Paste(P)".
  - $\otimes$  Method 2: Click the icon 💼 on the toolbar.
  - Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (V).
  - Method 4: Right click the mouse to get a pop-up menu and select "Paste" in the pop-up menu.

- Insert Block(O) ⇒ Insert a selection (selected block or data) into a program file (This function is valid for Ladder Diagram Mode only.).
  - Method 1: Click "Edit(E)" > "Insert Bock(O)".
  - Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (Ins).
  - Method 3: Right click the mouse to get a pop-up menu and select "Insert Block" in the pop-up menu.
- Insert Row(I) ⇒ Insert a blank row into a program file.
  - Method 1: Click "Edit(E)" > "Insert Row(I)".
  - Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (I).
  - Method 3: Right click the mouse to get a pop-up menu and select "Insert Row" in the pop-up menu.
- Delete  $Row(L) \Rightarrow$  Delete a row from a program file.
  - Method 1: Click "Edit(E)" > "Delete Row(L)".
  - Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (Y).
  - Method 3: Right click the mouse to get a pop-up menu and select "Delete Row" in the pop-up menu.
- Delete Vertical Line(D) ⇒ Delete the vertical lines from a program file(This function is valid for Ladder Diagram Mode only.).
  - Method 1: Click "Edit(E)" > "Delete Vertical Line(D)".
  - $\bullet$  Method 2: Click the icon  $\bullet$  on the toolbar.
  - ♦ Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (D).
  - Method 4: Right click the mouse to get a pop-up menu and select "Delete Vertical Line" in the pop-up menu.
- Program Title(S) ⇒ The information of program title, file name, company name and designer are shown here and can be printed as an easy cover.
  - Method 1: Click "Edit(E)" > "Program Title(S)".
  - ♦ Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (Alt) + (T).

## 2.3 Compiler

The "Compiler" function is shown as follows, including pull-down menu options:

🌇 Del	ta HMI-	WPLSoft							
File(F)	Edit(E)	Compiler(P)	Comments(M)	Search(S)	View(V)	Options(O)	Window(W)	Help(H)	
6	<b>10</b> 01		• Instruction(I) n => Ladder(L)		影響				
<b>!!</b>	<b>1∕2  1</b> 3		F 8 F 9 F11 F12		¥. ĤĐ				
🛃 La	dder Dia	agram Mode							
		M0							
	Ļ								
		1 1							

■ Ladder => Instruction(I) ⇒ Convert ladder diagrams to instruction codes.

Method 1: Click "Compiler(P)" > "Ladder => Instruction(I)".

 $\$  Method 2: Click the icon  $\$  on the toolbar.

Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (F9).

Instruction => Ladder(L)  $\Rightarrow$  Convert instruction codes to ladder diagrams.

Method 1: Click "Compiler(P)" > "Instruction => Ladder(L)".

♦ Method 2: Click the icon ⊥ on the toolbar.

♦ Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (F10).

### 2.4 Comments

The "Comments" function is shown as follows, including pull-down menu options:

🌇 Delta HMI	-WPLSoft	
File(F) Edit(E	) Compiler(P)	Comments(M) Search(S) View(V) Options(O) Window(W) Help(H)
<b>₽ №</b> №	XXD	Image: Edit Device Comments(D)       Ctrl+Alt+D         Image: Edit Segment Comments(B)       Ctrl+Alt+B
	방답되	Edit Row Comments(L) Ctrl+Alt+L
📑 Ladder D	iagram Mode	
📑 Ladder D	iagram Mode M0	

■ Edit Device Comments(D) ⇒ Insert a comment for every operand of the device where the cursor is positioned.

Method 1: Click "Comment(M)" > " Edit Device Comments(D)".

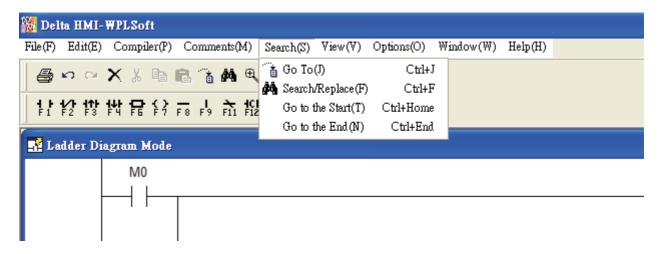
- ♦ Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (Alt) + (D).
- Method 3: Right click the mouse to get a pop-up menu and select "Edit Device comments" in the pop-up menu.
- Edit Segment Comments(B) ⇒ Insert a segment comment in the blank row (This function is valid for Ladder Diagram Mode only.).
  - Method 1: Click "Comment(M)" > "Edit Segment Comments(B)".
  - ♦ Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (Alt) + (B).
  - Method 3: Right click the mouse to get a pop-up menu and select "Edit Segment Comments" in the pop-up menu.
- Edit Row Comments(L) ⇒ Insert a row comment after output coil or instruction of each row (This function is valid for Ladder Diagram Mode only.).

Method 1: Click "Comment(M)" > " Edit Row Comments(L)".

- ♦ Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (Alt) + (L).
- Method 3: Right click the mouse to get a pop-up menu and select "Edit Row comments" in the pop-up menu.

## 2.5 Search

The "Search" function is shown as follows, including pull-down menu options:



- Go to(J)  $\Rightarrow$  Jump to the designated location (unit: Step).
  - Method 1: Click "Search(S)" > "Go to(J)".
  - ♦ Method 2: Click the icon <sup>1</sup> on the toolbar.
  - Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (J).
- Search/Replace(F) ⇒ Search or replace the device name and instruction of the designated device.
  - Method 1: Click "Search(S)" > "Search/Replace(F)".
  - ♦ Method 2: Click the icon ▲ on the toolbar.
  - Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (F).
- Go to the Start(T)  $\Rightarrow$  Jump to the start of the program.
  - ♦ Method 1: Click "Search(S)" > "Go to the Start(T)".
  - Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (Home).
- Go to the End(N)  $\Rightarrow$  Jump to the end of the program.
  - Method 1: Click "Search(S)" > "Go to the End(N)".
  - Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (End).

### 2.6 View

The "View" function is shown as follows, including pull-down menu options:

🎇 Delta HMI- WPLSoft	
File(F) Edit(E) Compiler(P) Comments(M) S	earch(S) View(V) Options(O) Window(W) Help(H)
_ <b>● ∽ ∼ X</b> % <b>h f i A 4</b> € ¢	Toolbars(T)   Toolbars(T)  Zoom(Z)  Standard
計控控性管容素。 Ladder Diagram Mode	Instruction List     Instruction List       Image: State of the state of t
	Image: Show Comments(M)       Image: Show Comments(M)         Image: Show Comments(M)       Image: Show Comments(M) </td
M1 	▼ 75% ▼ 100% 125% 150% 175% 200%

- Toolbars(T) ⇒ Display a list of the toolbars available in HMI-WPLSoft, including Status Bar, Standard, PLC and Ladder Diagram toolbars.
  - Status Bar: display or hide status bar.

 Replace
 Row: 3, Col: 2
 42/1000 Steps
 HMI-PLC

Method: Click "View(V)" > "Toolbars(T)" > "Status Bar".

• Standard: display or hide standard toolbar.

🞒 いい X 🐰 🖻 🖻 🔒 👭 락 🧶

Method: Click "View(V)" > "Toolbars(T)" > "Standard".

• PLC: display or hide HMI-WPLSoft toolbar.

Method: Click "View(V)" > "Toolbars(T)" > "PLC".

 Ladder Diagram toolbar: display or hide Ladder Diagram toolbar (display in Ladder Diagram Mode only).

\* 다 12 등 다 다 다 다 다 다 다 13 나 다 14 km

♦ Method: Click "View(V)" > "Toolbars(T)" > "Ladder Diagram".

Zoom(Z)  $\Rightarrow$  Let the user change and reduce the magnification level of the program.

Zoom In 🖭 function is used to get a closer look of the program and Zoom Out

function is used to see more of the program. The default settings for zooming provided by the system are Auto, 50 %, 75 %, 100 %, 125 %, 150 %, 175 % and 200 %.

- Method 1: Click "View(V)" > "Zoom (Z)".
- Method 2: Zoom In. Use keyboard shortcuts by pressing keys (Shift) + (Alt) + (I) or click the icon on the toolbar to zoom in.
- Method 3: Zoom Out. Use keyboard shortcuts by pressing keys (Shift) + (Alt) + (O) or click the icon 
   on the toolbar to zoom out.

- Instruction List(I)  $\Rightarrow$  Change to Instruction Mode.
  - Method 1: Click "View(V)" > "Instruction List(I)".
  - ♦ Method 2: Click the icon is on the toolbar.
- Ladder  $Diagram(L) \Rightarrow Change to Ladder Diagram Mode.$ 
  - Method 1: Click "View(V)" > "Ladder Diagram(L)".
  - $\otimes$  Click the icon  $\mathbb{B}$  on the toolbar.
- List of Used Device(U)  $\Rightarrow$  Display all device usage status.
  - Method 1: Click "View(V)" > "List of Used Device(U)".
  - ♦ Method 2: Use keyboard shortcuts by pressing keys (Ctrl)+ (Alt) + (U).
- Show Comments(M)  $\Rightarrow$  Display or hide device comments.
  - Method 1: Click "View(V)" > "Show Comments(M)".
  - ♦ Method 2: Click the icon <sup>IIII</sup> on the toolbar.

### 2.7 Options

The "Options" function is shown as follows, including pull-down menu options:

🧱 Delta HMI-WPLSoft	
File(F) Edit(E) Compiler(P) Comments(M) Search(S) View(V)	Options(O) Window(W) Help(H)
● ∽ ~ X % ┣ ■ 含 桷 曳 ↓ 號 課牒	Prompt to Edit Device Comment(H)
	Language Setup(L)   Tranditional Chinese
1 1 1/1 1/1 1/1 1/1 1/2 () - 1 → 1/1 1/2 1/2 ket F1 F2 F3 F4 F6 F7 F8 F9 F11 F12 c+0 A+9 A+0	Simplied Chinese
	🗸 English
📑 Ladder Diagram Mode	
M0	

■ Prompt to Edit Device Comment(H) ⇒ If this option is selected, in Instruction Mode or Ladder Diagram Mode, the system will ask the user to enter the corresponding device comment at the same time when the user uses the instruction code to edit a DOP-EXIO series program.

Method: Click "Options(O)" > "Prompt to Edit Device Comment(H)".

■ Language Setup(L) ⇒ Allow the user to change the display language of HMI-WPLSoft by requirement. There are three available languages for selection, Tranditional Chinese, Simplied Chinese and English.

Method: Click "Options(O)" > "Language Setup(L)".

### 2.8 Window

The "Window" function is shown as follows, including pull-down menu options:

🌇 Del	ta HMI-	WPLSoft						
File(F)	Edit(E)	Compiler(P)	Comments(M)	Search(S) V	∛iew(V)	Options(O)	Window(W) Help(H)	
6	<b>ന</b> വ	XXD	<b>r 🚡 👭</b> 🖽				☐ Cascade(C) ☐ Tile Horizontally(H)	
	<b>1∕1 111</b> F2 F3	<b>料 骨</b> 谷	F8 F9 F11 F1	Inder I ← I 2 C+D A+F9 A+I	н   D		DD Tile Vertically(V)	
Ladder Diagram Mode								
HE La	uuer Di	agram moue					✓ <u>2</u> Ladder Diagram Mode	
		M0						1

Cascade(C)  $\Rightarrow$  Arrange windows in an overlapping way.

Method: Click "Window(W)" > "Cascade(C)".

Title Horizontally(H)  $\Rightarrow$  Arrange the file in a horizontal way.

Method: Click "Window(W)" > "Title Horizontally(H)".

- Title Vertically(V)  $\Rightarrow$  Arrange files in a vertical way.
  - ♦ Method: Click "Window(W)" > "Title Vertically(V)".
- The current files list ⇒ e.g. Instruction Mode and Ladder Diagram Mode.

Method: In HMI-WPLSoft editing window, activate Instruction Mode and Ladder Diagram Mode and click "Window(W)", and then the user can see them show in Window drop-down menu.

## 2.9 Help

The "Help" function is shown as follows, including pull-down menu options:

🌇 Del	ta HMI	WPLS	oft											
File(F)	Edit(E)	Com	piler(P)	Com	uments(	M)	Search(S)	View(	(V)	Options(O)	Window(W)	Help(H)		
6	<b>n</b> ci	×	( Be	6.1	ă M	€	٩		11-5 11-5			🦓 Abou	tt HMI-WPLSoft(A)	
<b>       </b>	<b>1∕2 1</b> 13	봕두	<b>}</b> {}	F8 F	9 F11	<b>ICH</b> F12	loel I← C+D A+F9	¥. A+D						
🛃 La	dder Di	iagram	Mode											
		N	10											

■ About HMI-WPLSoft(A) ⇒ This command shows the version information of HMI-WPLSoft.

Method: Click "Help(H)" > "About HMI-WPLSoft(A)".

# **Chapter 3** Creating and Editing Programs

Activate HMI-WPLSoft, and then the system will enter into Ladder Diagram Mode as shown as the Fig. 3.1 below.

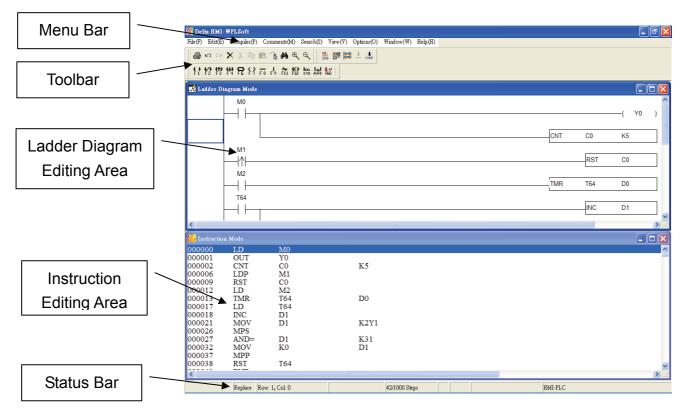


Fig. 3.1 Ladder Diagram Mode

There is a ladder diagram toolbar shown on the top of the Ladder Diagram Mode window. To create and edit a ladder diagram, the user can click the icon on toolbar directly by the mouse or move the editing block to the proper position and enter instructions. Besides, the user also can press F1 ~ F12 function keys on the keyboard to create and edit the ladder diagram. Please refer to the following sections for how to create and edit ladder diagram.

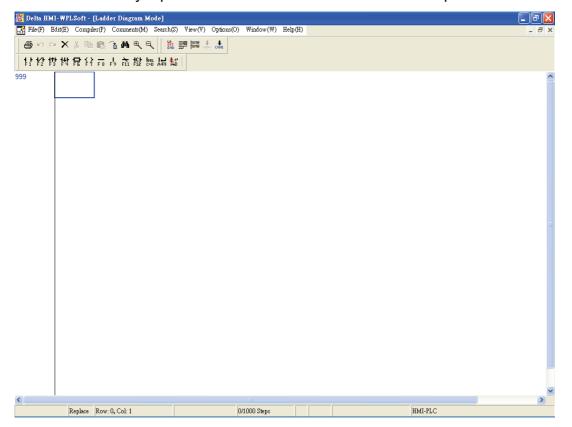
## 3.1 Basic Operation

Example: Create the diagram shown below.



■ Using the mouse and F1 ~ F12 function keys on the keyboard.

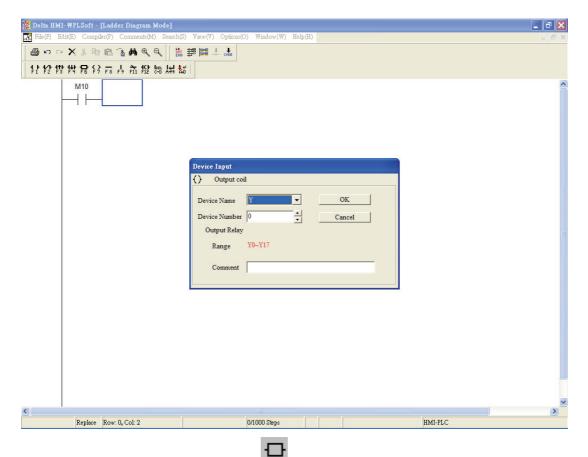
1. Click the Normally Open Contact icon **F1** on the toolbar or press F1 function key.



2. The "Device Input" dialog box will appear. The user can select device name (e.g. M), device number (e.g. 10), and enter comments (e.g. Internal Relay). Then, press the button "OK" to save the settings.

Device Input								
Constantly opened contact								
Device Name	M	OK						
Device Number	10	Cancel						
Internal Relay								
Range	M0~M999							
Comment								
<u></u>								

3. Click the Output Coil icon icon icon icon the toolbar or press F7 function key. The "Device Input" dialog box will appear next. The user can select device name (e.g. Y), device number (e.g. 0), and enter comments (e.g. Output Relay). Then, press the button "OK" to save the settings.



4. Click Application Instruction icon **F6** or press F6 function key. Choose "Function" from the "Function" drop-down menu and select "END" instruction from the "Application Instruction" drop-down menu. The user can also type in "END" instruction directly in the field of "Application Instruction". Then, press the button "OK" to save the settings.

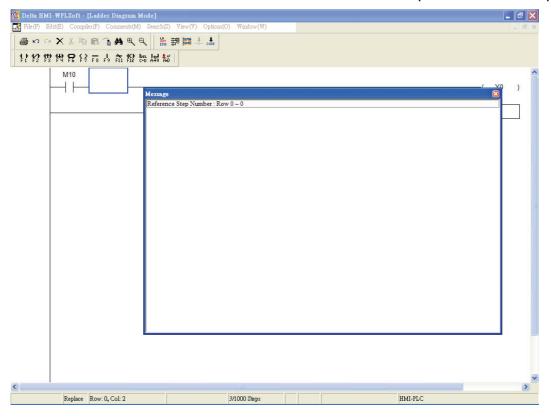
🎇 Delta HMI-WPLSoft - [Ladder Di	agram Mode]						ð	×
		) ∀iew(V) Options(O) Window(W) Hel	p(H)				- 6	×
🕘 🗠 🗠 🗙 🐇 🖻 🔒 📬 🌢	• • • • •	19 10						
111212121212		221						
	Application Ins Application List API Number Function	tructions n Instructions	END FRID FARD FOR HEX INC INC INC INC	OK Cancel	(	YO	)	
<							>	
Replace Row: 1, Col	:1	0/1000 Steps		HMI-PLC				

5. Click the icon to compile the ladder diagram and convert it to instruction codes.

After compiler action is completed, the numbers of steps will show on the left-hand side of the start of the ladder diagram.

🎇 Delta HMI-WPLSoft - [Ladder Diagram Mode] 👘					_	ð	×
File(F) Edit(E) Compiler(P) Comments(M) Search	(S) View(V) Options(O) W	Vindow(W) Help	(H)			- 8	×
<i>⊜</i> ∽∼X% ≞≣3#€€							
· # # # # # # 유 두 두 두 바 # 11	kť.						
0 M10	~						^
					—( Y0	)	
2					_( 10	,	
-					END		
999					- Contract (		
	n	Delta HMI-WPL:	Soft 🔀				
		Compiling is com	nleted II				
		OK					
	_						
							~
Replace		00 Steps		HMI-PLC		>	J
	0/100	oo napo.		IIMI-TEC			

6. If the ladder diagram is not correct, an error message dialog box will appear and point out the exact erroneous rows and addresses after the compiler action is completed.



- Keyboard Operation
  - Place the editing block at the start of the program (Row: 0, Col: 1), and type in "LD M10" by using the keyboard. Then, press the Enter key on the keyboard, or click the "OK" button to complete the settings.

🌇 Delta HMI-	WPLSoft -	[Ladder Diagram M	[ode]						_ 7 🛛
		er(P) Comments(M)				Help(H			_ 8 ×
<b>8</b> 000	XXh	<b>₽ ₩ ₽ €</b>							
		F8 F9 F11 F12 6							
	F4 F6 F7	F8 F9 F11 F12 c	*D A+F9 A+D						
999									<u>^</u>
-		1							
			Input Inst	ruction	LD M10		OK Cance	1	
					1			-	
									3
									~
<								)	>
	Replace	Row: 0, Col: 1			0/1000 Steps			HMI-PLC	

2. Type in "OUT Y0" by using the keyboard and press Enter key on the keyboard. Then, type in "END" by using the keyboard and press Enter key on the keyboard. Finally,

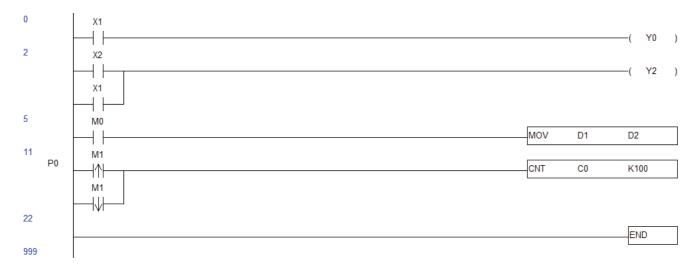
click the icon to compile the completed ladder diagram.

If the user wants to edit the comments at the same time when input an instruction by using keyboard, the user can click the "Prompt to Edit Device Comment(H)" under the "Options" menu. Then, the "Comment" dialog box (see the figure below) will appear for the user to enter and edit the corresponding comments after an instruction is input correctly.

Comment			×
Device	Edit Comment		
Y0 -	Output	OK	Cancel

## 3.2 Editing Example

Ladder Diagram



### Operation steps for editing the Ladder Diagram

Step	Ladder Symbol	Cursor Location	Input by cli	cking the Icon on the toolbar	Input by using the Keyboard
1	Τ	Row: 0, Column: 1	Footnote 1	Device Name: X Device Number: 1	ل or A X1 ل LD X1
2	(	Row: 0, Column:2	<mark>위</mark> *Footnote 2	Device Name: Y Device Number:0	or O Y0 لہOUT Y0
3	$\dashv \vdash$	Row: 1, Column: 1	f Fi	Device Name: X Device Number:2	لہ or A X2 لہ LD X2
4		Row: 1, Column: 2	F 9		F9
5	-( )	Row: 1, Column: 2	<b>( )</b> F7	Device Name: Y Device Number:2	ل or O Y2 ل OUT Y2
6	Τ	Row: 2, Column: 1	<b>H</b> Fi	Device Name: X Device Number:1	ل or A X1 ل LD X1
7	$\dashv \vdash$	Row: 3, Column: 1	f Fi	Device Name: M Device Number:0	لہ or A M0 لہ LD M0
8	—	Row: 3, Column: 2	<b>F</b> *Footnote 3	MOV Instruction Operand 1: D Device Number:1 Operand 2: D Device Number:2	MOV D1 D2 斗
9		Row: 4, Column: 0		Double click the mouse and enter P0	ب P0

Step	Ladder Symbol	Cursor Location	Input by cli	cking the Icon on the toolbar	Input by using the Keyboard
10	↑	Row: 4, Column: 1	<b>t</b> F3	Device Name: M Device Number:1	ل or + M1 ل LDP M1
11		Row: 4, Column: 2	<b>H</b> F 9		F9
12		Row: 4, Column: 2	<b>1</b>	CNT Instruction Operand 1: C Device Number: 0 Operand 2: K Device Number: 100	CNT C0 K100 🎝
13	↓	Row: 5, Column: 1	봕	Device Name: M Device Number: 1	لہ or – M1 لہ LDF M1
14	—	Row: 6, Column: 1	<b>C</b> F6	END Instruction	END ↓

After the ladder diagram is completed, the user can compile and convert the completed ladder diagram to instruction codes. The ladder diagram which has been converted to instruction codes is shown as the figure below.

		nstruction Mode]						- 7 ×
OUT File(F)	Edit(E) Compile	r(P) Comments(M) S	earch(S) View(V) Options(O)	Window(W) H	Ielp(H)			- 8 ×
1		B 78 M 4 9						
1		F 8 F 9 F11 F12 C+D 1						
000000	LD	X1						<u>^</u>
000001	OUT	Y0						
000002	LD	X2						_
000003	OR	X1						
000004	OUT	Y2						
000005	LD	T12						
000006	MOV	D1	D2					
000011	P000							
000012	LDP	M1						
000015	ORF	M1						
000018	CNT	C0	K100					
000022	END							
000023	NOP							
000024	NOP							
000025	NOP							
000026	NOP							
000027	NOP							
000028	NOP							
000029	NOP							
000030	NOP							
000031	NOP							
000032	NOP							
000033	NOP							
000034	NOP							
000035	NOP							
000036	NOP							
000037	NOP							
000038	NOP							
000039	NOP							
000040	NOP							
000041	NOP							
000042	NOP							
000043	NOP							
000044	NOP							
000045	NOP							
000046	NOP							×
<								>
	Replace 1	Row:0	2.	3/1000 Steps		HMI-I	LC	

\*Footnote 1: Input Basic Instruction

1. Click the icon 🔢 on the toolbar or press the F1 function key on the keyboard

and the "Device input" dialog box will appear. Then, the user can enter device name, device number, and edit comments in this dialog box.

Device Input								
Constantly opened contact								
Device Name	X	OK						
Device Number		Cancel						
Input Relay								
Range	X0~X17							
Comment								

2. For example, select the device name "X" and device number "1" from the drop-down menu or type in the device name "X" and device number "1" by using the keyboard. Then, press Enter key on the keyboard or click the "OK" button to save the settings.

Device Input		
- Constantly	opened contact	
Device Name	X	OK
Device Number	1 *	Cancel
Input Relay	_	
Range	X0~X17	
Comment	[	
L		

\*Footnote 2: Input Output Coil

1. Click the icon 2 on the toolbar or press the F7 function key on the keyboard and the "Device input" dialog box will appear. Then, the user can enter device name, device number, and edit comments in this dialog box.

Device Input			140013
() Output coi	1		
Device Name	Y	OK	
Device Number	1	Cancel	
Output Relay	_		
Range	Y0~Y17		
Comment			

2. For example, select the device name "Y" and device number "1" from the drop-down menu or type in the device name "Y" and device number "1" by using the keyboard. Then, press Enter key on the keyboard or click the "OK" button to save the settings.

\*Footnote 3: Input Application Instruction

1. Click the icon  $\blacksquare$  on the toolbar or press the F6 function key on the keyboard

and the "Application Instructions" dialog box will appear.

Application Instr	actions
Application 1	Instructions
Function List	Function OK
API Number	Application Instruction     Cancel
Function	

- First, choose one selection from the "Function List" drop-down menu (including all application instructions and output commands, etc.). Then, select the "API Number" and "Application Instruction". The user can also type in the desired instruction, e.g. MOV in the "Application Instruction" drop-down menu directly. After all settings are completed, press Enter key on the keyboard.
- 3. Select "Transfer and Compare" from the "Function List" drop-down menu and type in "MOV" in the field of "Application Instruction" directly (or choose "MOV" instruction from the "Application Instruction" drop-down menu). Then, press Enter key on the keyboard, and the user can see the figure below on the screen.

#### Chapter 3 Creating and Editing Programs | DOP-EXIO Series

Appl	icatio	on In	istruc	tion	s														
₽	App	licati	on In	struc	tions	1							Ν						
Fu	nctio	ion List Transfer and Compare										•	▼ OK						
AP	'I Nu:	mber 12  Application Instruction MOV									Cancel			]					
Fus	nctio	n	I	Datal	Mov	•													
S			Г		•														
D	I		Í		•														
Refer	rence																		
Op	P	I	N	X	Y	Μ	S	К	Н	KnX	KnY	KnM	KnS	Т	С	D	E	F	^
S								*	*	*	*	*	*	*	*	*	*	*	
D											*	*	*	*	*	*	*	*	~
Op										Help									
S	Dat	a sou	arce	_		_	_			11010							_		
D	Dat	a mo	ve de	stina	tion														_
																			~

- Input device name in the field of "S" (Operand 1) and "D" (Operand 2), and input device number in the field of "Device Number" in order. Select index register E or F if it exists. Then, press the "OK" button to save the settings.
- 5. The user can also double click the mouse on the "@" or "\*" symbol in the device reference table (refer to the figure above) to designate the device name (The symbol @ indicates this device can be modified by index register E or F and the symbol \* indicates this device can not be modified by index register E or F).

## 3.3 Ladder Diagram Editing Explanation

### Keyboard Entry

HMI-WPLSoft provides several brevity codes for the user to input Instructions more quickly and conveniently when editing a ladder diagram. Please refer to the following table.

Explanation	Instruction Icon	Instruction Code (Mnemonic Code)	Brevity Code	Example
Normally open contact	1 F	LD	А	LD M0 or A M0
Normally closed	12	LDI	В	LDI M0 or B M0

Explanation	Instruction Icon	Instruction Code (Mnemonic Code)	Brevity Code	Example
contact				
Rising pulse	111 F3	LDP	+	LDP M0 or + M0
Falling pulse	14	LDF	—	LDF M0 or – M0
Output coil	\$ ?	OUT	0	OUT M0 or O M0

#### Insert / Replace Mode

Using the "Insert" key on the keyboard can switch to the Insert Mode or the Replace Mode when editing a ladder diagram.

- If the "Replace" word is displayed on the status bar, pressing the Insert key on the keyboard is to switch to the Insert Mode. In the Insert Mode, insert a new ladder diagram to where the editing block is located, and the original ladder diagrams following the new diagram will shift one space to the right.
- If the "Insert" word is displayed on the status bar, pressing the Insert key on the keyboard is to switch to the Replace Mode. In Replace Mode, inserting a new ladder diagram can replace the original ladder diagram located in the editing block, and the following other ladder diagrams will not be changed.

### Edit(E)

- Undo(U) ⇒ Undo the most recent actions (the system allows the user to perform undo action for max. 10 times)
  - Method 1: Click "Edit(E)" > "Undo(U)".
  - ♦ Method 2: Click the icon ☐ on the toolbar.
  - ♦ Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (Z).
  - Method 4: Right click the mouse to get a pop-up menu and select "Undo" in the pop-up menu.
- **Redo**(R)  $\Rightarrow$  Redo the undo action.
  - Method 1: Click "Edit(E)" > "Redo(R)".
  - ♦ Method 2: Click the icon ☐ on the toolbar.
  - ♦ Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (Alt) + (Z).
  - Method 4: Right click the mouse to get a pop-up menu and select "Redo" in the pop-up menu.

■ Delete ⇒ Delete a selection (selected block or data) where the cursor is.

Method 1: Click "Edit(E)" > "Delete".

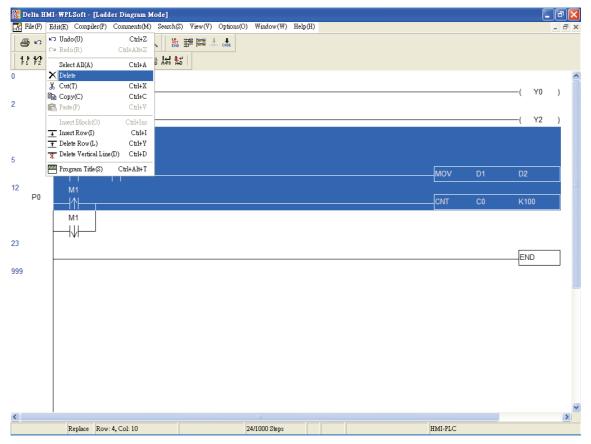
- $\otimes$  Method 2: Click the icon  $\mathbf{X}$  on the toolbar.
- ♦ Method 3: Use keyboard shortcuts by pressing key (Delete).
- Method 4: Move the cursor to the diagram block that the user wants to delete and right click the mouse to get a pop-up menu and select "Delete" in the pop-up menu to delete the selected diagram block.

ю	Undo(U)	Ctrl+Z
Ci	Redo(R)	Ctrl+Alt+Z
	Select All(A)	Ctrl+A
X	Delete	
*	Cut(T)	Ctrl+X
Đ	Сору(С)	Ctrl+C
ß	Paste(P)	Ctrl+V
	Insert Block(O)	Ctrl+Ins
Ŧ	Insert Row(I)	Ctrl+I
Ť	Delete Row(L)	Ctrl+Y
X	Delete Vertical Line(D)	) Ctrl+D
888	Program Title(S)	Ctrl+Alt+T

- Delete Row(L) ⇒ Delete a row or several rows in the ladder diagram
  - Method 1: Click "Edit(E)" > "Delete Row(L)". Then, the row where the cursor is will be deleted and the rows below the deleted row will move up.
  - Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (Y).
  - Method 3: Move the cursor to the row that the user wants to delete and right click the mouse to get a pop-up menu and select "Delete Row(L)" in the pop-up menu to delete the row.

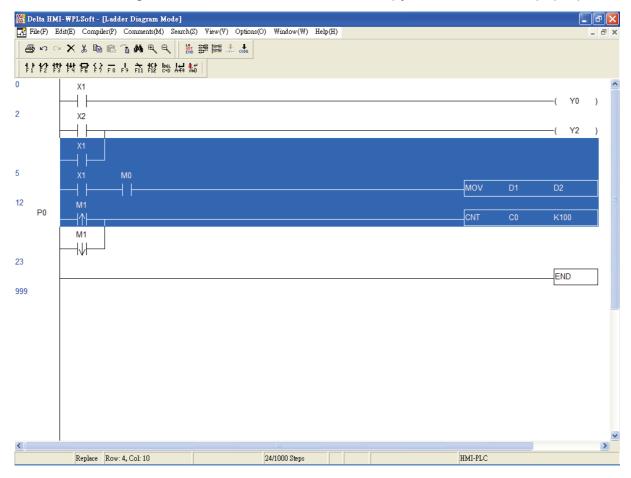
ĸ	Undo(U)	Ctrl+Z
C4	Redo(R)	Ctrl+Alt+Z
	Select All(A)	Ctrl+A
X	Delete	
*	Cut(T)	Ctrl+X
Þ	Copy(C)	Ctrl+C
ß	Paste(P)	Ctrl+V
	Insert Block(O)	Ctrl+Ins
ŧ	Insert Row(I)	Ctrl+I
Ť	Delete Row(L)	Ctrl+Y
×	Delete Vertical Line(D)	) Ctrl+D
888	Program Title(S)	Ctrl+Alt+T

- Method 4: Select the row that the user wants to delete. Right clicking the mouse to select the "Delete" command in the pop-up menu can delete the selected row immediately. Pressing the Delete key on the keyboard or clicking the icon on the toolbar can also delete the selected row.
- Delete Vertical Line(D) ⇒ Delete the vertical lines in the ladder diagram.
  - Method 1: Click "Edit(E)" > "Delete Vertical Line(D)". Then, the vertical line on the left-hand side of the editing block will be deleted.
  - Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (D).
  - Method 3: Move the editing block to the right-hand side of the vertical line that the user wants to delete and click the icon be on the toolbar. Then, the vertical line on the left-hand side of the editing block will be deleted.
  - Method 4: Move the editing block to the right-hand side of the vertical line that the user wants to delete. Right click the mouse to get a pop-up menu and select "Delete Vertical Line(D)" in the pop-up menu. Then, the vertical line on the left-hand side of the editing block will be deleted.
- Delete Block  $\Rightarrow$  Delete the selected block.
  - Method 1: Click "Edit(E)" > "Delete". Then, the selected block in the ladder diagram that the user wants to delete will be deleted immediately.



- Method 2: Select the block that the user wants to delete and click the icon 
   in the toolbar.
- Method 3: Select the block that the user wants to delete and right click the mouse to select the "Delete" command in the pop-up menu.
- Method 4: Select the block that the user wants to delete and press the Delete key
   on the keyboard.
- Copy Block  $\Rightarrow$  Copy the selected block.
  - Method 1: Click "Edit(E)" > "Copy(C)".
  - ♦ Method 2: Click the icon 🗎 on the toolbar.
  - Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (C).

♦ Method 4: Right click the mouse to select the "Copy" command in the pop-up menu.



- Cut Block ⇒ Cut the selected block.
  - Method 1: Click "Edit(E)" > "Cut(T)".
  - $\bullet$  Method 2: Click the icon  $\mathbb{X}$  on the toolbar.
  - Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (X).
  - Method 4: Right click the mouse to select the "Cut" command in the pop-up menu.

■ Paste Block ⇒ Paste the selected block.

- Method 1: Click "Edit(E)" > "Paste(P)".
- $\otimes$  Method 2: Click the icon 🖺 on the toolbar.
- Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (V).
- Method 4: Right click the mouse to select the "Paste" command in the pop-up menu.
- Insert Block ⇒ Insert the selected block (This function is valid after the "Copy Block" function is executed. Therefore, before inserting the selected block, perform "Copy Block" action first).
  - Method 1: Click "Edit(E)" > "Insert Block(O)".
  - Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (Ins).
  - Method 3: Right click the mouse to select the "Insert Block" command in the pop-up menu.

Ø	Undo(U)	Ctrl+Z
Ci	Redo(R)	Ctrl+Alt+Z
	Select All(A)	Ctrl+A
×	Delete	
Ж	Cut(T)	Ctrl+X
Þ	Copy(C)	Ctrl+C
ł	Paste(P)	Ctrl+∛
	Insert Block(O)	Ctrl+Ins
Ŧ	Insert Row(I)	Ctrl+I
Ť	Delete Row(L)	Ctrl+Y
×	Delete Vertical Line(D)	) Ctrl+D

### Compiler(P)

This function is used to compile current HMI-WPLSoft programs for DOP-EXIO series product. If the user completes the editing of the ladder diagram in the ladder diagram mode, performing this function will check whether the ladder diagram is valid or not. If there is no error occurred when converting the program, the ladder diagram can be converted to the instruction program successfully; meanwhile, the program memory addresses (numbers of steps) for each editing block will appear on the left-hand side of the start of the ladder diagram. However, if there is any error occurred, a ladder diagram error message dialog box will appear to display the error code and point out the exact erroneous addresses (exact row and column where the error occurred) after the compiler action is completed. If the user completes program editing in the instruction mode when performing this function, the system will start to check if there is any error occurred or not. If there is no error, the

instruction program will be converted to the ladder diagram successfully. However, if there is any error occurred, an error message dialog box will appear to display the error code and point out the exact erroneous steps (where the error occurred) after the compiler action is completed.

Ladder => Instruction(I)  $\Rightarrow$  This function is valid in Ladder Diagram Mode only.

Method 1: Click "Compiler(P)" > "Ladder => Instruction(I)".



♦ Method 2: Click the icon <sup>▲</sup> on the toolbar.

- Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (F9).
- Instruction => Ladder(L) ⇒ This function is valid in Instruction Mode only.

Method 1: Click "Compiler(P)" > "Instruction => Ladder(L)".



 $\otimes$  Method 2: Click the icon  $\blacksquare$  on the toolbar.

Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (F10).

# Search(S)

- Go to(J) ⇒ Jump to the designated location (unit: Step). This command is used to specify the program to jump to a designated location. If the designated step already exists, the program will jump to this existing designated step and put it in the first line.
  - Method 1: Click "Search(S)" > "Go to(J)". Enter the designated step where the user want to jump to, and then the ladder diagram will put this designated step in the first line.

♦ Method 2: Click the icon i on the toolbar.

Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (J).

■ Search/Replace(F)

The "Search/Replace(F)" command is used to search and replace the device and instruction within the program (if only the "Search" command is used, just enter the device name to be searched in the dialog box). If the device or the command is found, the view will be scrolled to the device or the command. Also, the user can search and replace the device and instruction by specifying the type of the device and instruction.

Method 1: Click "Search(S)" > "Search/Replace(F)".

♦ Method 2: Click the icon ▲ on the toolbar.

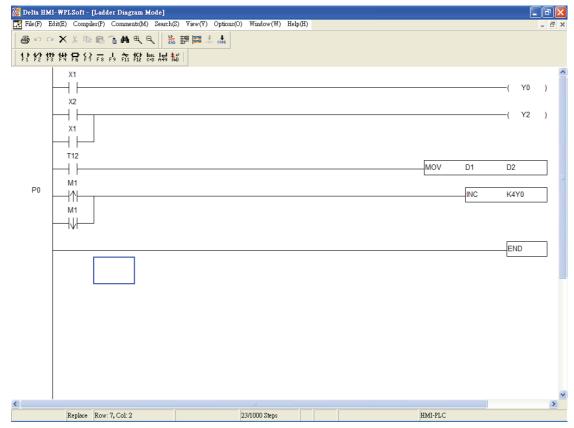
Method 3: Use keyboard shortcuts by pressing keys (Ctrl) + (F).

When the user selects the "Search/Replace" command, the following "Search/Replace" dialog box will appear. There are "Search Device", "Replace Device", "Search Instruction" and "Replace other Instruction" four functions in this dialog box for the user to use.

Search/Replace			
Search Device Replace D	evice	Search Instruction	Replace other Instr
Search Device			_
Туре	None		•
Scope From Cursor From Scope		Direction Forward Backward	
Search		Cancel	

Search Device

Use this command to search the specified device name match the search criteria in the program. For example, in the ladder diagram shown below, the instructions that contain device name Y0 are OUT Y0 and INC K4Y0.



Activate "Search/Replace" fuction to open "Search/Replace" dialog box and choose the "Search Device" tab. Enter device name "Y0" in the field of "Search Device" and select the "None" in the field of "Type". Then, press the "Search" button and the system will find the instructions "OUT Y0" and "INC K4Y0".

Search/Replace			X
Search Device	Replace Device	Search Instruction	Replace other Instr 📕 🕨
Search Device	YO		_
Туре	None		•
Scope From Curso From Scope		Direction • Forward • Backward	
Se	arch	Cancel	

However, if enter the device name "Y0" in the field of "Search Device" still, but change the "None" to "Fun." in the field of "Type", only the instruction "INC K4Y0" will be found when "Search" button is pressed.

Search/Replace			
Search Device	Replace Device	Search Instruction	Replace other Instr 🔳 🕨
Search Device	YO		_
Туре	Fun.		-
Scope		Direction	
From Curso	r	Forward	
C From Scope		C Backward	
Se	arch	Cancel	

Replace Device

Use this command to replace the specified device name match the search criteria in the program. For example, activate "Search/Replace" fuction and choose the "Replace Device" tab. In "Replace Device" tab, enter the "X0" in the field of "Search Device" and select the type of search device as "LD". Then, enter the "M100" in the field of "Replace Device" and select the type of replace device as "LD". Next, type in "10" in the field of "Device Number". Finally, press the "Replace" button, and the instructions which match the criteria will be changed to LD M100~M109.

Original Commane	d	Criteria					•	laced mand			
LD X0~X7		Type LD	+ Dev	vice X0	$\rightarrow$ T	ype L	D + D	evic	e M100	LD M10	00~M107
LD X10~X1	1			Device	e Nur	mber:	10			LD M10	)8~M109
	Searc	ch/Replace									
	Sear	rch Device	Replace	e Device	Sear	ch Instr	uction	Repl	ace other I	nstr 💶 🕨	
	Sea	arch Device		X0		Туре	LD	-			
	Re	place Devic	e	M100		Type	LD	•	Repla	ice	
	De	vice Numbe	n	10							
		cope			Direct						
		From Curs				rward					
	0	Entire Sco	pe		O Ba	ckward			Cano	:el	
	•	Copy Comments to Replace Devices									
	V										
	,		elete Source Device Comments								

If the user choose the device type as None, Out and Fun these three types, only the same type of the device which the name match the replace criteria can be replaced.

When None, Out and Fun these three types are selected, if the user tries to replace the different type of the device, a warning message dialog box looks like the figure below will appear.

Delta HMI-WPLSoft
Replacement instruction type is illegal; None, Out, Fun can be replaced with the same type.

Besides, the user can use "Copy Comments to Replace Devices" this option to copy the comments into the replace device. If "Delete Source Device Comments" this option is also selected, the comments of the search device will be deleted after the comments of the search device has been copied to the replace device. In this case, the boxes next to "Copy Comments to Replace Devices" and "Delete Source Device Comments" are checked both. It indicates that when the device name is replaced, i.e. the "Replace" button is pressed, the comment of the search device "X0" will be copied to the replace device "M100" and the comment of the search device "X0" will be deleted immediately at the same time.

# ✓ Limits

In "Replace Device" dialog box, only the devices of the same type can be replaced. For example, if D1 is replaced by D11, it is thus viewed as successful replacement; but if it

is replaced by C100, it is then a failure.

# Search Instruction

Use this command to search the specified instruction name match the search criteria in the program. Click "Search Instruction" tab after the "Seach/Replace" function is activated, and enter the instruction name that the user is looking for in the field of "Search Instruction". Then, press the "Search" button to start the search. The system will memorize and record all the searched instruction names in the "Search Instruction" drop-down menu. This is a useful function for the user to search more quickly and conveniently next time.

Search/Replace		
Search Device Replace Device	Search Instruction	Replace other Instr 🔺 🕨
Search Instruction Scope	et Direction © Forward © Backward Can	

Replace other Instruction

In "Replace other Instruction" tab, the system provides the replace criteria for SET, RST, PLS and PLF, these four kinds of instructions and allows the user to replace the devices match the criteria of these instructions in the program. For example, if the user wants to replace SET M0 ~ M35 with SET Y0 ~ Y43, in order to complete the replacement, the user can set the settings as shown as the figure below.

Search/Replace			×		
Replace Device Searc	h Instruction	Replace other Instr	uction I		
SET  Repl	ch Device ace Device ce Number	M0 Y0 36	Replace		
Scope From Cursor		rward			
<ul> <li>○ Entire Scope</li> <li>○ Backward</li> <li>Cancel</li> <li>✓ Copy Comments to Replace Devices</li> <li>✓ Delete Source Device Comments</li> </ul>					

Besides, as the boxes next to "Copy Comments to Replace Devices" and "Delete Source Device Comments" are checked both, it indicates that when the device name is replaced, the comments of the search device "M0 ~ M35" will be copied to the replace device "Y0 ~ Y43" and the comments of the search device "M0 ~ M35" will be deleted immediately at the same time.

Go to the Start(T)  $\Rightarrow$  Jump to the start of the program.

Method 1: Click "Search(S)" > "Go to the Start(T)".

♦ Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (Home).

Go to the End(N)  $\Rightarrow$  Jump to the end of the program.

Method 1: Click "Search(S)" > "Go to the End(N)".

Method 2: Use keyboard shortcuts by pressing keys (Ctrl) + (End).

# 3.4 Editng Instructions

Input DOP-EXIO Series Instructions

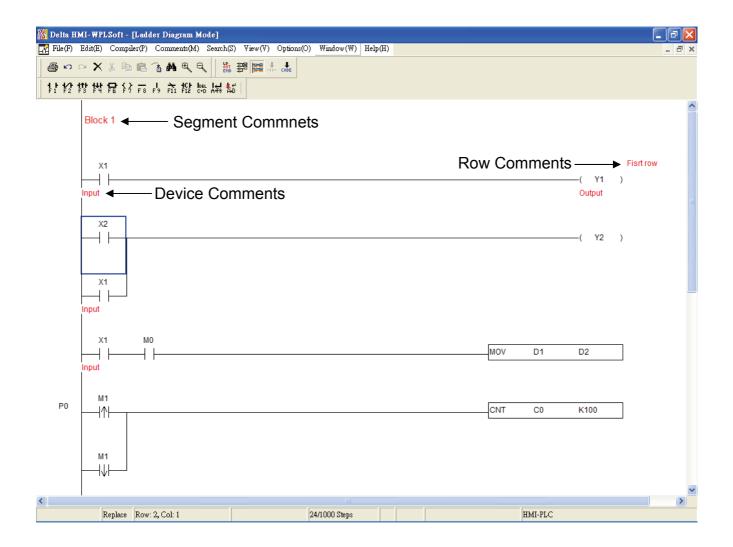
After entering the instruction mode, the user may type an instruction directly. If the instruction format is valid, press the Enter key on the keyboard to complete the settings. The input instructions will be located in the editing area and the program memory address of DOP-EXIO series will appear on the left-hand side of the program. Thus, the user can get the corresponding program memory addresses of the instructions clearly. For the introductions of the formats of all instructions, please refer to Appendix A and Appendix B in this manual.

# 3.5 Editing Comments

In the ladder diagram mode, there are three operating modes for editing comments: Device comments, Segment comments and Row comments. Please refer to the following sections for more introductions on editing comments.

Ladder Diagram Mode:

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# Edit Device Comments

Move the editing block on the desired device and right click the mouse. The pop-up menu box shown on the following figure will appear. From this pop-up menu, choosing "Edit Device Comments" can enter and edit device comments. After editing the comments is completed, press "Enter" key on the keyboard or click the "OK" button by using the mouse to have the record saved.

		Soft - [Ladder Diagram										. ð 🗙
		Compiler(P) Comments(A	1		₩indow(₩)	Help(H)						- 8 ×
1		X B B 3 # 4	1									
F1 F2	F3 141 1	않 쇼 유 ㅋ 우 ㅋ	C+D A+F9 A+D									
	Block	1										^
	Diocit											
	X1									( ) <b>(</b>	Fisrt row	
	Input	Undo	Ctrl+Z							— ( Y1 Output	)	
		Redo	Ctrl+Alt+Z									≡
	x	Delete										
		Cut Copy	Ctrl+X Ctrl+C							—( Y2	)	
	-	Paste	Ctrl+V									
	x	Insert Block Insert Row	Ctrl+Ins Ctrl+I									
	Input	Delete Row	Ctrl+Y									
		Delete Vertical Line	Ctrl+D									
	x	Edit Device Comments Edit Segment Comments	Ctrl+Alt+D Ctrl+Alt+B								_	
	Input	Edit Row Comments	Ctrl+Alt+L					MOV	D1	D2		
	input											
P0	M1										_	
10								CNT	C0	K100		
	M1											
	<u> </u> − ↓											
<											j	>
	R	eplace Row: 1, Col: 1		2	24/1000 Steps				HMI-PLC			
										_		
		Commen	đ									
		Device	Edit	Comment								
					1		ОК		Cancel	7		
		X1	- Inpu	ut Output Coi	4				Cancer			

Edit Row Comments: (Only for ladder diagram mode)

Enable this function, and then the user can edit all row comments at the same time.

🎆 Row Co	omment 🔀
Row	Comment
0	
*1	Fisrt row
*2	
3	
*4	
*5	
6	
*7	

Edit Segment Comments: (Only for ladder diagram mode)

After editing the segment comments is completed, press the "OK" button to save the settings.

Edit Comment	Block 1	OK Cancel
	Dioca I	

# 3.6 Edit Device Comments

In the Ladder Diagram Mode and Instruction Mode, the user can set the comments to be displayed in the device.

Method 1:

 First, choose to enter the Ladder Diagram Mode (or Instruction Mode). Move the editing block on the desired device. From the "Comments" menu, choose "Edit Device Comments(D)" or use the keyboard shortcuts by pressing keys (Ctrl) + (Alt) + (D).

🌇 Delta HMI-WPLSoft - [Ladder Diagram Mode]			
File(F) Edit(E) Compiler(P) Comments(M) Search		H)	_ @ ×
B ∽ ∼ X % B C H Edit Device Comme	nts(D) Ctrl+Alt+D		
	uents(B) Ctrl+Alt+B		
	s(L) Ctrl+Alt+L		
			<u>^</u>
Block 1			
X1			Fisrt row
			(Y1 )
Input			Output
X2			( Y2 )
			( Y2 )
X1			
Input			
X1 M0			
		MOV	D1 D2
Input			
M1			
		CNT	C0 K100
M1			
			×
<	Ш		
Replace Row: 0, Col: 1	24/1000 Steps	HM	I-PLC

2. The Comment dialog box will appear and the user can edit comments for the desired device that the user chooses, e.g. M0 (If the chose device is the special M and D device, the user will see the preset comments shown in the Comment dialog box). After the device comments editing is completed, press "Enter" key on the keyboard or click the "OK" button by using the mouse.

Comment			×
Device M0 💌	Edit Comment Relay	OK	Cancel

3. If the user wants to display or hide device comments in the Ladder Diagram Mode, click the icon <sup>IIII</sup> on the toolbar or choose "Show Comments(M)" from "View(V)" menu.

# Method 2:

1. Enter the Ladder Diagram Mode (or Instruction Mode). Move the editing block on the desired device (such as T64). Right click the mouse and then the following pop-up menu will appear on the screen.

Ctrl+Z
Ctrl+Alt+Z
Ctrl+X
Ctrl+C
Ctrl+V
Ctrl+Ins
Ctrl+I
Ctrl+Y
Ctrl+D
Ctrl+Alt+D
Ctrl+Alt+B
Ctrl+Alt+L

# In Ladder Diagram Mode

## In Instruction Mode

Select all	Ctrl+A
Undo	Ctrl+Z
Redo	Ctrl+Alt+Z
Delete	
Cut	Ctrl+X
Сору	Ctrl+C
Paste	Ctrl+V
Insert Row	Ctrl+I
Device comment	Ctrl+Alt+D
Export to Excel	

2. Choose "Edit Device Comments" from the pop-up menu, and the Comment dialog box will appear (see the figure below). Select the desired device, e.g. T64 and enter the comments for device T64. After the comments editing is completed, press "Enter" key on the keyboard or click the "OK" button by using the mouse.

Comment	
Device Edit Comment	
T64 Timer	OK Cancel

# 3.7 Edit Row Comments

# Method 1:

1. Move the editing block to the desired row. Right click the mouse and the pop-up menu below will appear. Select "Edit Row Comments" to add and edit comments into the row.

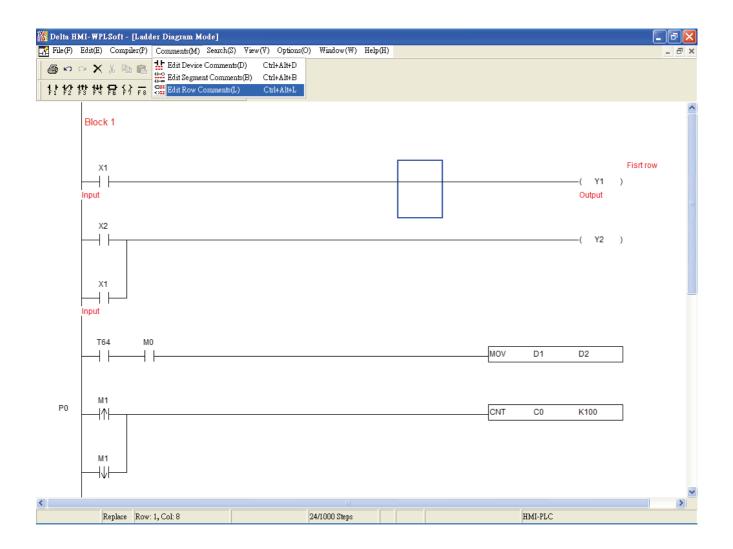
Undo	Ctrl+Z
Redo	Ctrl+Alt+Z
Delete	
Cut	Ctrl+X
Сору	Ctrl+C
Paste	Ctrl+V
Insert Block	Ctrl+Ins
Insert Row	Ctrl+I
Delete Row	Ctrl+Y
Delete Vertical Line	Ctrl+D
Edit Device Comments	Ctrl+Alt+D
Edit Segment Comments	Ctrl+Alt+B
Edit Row Comments	Ctrl+Alt+L

2. After clicking on "Edit Row Comments", the following dialog box will appear. Then, the user can add and edit several row comments at the same time. After the comments editing is completed, close this dialog box to save the edited comments.

omment 🔀	]
Comment	T
	Ī
Fisrt row	-
	1
	1
	1
	1
	1
	1

# Method 2:

Move the editing block on the desired device. From "Comments" menu, choose "Edit Row comments(L)" or use the keyboard shortcuts by pressing keys (Ctrl) + (Alt) + (L). The "Row comment" dialog box will appear. Then, the user can enter the comments in each row. After the row comments editing is completed, close this dialog box to save the edited comments.



# 3.8 Segment Comments

Method 1:

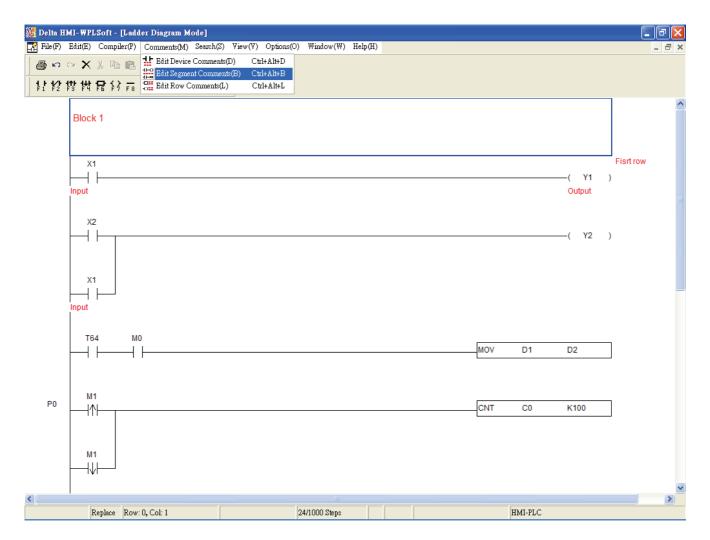
Move the editing block to the blank area that the user wants to enter the segment comments (the user can also use the keyboard shortcuts by pressing keys (Ctrl) + (I) to insert a new row). Right click the mouse, and the pop-up menu in the following figure will appear. Then, choose "Edit Segment Comments" to enter the segment comments (60 characters maximum). Finally, press the "OK" button to complete the editing.

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		adder Diagram Mode] (P) Comments(M) Search(S)	View(V) Options(O)	Window(W)	Help(H)					<b>₽</b> ×
~ ~ ~ ~	XXBI	1.5								
-	X1       I       I       I       I       X2       I	Undo Redo Delete Cut Copy Paste Insert Block Insert Row Delete Row	Cttl+Z           Cttl+Alt+Z           Cttl+X           Cttl+V           Cttl+V           Cttl+Ins           Cttl+I           Cttl+I           Cttl+Y					——( Y1 Output ——( Y2	Fisrt row )	•
In	X1 	Delete Vertical Line Edit Device Comments Edit Segment Comments Edit Row Comments	Cttl+D Cttl+Alt+D Cttl+Alt+B Cttl+Alt+L			 MOV	D1	D2	]	
PO	M1  ↑					 CNT	C0	K100	]	
<	Replace R	tow: 0, Col: 1	24	4/1000 Steps			HMI-PLC			>
		Edit Comment	Block 1				OK	Cancel		

# Method 2:

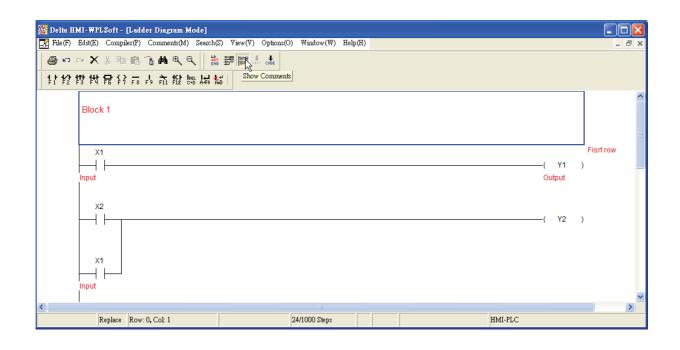
Click "Comment" from the menu bar, and choose "Edit Segment Comments(B)" or use the keyboard shortcuts by pressing keys (Ctrl) + (Alt) + (B) to enter and edit the segment comments.



# ■ Show or Hide Comments

The user can show and hide the comment by clicking "View(V)" > "Show Comments(M)" or clicking the icon is on the toolbar. However, this function is provided for device comments and row comments only. The user cannot show and hide segment comments by using this function. When this function is enabled, the height of the ladder diagram will become higher in order to display the comments.

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# Chapter 4 I/O Point Indicators

In the editing environment of ScrEdit (Screen Editor) programming software, the user can use digital input/output point indicators (hereinafter called "I/O point indicators") to display the status of the input and output points and monitor the operation of DOP-EXIO series. Please refer to the Fig. 4.1 below.

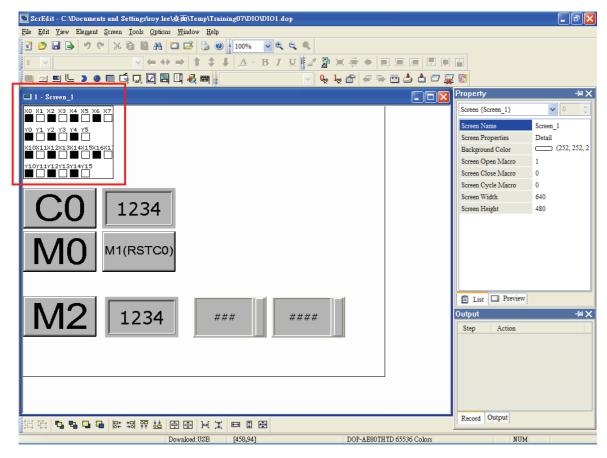


Fig. 4.1 Status of I/O point indicators

After opening the "Screen Properties" dialog box, which provides screen property settings for each screen, the user can set the settings of the I/O point indicators. Please refer to Fig. 4.2 in the following page.

Screen Properties			
Screen Number			
General View Screen     Apply Print Screen	← Hard Copy Region —		
This screen is a sub-screen	Top-Left	0	0
<u>W</u> idth 640	Right-Bottom	639	479
<u>H</u> eight 440		х	Y
<ul> <li>○ Center on display</li> <li>● Origin: X 0 Y 0</li> <li>✓ Use Title Bar</li> </ul>	Use base screen		
Macro Cycle Delay 100 🔹 ms			
Fast Refresh Rate			
EXIO Indicator X Y			
Top-Left 0 0 Font Size	Display Type		OK
Right-Bottom 160 130 8	Single	~	Cancel

Fig. 4.2 "Screen Properties" dialog box

1. Display Position:

Determine the position of the I/O point indicators by setting the coordinates of the Top-Left and Right-Bottom points.

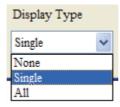
2. Font Size:

Determine the font size of the font which displays in the I/O point indicators. (The available selection includes 8, 10, 12, 14, 16, 18, 20, 24, 28, 32, 40, 48, 64.)

3. Display Type:

There are three kinds of display types: None, Single and All. The display of the indicators will change depending on the settings of the screen properties. None: When the user selects this option, the indicators will not show on the screen.

- Single: When the user selects this option, the indicators will display on a certain screen only.
- All: When the user selects this option, the indicators will display on all screens.



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# Chapter 5 Internal Memory Address

After enabling the DOP-EXIO function, all the HMI elements can use DOP-EXIO series as internal memory addresses. The usage is the same as the usage of HMI internal memory \$0 ~ \$65535. Some of the internal memory addresses are "For latched". For more introductions and the setting range of each device, please refer to Appendix A in this manual.

When the function for DOP-EXIO series is activated, the devices for DOP-EXIO series will appear in the "Device Type" drop-down menu shown in the "Internal Memory" selection. Some of the devices have special definitions and will be set or referred within some specific instructions. For more descriptions of the devices and instructions for DOP-EXIO series, please refer to Appendixes in this manual.

Input	? 🔀
Гуре	
O PLC Device (Word)	Link Internal Memory 🗸
O PLC Device (Bit)	Device Type ID
• Internal Memory (Word)	Addr/Value \$ \$M *\$
O Internal Memory (Bit)	Tag IX IY
○ Constant	!M
	B C D IS
○10 ○10U ○16	6 7 8 !C
010 0100 010	1 2 3 !E
PLC Station Number	0 : + - /
0 🔷 Default	None

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# Appendix A List of Devices

Туре	Device		tem	Range	Function		
	V	Input relay		X0~X7, 8 points, octal	DOP-EXIO14RAE	Corresponds to external input point.	
	Х			X0~X17, 16 points, octal	DOP-EXIO28RAE	Corresponds to external input point.	
				Y0~Y5, 6 points, octal	DOP-EXIO14RAE	Internal output point.	
	Y			Y0~Y5, Y10~Y15, 12 points, octal	DOP-EXIO28RAE	Internal output point.	
	Μ	Auxiliary Relay General puspose M0~M 744 po M1279		M0~M511, M768~M999, 744 points; M1000~ M1279, 280 points <sup>*2</sup> M512~M767, 256 points	Total is 1,280 points	The contacts can be ON/OFF in the program.	
Relay (bit)	т	Timer	100ms	T0~T63, 64 points	~T63, 64 points Total is		
			10ms	T64~T126, 63 points	128 points	target, the T contact of the same number	
			1ms	T127, 1 point		will be On.	
			16-bit	C0~C111, 112 points	Total is	Counter indicated by CNT (DCNT)	
	С	Countor	counting up	C112~C127, 16 points	128 points	instruction. If	
	C	Counter	32-bit	C235,C236,C237,C238,		counting reaches its target, the C contact	
			counting	C241,C242,C244,C246,	Total is	of the same number	
			up/down	C247,C249,C251,C252,	13 points	will be On.	
			(Latched <sup>*1</sup> )	C254, 13 points			
	S	Step point	Latched <sup>*1</sup>	S0~S127, 128 points	Total is 128 points	Used for step ladder diagram	
Register (word data)	Т	Present va	alue of timer	T0~T127, 128 points	When the timing reaches the target, the contact of the timer will be On.		

Туре	Device		Item	em Range				
d data)	С	Present	value of counter	C0~C127, 16-bit counter, C235,C236,C237,C238, ( C246, C247,C249,C251,( counter, 13 points	When the ounting reaches the arget, the contact of the counter will be On.			
Register (word data)			General purpose	D0~D407, 408 points				
tegist	D	Data	Latched <sup>*1</sup> D408~D599, 192 points			storage; E, F can be used for index		
Ľ.		register	Index indication	E. F. 2 points To		indication.		
iter	N	For masternested loc		N0~N7, 8 points	N0~N7, 8 points			
Pointer	Р	For CJ, C instructio		P0~P63, 64 points	Position index for CJ and CALL.			
Constant	К	Decimal	form	K-32,768 ~ K32,767 (16-bit operation) K-2,147,483,648 ~ K2,147,483,647 (32-bit operation)				
Con	Н	Hexadec	imal form	H0000 ~ HFFFF (16-bit operation) H00000000 ~ HFFFFFFF (32-bit operation)				

\*1: The latched area is fixed and cannot be changed.

\*2: M1000, M1001, M1002, M1003, M1020, M1021, M1022, M1067, M10068, and M1161 are the special auxiliary relays (special M).

# **Special Auxiliary Relay**

The types and functions of special auxiliary relays (special M) are listed in the table below. Please be noted that the columns marked with "R" refers to "read only", "and "R/W" refers to "read and write" and "-" refers to the status remains unchanged.

		Power Off	STOP	RUN				
Special M	Function	Û	Û	Û	Attribute	Latched	Default	Applicable Model
		Power On	RUN	STOP				
M1000	Monitoring normally open	Off	On	Off	R	No	Off	
1011000	contact (A) <sup>*1</sup>	Oli	On	Oli	Γ	INU	Oli	
M1001	Monitoring normally closed	On	Off	On	R	No	On	
IVI I UU I	contact (B) *2	OII	Oli	On	Γ	INO	On	
M1002	Enabling positive pulses *3	Off	On	Off	R	No	Off	DOP-EXIO14RAE
M1003	Enabling negative pulses *4	On	Off	On	R	No	On	DOP-EXIO28RAE
M1020	Zero flag	Off	-	-	R	No	Off	
M1021	Borrow flag	Off	-	-	R	No	Off	
M1022	Carry flag	Off	-	-	R	No	Off	
M1067	Calculation error	Off	Off	-	R	No	Off	

		Power Off	STOP	RUN				
Special M	Function	Û	Û	Û	Attribute	Latched	Default	Applicable Model
		Power On	RUN	STOP				
M1068	Calculation error locked	Off	-	-	R	No	Off	
MAACA	8/16 bit mode switch	0"				Nie	0"	DOP-EXIO14RAE
M1161	On: in 8-bit mode	Off	-	-	R/W	No	Off	DOP-EXIO28RAE

\*1: M1000 (A contact) is constantly "On" during operation and detection. When ELC is in RUN status, M1000 remains "On".

\*2: M1001 (B contact) is constantly "Off" during operation and detection. When ELC is in RUN status, M1001 remains "Off"

\*3: M1002 is "On" during the first scan when ELC starts to RUN and remains "Off" afterward. The pulse width = 1 scan time. Use this contact for all kinds of initial settings. (On immediately when RUN).

\*4: M1003 is "Off" during the first scan when ELC starts to RUN and remains "On" afterward. M1003 enables negative-direction pulses. ("Off" immediately when RUN)

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# Appendix B List of Instructions

	Ava	ailable Instructions			
16-bit Instruction	32-bit Instruction	Function			
LD	-	Loading in A contact			
LDI	-	Loading in B contact			
AND	-	Series Connection- A Contact			
ANI	-	Series Connection- B Contact			
OR	-	Parallel Connection- A Contact			
ORI	-	Parallel Connection- B Contact			
ANB	-	Series connection- loop blocks			
ORB	-	Parallel connection- loop blocks			
MPS	DMOV	Store the current result of the internal EXIO operations			
MRD	DCML	Read the current result of the internal EXIO operations			
ANDP	-	Rising-edge Series Connection			
ANDF	DFMOV	Falling-edge Series Connection			
ORP	DXCH	Rising-edge Parallel Connection			
ORF	DBCD	Falling-edge Parallel Connection			
PLS	DBIN	Rising-edge Output			
PLF	DADD	Falling-edge Output			
END	DSUB	Program End			
NOP	DMUL	No Operation			
INV	DRCL	Inverting Operation			
Р	-	Pointer			
MOV	-	Move			
CML	-	Compliment			
BMOV	-	Block Move			
FMOV	-	Fill Move			
ХСН	-	Exchange			
BCD	-	Binary Coded Decimal			
BIN	-	Binary			
ADD	-	Addition			
SUB	-	Subtraction			
MUL	-	Multiplication			
RCL	-	Rotation Left with Carry			
SFTR	-	Bit Shift Right			
SFTL	-	Bit Shift Left			
ZRST	-	Zero Reset			

## Appendix B List of Instructions | DOP-EXIO Series

	Ava	ailable Instructions
16-bit Instruction	32-bit Instruction	Function
SUM	DSUM	Sum of Active Bits
BON	DBON	Check Specified Bit Status
MEAN	DMEAN	Mean
REF	-	Refresh
ALT	-	Alternate State
ASCI	-	Convert Hex to ASCII
AND=	DAND=	Series Connection Contact Compare =
AND>	DAND>	Series Connection Contact Compare >
AND<	DAND<	Series Connection Contact Compare <
AND<>	DAND<>	Series Connection Contact Compare <>
AND<=	DAND<=	Series Connection Contact Compare <=
AND>=	DAND>=	Series Connection Contact Compare >=
MPP	-	Pop (recall and remove) the currently stored result
OUT	-	Output Coil
SET	-	Latch (ON)
RST	-	Clear the contacts or the registers
TMR	-	16-bit Timer
CNT	DCNT	16-bit / 32-bit Counter
МС	-	Master Control Start
MCR	-	Master Control Reset
LDP	-	Rising-edge Detection Operation
LDF	-	Falling-edge Detection Operation
STL	-	Step Transition Ladder Start Command
RET	-	Step Transition Ladder Return Command
CJ	-	Conditional Jump
CALL	-	Call Subroutine
SRET	-	Subroutine Return
FEND	-	The End of the Main Program (First End)
FOR	-	Start of a FOR-NEXT Loop
NEXT	-	End of a FOR-NEXT Loop
CMP	DCMP	Compare
ZCP	DZCP	Zone Compare
DIV	DDIV	Division
INC	DINC	Increment
DEC	DDEC	Decrement
WAND	DAND	Logical Word AND
WOR	DOR	Logical Word OR

Available Instructions					
16-bit Instruction	32-bit Instruction	Function			
WXOR	DXOR	Logical Exclusive OR			
NEG	DNEG	2's Complement (Negative)			
ROR	DROR	Rotation Right			
ROL	DROL	Rotation Left			
RCR	DRCR	Rotation Right with Carry			
HEX	-	Convert ASCII to Hex			
ABS	DABS	Absolute Value			
SWAP	DSWAP	Byte Swap			
LD=	DLD=	Load Contact Compare =			
LD>	DLD>	Load Contact Compare >			
LD<	DLD<	Load Contact Compare <			
LD<>	DLD<>	Load Contact Compare <>			
LD<=	DLD<=	Load Contact Compare <=			
LD>=	DLD>=	Load Contact Compare >=			
OR=	DOR=	Parallel Connection Contact Compare =			
OR>	DOR>	Parallel Connection Contact Compare >			
OR<	DOR<	Parallel Connection Contact Compare <			
OR<>	DOR<>	Parallel Connection Contact Compare <>			
OR<=	DOR<=	Parallel Connection Contact Compare <=			
OR>=	DOR>=	Parallel Connection Contact Compare >=			

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# Appendix C Use of Basic Instructions

LD Loading in A contact	

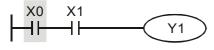
Operand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	$\checkmark$	$\checkmark$	✓	$\checkmark$	$\checkmark$	$\checkmark$	-

# **Explanation:**

The LD instruction is used on the A contact that has its start from the left BUS or the A contact that is the start of a contact circuit. The functions are to save the present contents and store the acquired contact status into the accumulative register.

# **Program Example:**

Ladder diagram:



Instructi	on code:	Operation:
LD	X0	Loading in contact A of X0
AND	X1	Connecting to contact A of X1 in series
OUT	Y1	Driving Y1 coil

Mnemonic	Functions
LDI	Loading in B contact

Operand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	✓	$\checkmark$	~	$\checkmark$	✓	✓	-

# **Explanation:**

The LDI instruction is used on the B contact that has its start from the left BUS or the B contact that is the start of a contact circuit. The functions are to save the present contents and store the acquired contact status into the accumulative register.

# **Program Example:**

Ladder diagram:



Instruct	tion code:	Operation:
LDI	X0	Loading in contact B of X0
AND	X1	Connecting to contact A of X1 in series
OUT	Y1	Driving Y1 coil

Mnemonic	Functions
AND	Series Connection- A Contact

Operand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
operand	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	-

# Explanation:

The AND instruction is used in the series connection of A contact. The functions are to read out the status of present specific series connection contacts and perform the "AND" operation with the logical operation result obtained. The final result will be store in the accumulative register.

# Program Example:

Ladder diagram:



Instruct	ion code:	Operation:
LDI	X1	Loading in contact B of X1
AND	X0	Connecting to contact A of X0 in series
OUT	Y1	Driving Y1 coil

Mnemonic	Functions
ANI	Series Connection- B Contact

Operand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	✓	$\checkmark$	✓	$\checkmark$	$\checkmark$	$\checkmark$	-

# **Explanation:**

The ANI instruction is used in the series connection of B contact. The functions are to read out the status of present designated series connection contacts and perform the "AND" operation with the logical operation result obtained. The final result will be store in the accumulative register.

# **Program Example:**

Ladder diagram:

X0	
-11	

Instruct	ion code:	Operation:
LD	X1	Loading in contact A of X1
ANI	X0	Connecting to contact B of X0 in series
OUT	Y1	Driving Y1 coil

Mnemonic	Functions
OR	Parallel Connection- A Contact

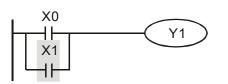
Operand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	$\checkmark$	$\checkmark$	✓	$\checkmark$	$\checkmark$	$\checkmark$	-

# Explanation:

The OR instruction is used in the parallel connection of A contact. The functions are to read out the status of present designated parallel connection contacts and perform the "OR" operation with the logical operation result obtained. The final result will be store in the accumulative register.

# Program Example:

Ladder diagram:



Instructio	on code:	Operation:
LD	X0	Loading in contact A of X0
OR	X1	Connecting to contact A of X1 in parallel
OUT	Y1	Driving Y1 coil

Mne	emonic	Functions
C	DRI	Parallel Connection- B Contact

Operand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	✓	$\checkmark$	~	$\checkmark$	$\checkmark$	✓	-

#### **Explanation:**

The ORI instruction is used in the parallel connection of B contact. The functions are to read out the status of present designated parallel connection contacts and perform the "ORI" operation with the logical operation result obtained. The final result will be store in the accumulative register.

## **Program Example:**

Ladder diagram:	Instruction	on code:	Operation:
. X0	LD	X0	Loading in contact A of X0
Y1	ORI	X1	Connecting to contact B of X1 in parallel
	OUT	Y1	Driving Y1 coil

Mnemonic	Functions						
ANB	Series connection- loop blocks						
Operand	none						

#### **Explanation:**

To perform the "AND" operation of the preserved logic results and content in the accumulative register.

#### **Program Example:**

Ladder diagram:	Instructio	on code:	Operation:
X0 ANB X1	LD	X0	Loading in contact A of X0
Y1	ORI	X2	Connecting to contact B of X2 in parallel
	LDI	X1	Loading in contact B of X1
Block A Block B	OR	X3	Connecting to contact A of X3 in parallel
BIOCK A BIOCK B	ANB		Connecting circuit block in series
	OUT	Y1	Driving Y1 coil

## Appendix C Use of Basic Instructions | DOP-EXIO Series

Mnemonic	Functions	
ORB	Parallel connection- loop blocks	
Operand	None	

#### **Explanation:**

To perform the "OR" operation of the preserved logic results and content in the accumulative register.

#### **Program Example:**

Ladder diagram:	Instruction code:		Operation:
X0 X1 Block A	LD	X0	Loading in contact A of X0
	ANI	X1	Connecting to contact B of X1 in series
X2 X3	LDI	X2	Loading in contact B of X2
	AND	X3	Connecting to contact A of X3 in series
Block B	ORB		Connecting circuit block in parallel
	OUT	Y1	Driving Y1 coil

Mnemonic	Functions
MPS	Store the current result of the internal EXIO operations

Operand	None
---------	------

#### **Explanation:**

To save the content in the accumulative register into the operational result (the pointer of operational result will plus 1).

Mnemonic	Functions
MRD	Read the current result of the internal EXIO operations

	Operand	None	
--	---------	------	--

#### **Explanation:**

To read the operational result and store it into the accumulative register (the pointer of operational result stays intact).

Mnemonic	Functions
MPP	Pop (recall and remove) the currently stored result

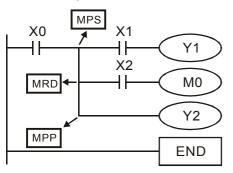
Operand	None
---------	------

# **Explanation:**

To retrieve the previous preserved logical operation result and store it into the accumulative register (the pointer of operational result will minus 1).

# Program Example:

Ladder diagram:



Instruction code:		Operation:			
LD	X0	Loading in contact A of X0			
MPS		Saving into stack			
AND	X1	Connecting to contact A of X1 in series			
OUT	Y1	Driving Y1 coil			
MRD		Reading from stack			
AND	X2	Connecting to contact A of X2 in series			
OUT	M0	Driving M0 coil			
MPP		Reading from stack and pop pointer			
OUT	Y2	Driving Y2 coil			
END		Program ends			

	Functions
OUT Output Coil	

Operand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
	-	$\checkmark$	✓	$\checkmark$	-	-	-

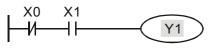
# **Explanations:**

- 1. To output the logical operation result before OUT instruction into a designated device.
- 2. Actions of coil contact:

	OUT instruction				
Operational result	Coil	Contact			
	COII	A contact (normally open)	B contact (normally closed)		
FALSE	Off	Off	On		
TRUE	On	On	Off		

# Program Example:

Ladder diagram:



Instruction code:		Operation:
LDI	X0	Loading in contact B of X0
AND	X1	Connecting to contact A of X1 in series
OUT	Y1	Driving Y1 coil

## Appendix C Use of Basic Instructions | DOP-EXIO Series

Mnemonic	Functions
SET	Latch (ON)

Operand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	-	$\checkmark$	✓	$\checkmark$	-	-	-

#### **Explanations:**

When the SET instruction is driven, its designated device will be "On" and keep being On both when SET instruction is still being driven or not driven. Use RST instruction to set "Off" the device.

## **Program Example:**

Ladder diagram:	Instruct	ion code:	Operation:
	LD	X0	Loading in contact A of X0
	ANI	Y0	Connecting to contact B of Y0 in series
SET Y1	SET	Y1	Y1 latched (On)

Mnemonic	Functions
RST	Clear the contact or the registers

Operand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599	E, F
Operand	-	$\checkmark$	✓	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	✓

# **Explanations:**

1. When the RST instruction is driven, the actions of the designated devices are:

Device	Status
Y, M, S,	Coil and contact will be set to "Off"
Т, С	Present values of the timer or counter will be set to "0", and the coil and contact will be set to "Off"
D, E, F	The content will be set to "0".

Operation:

Loading in contact A of X0

Resetting contact Y5

2. If RST instruction is not being executed, the status of the designated device will stay intact.

LD

RST

Instruction code:

# Program Example:

Ladder diagram:



Mnemonic	Functions
TMR	16-bit Timer

X0

Y5

Operand	T-K	T0~T127, K0~K32,767
Operand	T-D	T0~T127, D0~D599

# **Explanations:**

When TMR instruction is executed, the designated coil of the timer will be On and the timer will start to time. When the set value in the timer is reached (present  $\geq$  set value), the contact will be:

NO (Normally Open) contact	Open collector
NC (Normally Closed) contact	Close collector

# Program Example:

Ladder diagram:				Instructio	n code:	Operation:
X0				LD	X0	Loading in contact A of X0 T5 timer
<u>├</u> -1├	TMR	Т5	K1000	TMR	T5 K1000	Set value in timer T5 as K1,000

Mnemonic	Functions
CNT	16-bit Counter

Operand	C-K	С0~С127, К0~К32,767
	C-D	C0~C127, D0~D599

# **Explanations:**

1. When the CNT instruction goes from Off to On, the designated counter coil will be driven, and the present value in the counter will plus 1. When the counting reaches the set value (present value = set value), the contact will be:

NO (Normally Open) contact	Open collector
NC (Normally Closed) contact	Close collector

2. If there are other counting pulse input after the counting reaches its target, the contact and present value will stay intact. Use RST instruction to restart or reset the counting.

# **Program Example:**

Ladder diagram:		Instruction code:		Operation:	
X0			LD	X0	Loading in contact A of X0
	C20	K100	CNT	C20	Set value in counter C20 as K100
				K100	

Mnemonic	Functions
DCNT	32-bit Counter

Operand	C-K	C235~C254
	C-D	C235~C254, D0~D598

# Explanations:

1. DCNT is the instruction for enabling the 32-bit high-speed counters C235 ~ C254. The method of

using DCNT instruction is the same as using CNT instruction to enabling C0~C127.

2. When DCNT is Off, the counting will stop, but the existing present value in the counter will not be cleared. To clear the present value and the contact, the user has to use the instruction RST C2XX.

#### Program Example:

Ladder diagram:				Instructio	on code:	Operation:
MO		0054		LD	M0	Loading in contact A of M0
	DCNT	C254	K1000	DCNT	C254	Set value of counter C254 as K1,000
					K1000	

Mnemonic	Functions
MC / MCR	Master Control Start / Reset

Operand
---------

#### **Explanations:**

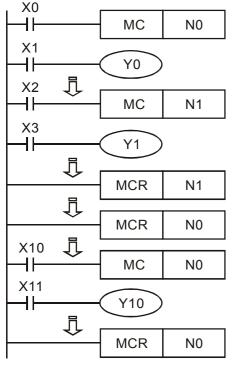
1. MC is the main-control start instruction. When MC instruction is executed, the execution of instructions between MC and MCR will not be interrupted. When MC instruction is Off, the actions of the instructions between MC and MCR are:

Instruction type	Explanation
General purpose timer	Present value = 0 Coil is Off, No action for the contact
Accumulative timer	Coil is Off, present value and contact stay intact
Subroutine timer	Present value = 0 Coil is Off, No action for the contact
Counter	Coil is Off, present value and contact stay intact
Coils driven by OUT instruction	All Off
Devices driven by SET and RST instructions	Stay intact
Application instructions	All disabled. The FOR-NEXT nested loop will still execute back and forth for N times. Instructions between FOR-NEXT will act as the instructions between MC and MCR.

- 2. MCR is the main-control end instruction that is placed in the end of the main-control program. There should not be any contact instructions prior to MCR instruction.
- MC-MCR main-control program instructions support the nested program structure (max. 8 layers) and please use the instruction in the order N0 ~ N7.

## **Program Example:**

Ladder diagram:



Instruction code: Operation: LD X0 Loading in A contact of X0 MC N0 Enabling N0 common series connection contact LD X1 Loading in A contact of X1 OUT Y0 Driving Y0 coil LD X2 Loading in A contact of X2 N1 Enabling N1 common series connection MC contact Х3 Loading in A contact of X3 LD OUT Y1 Driving Y1 coil MCR N1 Disabling N1 common series connection contact : **N0** MCR Disabling N0 common series connection contact : X10 LD Loading in A contact of X10 MC N0 Enabling N0 common series connection contact LD X11 Loading in A contact of X11 Y10 OUT Driving Y10 coil N0 Disabling N0 common series connection MCR contact

Mnemonic	Functions
LDP	Rising-edge Detection Operation

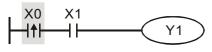
Operand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
	$\checkmark$	$\checkmark$	✓	$\checkmark$	$\checkmark$	$\checkmark$	-

## **Explanations:**

The method of using LDP is the same as using LD, but the actions of the two instructions differ. LDP saves the current content and store the detected status of rising-edge to the accumulative register.

## **Program Example:**

Ladder diagram:



Instruction code:		Operation:
LDP	X0	Starting X0 rising-edge detection
AND	X1	Series connecting A contact of X1
OUT	Y1	Driving Y1 coil

#### Appendix C Use of Basic Instructions | DOP-EXIO Series

Mnemonic	Functions	
LDF	Falling-edge Detection Operation	

	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	✓	$\checkmark$	~	$\checkmark$	$\checkmark$	~	-

#### **Explanations:**

The method of using LDF is the same as using LD, but the actions of the two instructions differ. LDF saves the current content and store the detected status of falling-edge to the accumulative register.

## Program Example:

Ladder diagram:



Instruction code:		Operation:
LDF	X0	Starting X0 falling-edge detection
AND	X1	Series connecting A contact of X1
OUT	Y1	Driving Y1 coil

Mnemonic	Functions	
ANDP	Riding-edge Series Connection	

Operand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	-

#### **Explanations:**

ANDP instruction is used in the series connection of the contacts' rising-edge detection.

## Program Example:

Ladder diagram:



Instruction code:		Operation:
LD	X0	Loading in A contact of X0
ANDP	X1	X1 rising-edge detection in series connection
OUT	Y1	Driving Y1 coil

Mnemonic	Functions
ANDF	Falling-edge Series Connection

Onerand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	$\checkmark$	$\checkmark$	~	~	~	~	-

## Explanations:

ANDF instruction is used in the series connection of the contacts' falling-edge detection.

## **Program Example:**

Ladder diagram:



Instructio	n code:	Operation:
LD	X0	Loading in A contact of X0
ANDF	X1	X1 falling-edge detection in series connection
OUT	Y1	Drive Y1 coil

Mnemonic	Functions	
ORP	Rising-edge Parallel Connection	

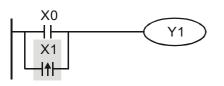
Onerand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	✓	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	✓	-

#### **Explanations:**

The ORP instructions are used in the parallel connection of the contact's rising-edge detection.

#### **Program Example:**

Ladder diagram:



Instruction code:		Operation:
LD	X0	Loading in A contact of X0
ORP	X1	X1 rising-edge detection in parallel
		connection
OUT	Y1	Driving Y1 coil

Mnemonic	Functions
ORF	Falling-edge Parallel Connection

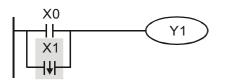
One and	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	✓	$\checkmark$	✓	$\checkmark$	$\checkmark$	$\checkmark$	-

#### **Explanations:**

The ORF instructions are used in the parallel connection of the contact's falling-edge detection.

#### **Program Example:**

Ladder diagram:



Instruct	ion code:	Operation:
LD	X0	Loading in A contact of X0
ORF	X1	X1 falling-edge detection in parallel connection
OUT	Y1	Driving Y1 coil

#### Appendix C Use of Basic Instructions | DOP-EXIO Series

Mnemonic	Functions
PLS	Rising-edge Output

Onerand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	-	$\checkmark$	$\checkmark$	-	-	-	-

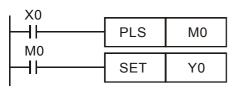
#### **Explanations:**

When X0 goes from Off to On (rising-edge trigger), PLS instruction will be executed and M0 will send out pulses for once of 1 scan time.

Instruction and a:

## Program Example:

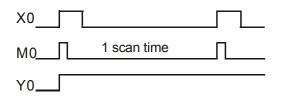
Ladder diagram:



instruction code.		Operation.
LD	X0	Loading in A contact of X0
PLS	M0	M0 rising-edge output
LD	M0	Loading in contact A of M0
SET	Y0	Y0 latched (On)

Operation:

Timing Diagram:



Mnemonic	Functions
PLF	Falling-edge Output

Onerend	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	-	$\checkmark$	✓	-	-	-	-

## **Explanations:**

When X0 goes from On to Off (falling-edge trigger), PLF instruction will be executed and M0 will send out pulses for once of 1 scan time.

## **Program Example:**

Ladder diagram:

×0 −−1	PLF	M0
мо —	SET	Y0

Instruction code:		Operation:
LD	X0	Loading in A contact of X0
PLF	MO	M0 falling-edge output
LD	M0	Loading in contact A of M0
SET	Y0	Y0 latched (On)

Timing Diagram:

X0		
M0	 1 scan time	
/0		

Mnemonic	Functions
END	Program End

None

#### **Explanations:**

Operand

END instruction has to be placed in the end of a ladder diagram or instruction program. DOP-EXIO series will start to scan from address 0 to END instruction and return to address 0 to restart the scan.

#### **Program Example:**

Ladder diagram:	Instruction code:		Operation:
X0 X1	LD	X0	Loading in B contact of X0
	AND	X1	Series connecting A contact of X1
	OUT	Y1	Driving Y1 coil
END	END		Program end

Mnemonic	Functions
NOP	No Operation

None

# Explanations:

Operand

NOP instruction does not conduct any operations in the program; therefore, after the execution of NOP, the existing logical operation result will be kept. If the user wants to delete a certain instruction without altering the length of the program, the user can use NOP instruction. If the user wants to delete a certain instruction temporarily, the user can also use NOP instruction.

# Program Example:

Ladder diagram:	Ins
NOP instruction will be	LD
omitted in the ladder diagram	NC
X0	Ol

	Instruction code:		Operation:
_	LD	X0	Loading in B contact of X0
n	NOP		No operation
	OUT	Y1	Driving Y1 coil

#### Appendix C Use of Basic Instructions | DOP-EXIO Series

Mnemonic	Functions	
INV	Inverting Operation	
Operand	None	

#### **Explanations:**

The logical operation result before INV instruction will be inverted and stored in the accumulative register.

# Program Example:

Ladder diagram:	Instruc	tion code:	Operation:
X0	LD	X0	Loading in A contact of X0
$    \cdot \rangle \langle \gamma   \rangle$	INV		Inverting the operation result
	OUT	Y1	Driving Y1 coil

Mnemonic	Functions
Р	Pointer
Operand	P0~P63

#### **Explanations:**

Pointer P is used in 00 CJ and 01 CALL instructions. The use of P does not need to start from No. 0, and the No. of P cannot be repeated; otherwise, unexpected errors may occur.

## **Program Example:**

Ladder diagram:	Instruc	tion code:	Operation:
X0 CJ P10	LD CJ	X0 P10	Loading in A contact of X0 From instruction CJ to P10
	P10 LD OUT	X1 Y1	Pointer P10 Loading in A contact of X1 Driving Y1 coil
	001		Driving 11 con

Mnemonic	Functions
STL	Step Transition Ladder Start Command

Onerand	X0~X17	Y0~Y17	M0~M1279	S0~S127	T0~T127	C0~C254	D0~D599
Operand	-	-	-	$\checkmark$	-	-	-

## **Explanations:**

STL Sn constructs a step. When STL instruction appears in the program, the program will enter a step ladder diagram status controlled by steps. The initial status has to start from S0 ~ S9. RET instruction

indicates the end of a step ladder diagram starting from S0 ~ S9 and the bus returns to a normal ladder diagram instruction. The No. of S cannot be repeated.

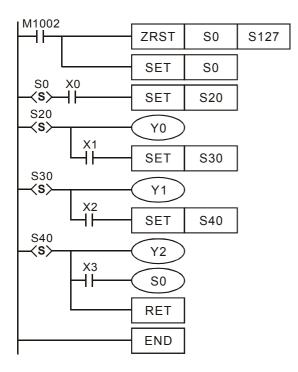
Mnemonic	Functions								
RET	Step Transition Ladder Return Command								
Operand None									

## **Explanations:**

RET indicates the end of a step. There has to be a RET instruction in the end of a series of steps. One EXIO program can be written in maximum 10 steps (S0  $\sim$  S9) and every step should end with a RET.

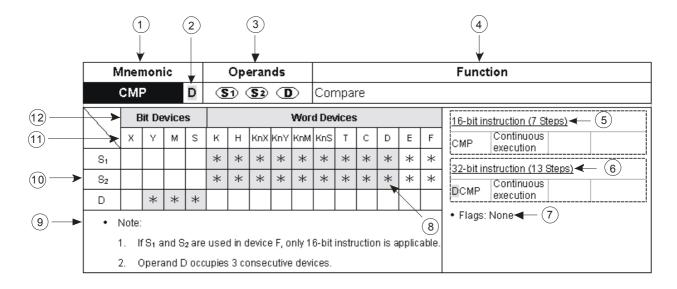
## **Program Example:**

Ladder diagram:



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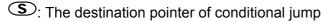
# Appendix D Use of Application Instructions



Format of an application instruction:

- ① Mnemonic of an application instruction.
- Indication of if there is a 16-bit or 32-bit instruction. If there is a 32-bit instruction, the column will be marked with "D".
- 3 Operands
- ④ Function of the application instruction
- 5 Steps occupied by the 16-bit execution instruction
- 6 Steps occupied by the 32-bit execution instruction
- ⑦ Related flags for the application instruction
- 8 Column marked with \* and in grey refers to E, F index register modification is applicable.
- 9 Note
- 10 Column marked with \* is the device applicable for the operand
- ① Device name
- 12 Device type

M	Mnemonic Operands												Function			
	CJ					(	S			Con	ditic	onal	Jum	р		
	E	Bit De	evice	s				1	Wor	d Dev	/ices	;				16-bit instruction (3 Steps)
	Х	Y	Μ	S	к	Н	KnX	KnY	KnM	KnS	STCDEF					CJ Continuous execution
• 1	Vote:															32-bit instruction
	1. Operand S can designate P.															
2	2. P can be modified by index register E, F.													Flags: None		

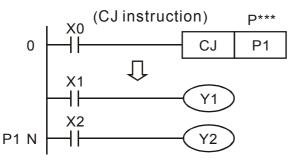


## **Explanations:**

- 1. When the user does not wish a particular part of DOP-EXIO program in order to shorten the scan time and execute dual outputs, CJ instruction or CJP instruction can be adopted.
- 2. When the program designated by pointer P is prior to CJ instruction, WDT timeout will occur and DOP-EXIO will stop running. Please use it carefully.
- 3. CJ instruction can designate the same pointer P repeatedly. However, CJ and CALL cannot designate the same pointer P; otherwise an error will occur.

# Program Example 1:

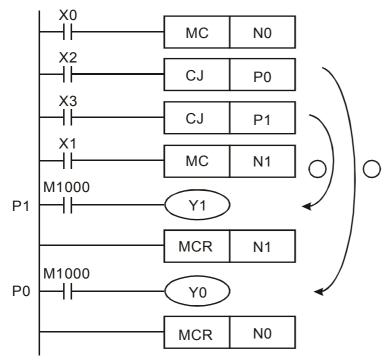
- When X0 = On, the program automatically jumps from address 0 to N (the designated label P1) and keeps its execution. The addresses between 0 and N will not be executed.
- 2. When X0 = Off, as an ordinary program, the program keeps on executing from address 0. CJ instruction will not be executed at this time.



# Program Example 2:

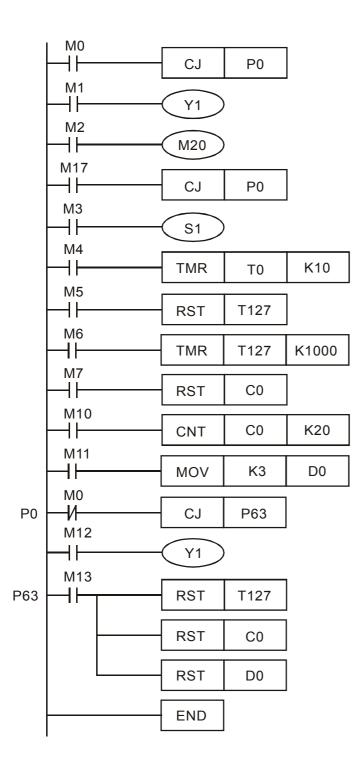
- 1. CJ instruction can be used in the following 5 conditions between MC and MCR instructions.
  - a) Without MC ~ MCR.
  - b) From without MC to within MC. Valid in the loop P1 as shown in the figure below.
  - c) In the same level N, inside of MC~MCR.
  - d) From within MC to without MCR.
  - e) Jumping from this MC ~ MCR to another MC ~ MCR

 When CJ instruction is used between MC and MCR, it can only be applied without MC ~ MCR or in the same N layer of MC ~ MCR. Jumping from this MC ~ MCR to another MC ~ MCR will result in errors, i.e. a) and c) as stated above can ensure correct actions; others will cause errors.



## Program Example 3:

- 1. The status of each device when executing CJ instruction:
  - The method of using this CJ instruction is similar to the method of using goto instruction of C-language. When executing CJ instruction, the status of each device will not be changed.
  - > When the timers are driven and encounter the execution of CJ instruction, the timing will resume. After the timing target is reached, the output contact of the timer will be On.
  - > The counter will stop counting (This is because the counter is activated to count via the software).
  - All the instructions which have encounterd the execution of CJ instruction will not be activated.
- 2. Y1 is a dual output. When M0 = Off, Y1 is controlled by M1. When M0 = On, Y1 is controlled by M12.



N	Iner	non	ic		Operands											Function			
	CAL	L				(	S			Call	Sub								
	E	Bit Devices Word Devices							d Dev	vices	i				16-bit instruction (3 Steps)				
	х	Y	Μ	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	CALL Continuous execution			
•	Note:															32-bit instruction			
	1. (	Opera	and S	can	desi	esignate P.													
:	2. P can be modified by index register E, F.													Flags: None					

S: The pointer of call subroutine.

#### **Explanations:**

- 1. Edit the subroutine designated by the pointer after FEND instruction.
- 2. The number of pointer P, when used by CALL, cannot be the same as the number designated by CJ instruction.
- 3. If only CALL instruction is in use, it can call subroutines of the same pointer number with no limit on times.
- 4. Subroutine can be nested for 5 levels including the initial CALL instruction. (If entering the sixth level, the subroutine won't be executed.)

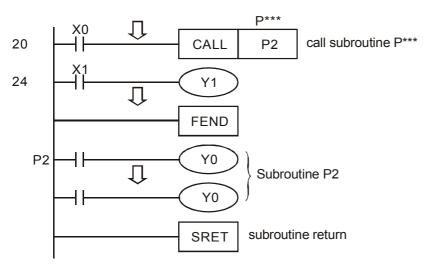
Mnemonic			Оре	eran	ds			Function										
SRET	None									Subroutine Return								
Bit Devices					١	Wor	d Dev	vices	;				16-bit instruction (1 Step)					
Х Ү М	X Y M S K H KnX KnY Kn								С	D	Е	F	SRET Continuous execution					
Note:     1. No operand.				32-bit instruction														
2. No contact to drive the instruction is required.												Flags: None						

## **Explanations:**

- 1. This instruction denotes the end of the subroutine program.
- 2. The subroutine will return to main program by SRET after the termination of subroutine and execute the sequence program located at the next step to the CALL instruction.

## Program Example 1:

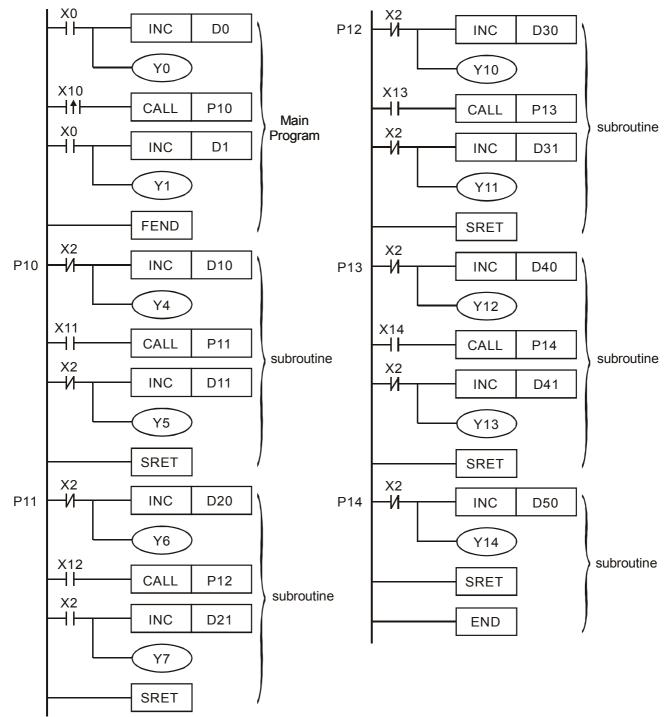
When X0 = On, CALL instruction is executed and the program jumps to the subroutine designated by P2. When SRET instruction is executed, the program returns to address 24 and continues its execution.



## Program Example 2:

- 1. When X10 goes from Off to On, its rising-edge trigger executes CALL P10 instruction and the program jumps to the subroutine designated by P10.
- 2. When X11 is On, CALL P11 is executed and the program jumps to the subroutine designated by P11.
- 3. When X12 is On, CALL P12 is executed and the program jumps to the subroutine designated by P12.
- 4. When X13 is On, CALL P13 is executed and the program jumps to the subroutine designated by P13.

- 5. When X14 is On, CALL P14 is executed and the program jumps to the subroutine designated by P14. When SRET is executed, the program returns to the previous P\*\* subroutine and continues its execution.
- 6. After SRET instruction is executed in P10 subroutine, returning to the main program.

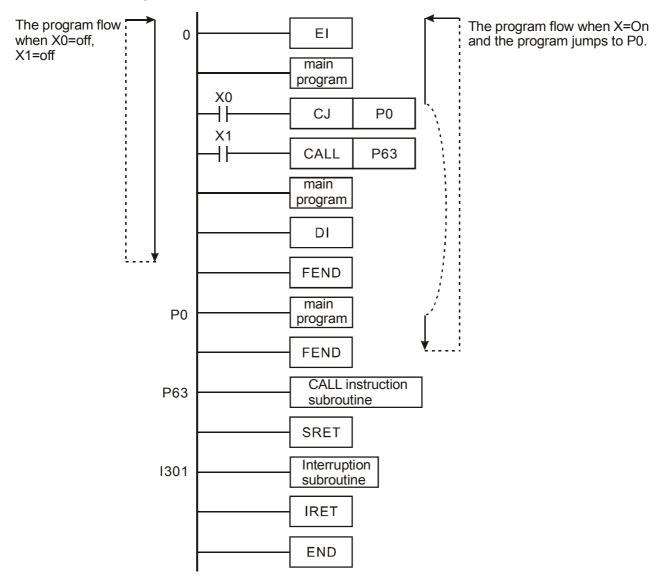


M	Mnemonic Operands												Function					
F	EN	D				Ν	lone	;		The End of The Main Program (First End)								
	Bit Devices Word									d Dev	vices	i				16-bit instruction (1 Step)		
	X Y M S K H KnX KnY KnM							KnS	Т	С	D	Е	F	FEND Continuous execution				
• 1	<ul><li>Note:</li><li>1. No operand.</li></ul>													<u>32-bit instruction</u>				
2	<ol> <li>No contact to drive the instruction is required.</li> </ol>														Flags: None			

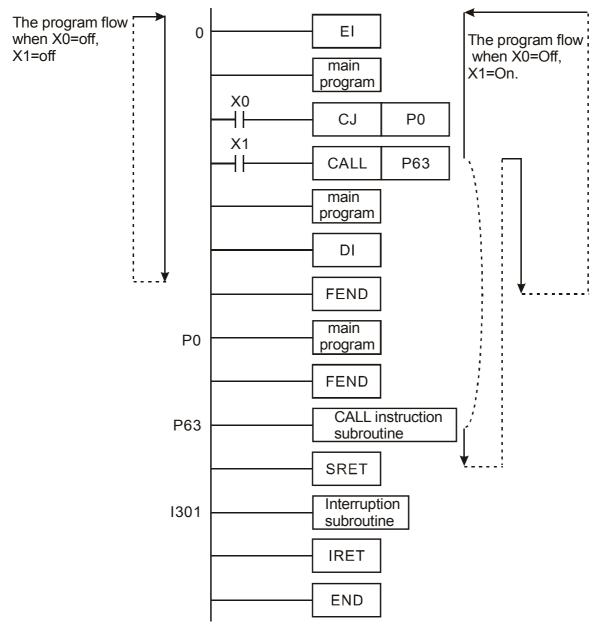
## **Explanations:**

- 1. This instruction denotes the end of the main program. It has the same function as that of END instruction when being executed by DOP-EXIO series.
- 2. CALL must be written after FEND instruction and add SRET instruction in the end of its subroutine. Interruption program has to be written after FEND instruction and IRET must be added in the end of the service program.
- 3. If several FEND instructions are in use, place the subroutine and interruption service programs between the final FEND and END instruction.
- 4. After CALL instruction is executed, executing FEND before SRET will result in errors in the program.
- 5. After FOR instruction is executed, executing FEND before NEXT will result in errors in the program.

# **CJ Instruction Program Flow:**



#### **CALL Instruction Program Flow:**



Μ	Iner	non	ic		Operands											Function			
	FOF	२				(	S			Star	t of	a F(	DR-I	NEX	TL	рор			
	E	Bit De	evice	s	Word Devices											16-bit instruction (3 Steps)			
	Х	Υ	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	FOR Continuous			
S					*	*	*	*	*	*	*	*	*	*	*	32-bit instruction			
1 •	Note: 1. N		ntact	to d	rive t	he in	struc	tion i	s req	uired						• Flags: None			

S: The number of repeated nested loops

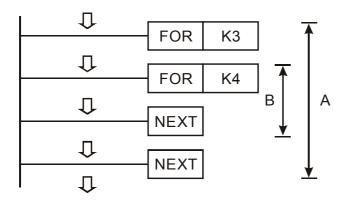
Μ	Iner	non	ic			Оре	eran	ds									Funct	ion	
1	NEX	T				Ν	lone	9		End	of a	a FC	)R-N	IEX <sup>-</sup>	T Lo	ор			
$\sum_{i=1}^{n}$	E	Bit D	evice	s					Wor	d Dev	/ices	;				1	6-bit in:	struction (1 Step)	-
	х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	Ν	NEXT	Continuous	
• 1	Note:															3	32-bit in	struction	7
	1. 1	No op	beran	d.												_			
2	2. 1	No co	ontac	t to d	rive tł	ne in	struc	tion is	s req	uired	•					•	Flags:	None	

## **Explanations:**

- 1. FOR instruction indicates FOR ~ NEXT loops executing back and forth N times before escaping for the next execution.
- 2. N = K1 ~ K32,767. N is regarded as K1 when N  $\leq$  1.
- 3. When FOR~NEXT loops are not executed, the user can use the CJ instruction to escape the loops.
- 4. Error will occur when
  - a) NEXT instruction is before FOR instruction.
  - b) FOR instruction exists but NEXT instruction does not exist.
  - c) There is NEXT instruction after FEND or END instruction.
  - d) The number of instructions between FOR ~ NEXT differs.
- FOR~NEXT loops can be nested for maximum five levels. Be careful that if there are too many loops, the increased PLC scan time may cause timeout of watchdog timer and error. Users can use WDT instruction to modify this problem.

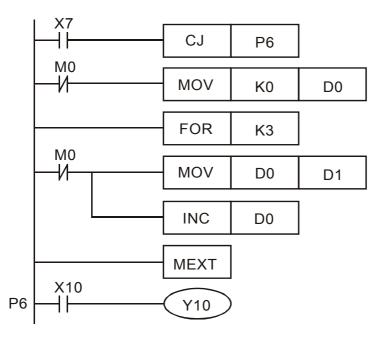
#### Program Example 1:

After program A has been executed for 3 times, it will resume its execution after NEXT instruction. Program B will be executed for 4 times whenever program A is executed once. Therefore, program B will be executed  $3 \times 4 = 12$  times in total.



# Program Example 2:

When X7 = Off, DOP-EXIO series will execute the program between FOR ~ NEXT. When X7 = On, CJ instruction jumps to P6 and avoids executing the programs between FOR ~ NEXT.



## Program Example 3:

When the programs between FOR ~ NEXT are not to be executed, the user can adopt CJ instruction for a jumping. When the most inner FOR ~ NEXT loop is in the status of X1 = On, CJ instruction executes jumping to P0 and skips the execution on P0.

A0       TMR       T0       K10         FOR       K4X100       K4X100         X0       INC       D0         FOR       K2       K2         X0       INC       D1         FOR       K3       K4         X0       INC       D2         FOR       K4       K4         X0       WDT       INC         FOR       K5       X0         INC       D4       INEXT         NEXT       NEXT       INEXT         INEXT       INEXT       INEXT         INEXT       INEXT       INEXT		X0			
X0       INC       D0         FOR       K2         X0       INC       D1         FOR       K3         X0       INC       D2         FOR       K3         X0       INC       D2         FOR       K4         X0       WDT         INC       D3         X1       CJ       P0         FOR       K5         X0       INC       D4         NEXT       NEXT         NEXT       NEXT         NEXT       NEXT			TMR	Т0	K10
P0 INC D0 FOR K2 X0 INC D1 FOR K3 X0 FOR K3 X0 FOR K4 X0 FOR K4 X0 FOR K4 X0 FOR K5 X0 FOR K5 X0 INC D4 FOR K5 X0 INC D4 NEXT NEXT NEXT NEXT NEXT			FOR	K4X100	
X0       INC       D1         FOR       K3         X0       INC       D2         FOR       K4         X0       WDT         FOR       K4         X0       WDT         INC       D3         X1       CJ         FOR       K5         X0       INC       D4         NEXT       NEXT         NEXT       NEXT         NEXT       NEXT			 INC	D0	
P0 NEXT P0 NEXT			FOR	K2	
P0			INC	D1	
P0 NEXT P0 NEXT			FOR	K3	
P0 (NEXT) P0 (NEXT) NEXT NEXT NEXT NEXT NEXT NEXT NEXT NEXT NEXT			INC	D2	
P0 WDT INC D3 X1 CJ P0 FOR K5 X0 INC D4 NEXT NEXT NEXT NEXT			FOR	K4	
P0 X1 CJ P0 FOR K5 X0 INC D4 NEXT NEXT NEXT NEXT			WDT	]	
P0 CJ P0 FOR K5 X0 NEXT P0 NEXT NEXT NEXT NEXT NEXT			INC	D3	
P0 NEXT NEXT NEXT NEXT NEXT NEXT NEXT			CJ	P0	
P0 NEXT NEXT NEXT NEXT NEXT NEXT			 FOR	K5	
P0 NEXT NEXT NEXT NEXT			 INC	D4	
NEXT NEXT			 NEXT	]	
NEXT	P0		 NEXT	]	
NEXT			 NEXT	]	
			 NEXT	]	
END			NEXT	]	
			END	]	

N	Inen	non	ic			Оре	eran	ds								Function
	CMF	0		D	S	) (I	<b>S</b> 2		D	Con	npar	e				
	Bit Devices Word Devices													16-bit instruction (7 Steps)		
	х	Υ	М	S	K H KnX KnY KnM KnS T C D E F											CMP Continuous
<b>S</b> <sub>1</sub>				* * * * * * * * * * * * * * * * * *												
S <sub>2</sub>																
D		*	*	*												execution
1 •	Note:     Flags: None											Flags: None				
1. If $S_1$ and $S_2$ are used in device F, only 16-bit instruction is applicable.																
2. Operand D occupies 3 consecutive devices.																

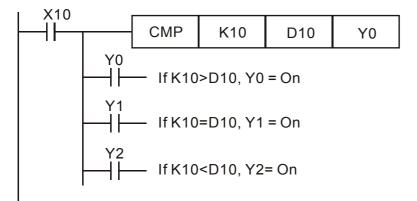
```
(S1): Comparison Value 1 (S2): Comparison Value 2 (D): Comparison result
```

# **Explanations:**

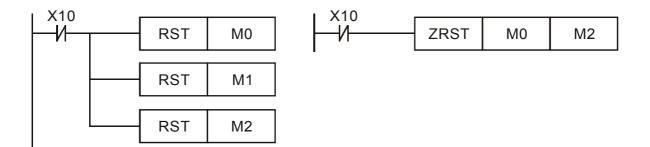
- 1. The contents in  $S_1$  and  $S_2$  are compared and the result will be stored in **D**.
- The two comparison values are compared algebraically and the two values are signed binary values. When b15 = 1 in 16-bit instruction or b31 = 1 in 32-bit instruction, the comparison will regard the value as negative binary values.

## Program Example:

- 1. Designate device Y0, and operand D automatically occupies Y0, Y1, and Y2.
- When X10 = On, CMP instruction will be executed and one of Y0, Y1, and Y2 will be On. When X10 = Off, CMP instruction will not be executed and Y0, Y1, and Y2 remain their status before X10 = Off.
- If the user needs to obtain a comparison result with ≥ ≤, and ≠, make a series parallel connection between Y0 ~ Y2.



4. To clear the comparison result, use RST or ZRST instruction.



M	Iner	non	ic			Op	oera	nds								Function
	ZCF	)			<b>S</b> 1	) (5	2	S		) Zo	one	Con	npar	е		
															16-bit instruction (9 Steps)	
															ZCP Continuous execution	
S <sub>1</sub>	S <sub>1</sub> * * * * * * * * * * * *															
S <sub>2</sub>	S2     * </td <td><u>32-bit instruction (17 Steps)</u> DZCP</td>													<u>32-bit instruction (17 Steps)</u> DZCP		
S														DZCP execution		
D		*	*	*												• Flags: None
2	2. The content in $S_1$ should be smaller than the content in $S_2$ .															
3	3. (	Opera	and D	000	upies	s 3 co	onsec	cutive	e devi	ces.						

(S1): Lower bound of zone comparison (S2): Upper bound of zone comparison

S: Comparison value D: Comparison result

# **Explanations:**

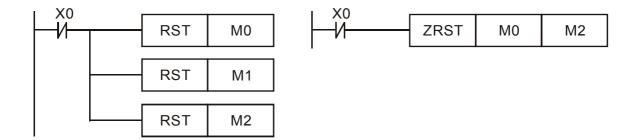
- 1. **S** is compared with its  $S_1$ ,  $S_2$  and the result is stored in **D**.
- 2. When  $S_1 > S_2$ , the instruction performs comparison by using  $S_1$  as the lower/upper bound.
- 3. The two comparison values are compared algebraically and the two values are signed binary values. When b15 = 1 in 16-bit instruction or b31 = 1 in 32-bit instruction, the comparison will regard the value as negative binary values.

## Program Example:

- 1. Designate device M0, and operand D automatically occupies M0, M1 and M2.
- When X0 = On, ZCP instruction will be executed and one of M0, M1, and M2 will be On. When X0 = Off, ZCP instruction will not be executed and M0, M1, and M2 remain their status before X0 = Off.

X0  
ZCP K10 K100 C10 M0  
M0  
If C10 < K10, M0 = On  
M1  
If K10 
$$\leq$$
 C10  $\leq$  K100, M1 = On  
M2  
If C10 > K100, M2 = On

3. To clear the comparison result, use RST or ZRST instruction.



N	Iner	non	ic			Оре	eran	ds								Function
	MO			D		S		D		Mov	'e					
	Bit Devices Word Devices													16-bit instruction (5 Steps)		
	X Y M S K H KnX KnY KnM KnS T C D E											Е	F	MOV Continuous execution		
S												*	*			
D								*	*	*	*	*	*	*	*	<u>32-bit instruction (9 Steps)</u>
1 •	Jote:													execution		
	1. If S, and D are used in device F, only 16-bit instruction is applicated											ıble.	Flags: None			

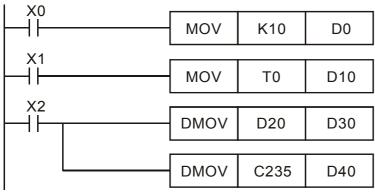
S: Source of data D: Destination of data

## **Explanations:**

- 1. When this instruction is executed, the content of **S** will be moved directly to **D**. When this instruction is not executed, the content of **D** remains unchanged.
- 2. If the operation result refers to a 32-bit output, (i.e. application instruction MUL and so on), and the user needs to move the present value in the 32-bit high-speed counter, DMOV instruction has to be adopted.

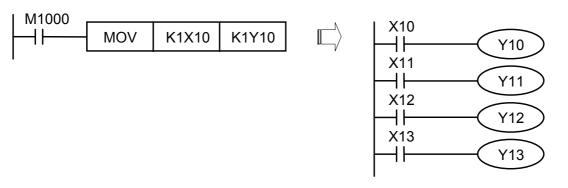
## **Program Example:**

- 1. MOV instruction has to be adopted in the moving of 16-bit data.
  - a) When X0 = Off, the content in D10 will remain unchanged. If X0 = On, the value K10 will be moved to D10 data register.
  - b) When X1 = Off, the content in D10 will remain unchanged. If X1 = On, the present value T0 will be moved to D10 data register.
- DMOV instruction has to be adopted in the moving of 32-bit data.
   When X2 = Off, the content in (D31, D30) and (D41, D40) will remain unchanged. If X2 = On, the present value of (D21, D20) will be sent to (D31, D30) data register. Meanwhile, the present value of C235 will be moved to (D41, D40) data register.



#### 3. Move bit data:

When the program is driven, the data of X10~X13 is moved to the Y10~Y13. Please refer to the figure below. The left program has the same function as the right.



N	Iner	non	ic			Ор	eran	ds								Function
	CMI			D		S		D		Con	nplir	nen	t			
	E	Bit Devices Word Devices												16-bit instruction (5 Steps)		
	Х												Е	F	CML Continuous execution	
S												*	*			
D												*	*	<u>32-bit instruction (9 Steps)</u> Continuous		
• 1	Note:	lote:													DCML execution	
	1. If S, and D are used in device F, only 16-bit instruction is applicated											plica	ıble.	Flags: None		

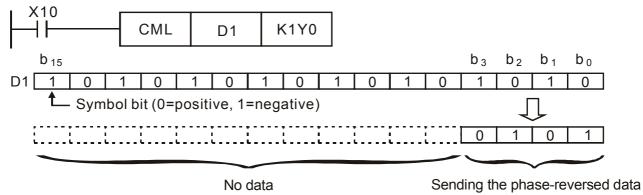
S: Source of data D: Destination device

## **Explanations:**

- 1. This instruction can be used for phase-reversed output.
- 2. Reverse the phase  $(0 \rightarrow 1, 1 \rightarrow 0)$  of all the contents in **S** and send the contents to **D**. Given that the content is a constant K, K will be automatically converted into a BIN value.

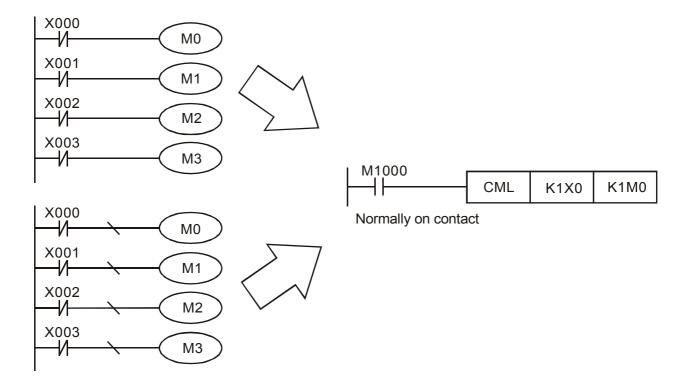
#### Program Example 1:

- 1. When the user wants to perform the phase-reversed output operation, please use this instruction.
- 2. When X10 = On,  $b0 \sim b3$  in D1 will be phase-reversed and send to Y0  $\sim$  Y3.



## Program Example 2:

The loop below can also adopt CML instruction (see the right side program of the figure below).



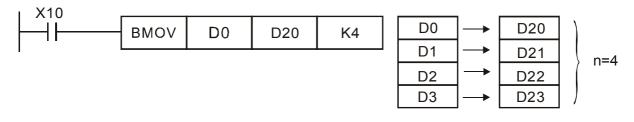
M	Iner	non	ic			Ор	eran	ds								Function
E	BMO	V		D	G	$\mathbf{D}$	D		D	Bloo	ck N	love				
	Bit Devices Word Devices													16-bit instruction (7 Steps)		
	X Y M S K H KnX KnY KnM KnS T C D E										F	BMOV Continuous execution				
S							*	*	*	*	*	*	*			
D								*	*	*	*	*	*			- <u>32-bit instruction</u>
n					*	*										
• •	• Note:												Flags: None			
	1. F	Range	e of r	n: 1 ~	· 512											

## **Explanations:**

The contents in n registers starting from the device designated by **S** will be moved to n registers starting from the device designated by **D**. If n exceeds the actual number of available source devices, only the devices that fall within the valid range will be used.

# Program Example 1:

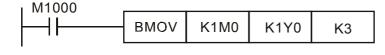
When X10 = On, the contents in registers  $D0 \sim D3$  will be moved to the 4 registers  $D20 \sim D23$ .



## Program Example 2:

Assume the bit devices KnX, KnY, KnM and KnS are designated for moving, the number of digits of **S** and **D** has to be the same, i.e. their n has to be the same.

#### Appendix D Use of Application Instructions | DOP-EXIO Series



M0	 Y0	
M1	 Y1	
M2	 Y2	
M3	 Y3	
M4	 Y4	
M5	 Y5	n=3
M6	 Y6	11-5
M7	 Y7	
M8	 Y10	
M9	 Y11	
M10	 Y12	
M11	 Y13	

# Program Example 3:

To avoid coincidence of the device numbers to be moved designated by the two operands and cause confusion, please be aware of the arrangement on the designated device numbers.

1. When **S** > **D**, the instruction is processed following the order  $\mathbb{O} \rightarrow \mathbb{O} \rightarrow \mathbb{O}$ 

X10			-		_	
	вмоу	D20	D19	K3		D20
						D21
						D22

	ו 🛈 רו	D40
D20		D19
D21		D20
D22	<b>₩</b>	D21

2. When **S** < **D**, the instruction is processed following the order  $\Im \rightarrow \Im \rightarrow \Im$ 

X11						6	
	BMOV	D10	D11	K3	D10	<u>③</u> ►	D11
					D11		D12
					D12		D13

N		Ор	eran	ds		Function										
F	-MC	V		D	G	$\mathbf{S}$	D		D	Fill	Mov	e				
$\sum_{i=1}^{n}$	E	Bit De	evice	es	Word Devices											16-bit instruction (7 Steps)
	х	Υ	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	FMOV Continuous execution
S					*	*	*	*	*	*	*	*	*	*	*	
D								*	*	*	*	*	*			32-bit instruction (13 Steps)
n					*	*										DFMOV execution
•	Note		1			1						1				• Flags: None
	1. I	f S is	use	d in c	levice	e F, c	only 1	6-bit	instru	uctior	n is a	pplic	able.			
	2. F	Rang	e of	n: 1~	512											

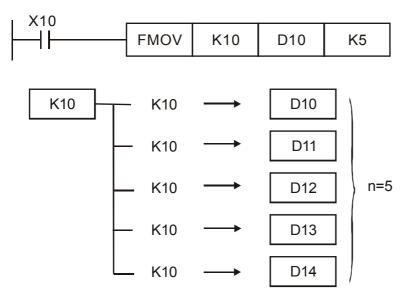
S: Source of data D: Destination of data : Number of data to be moved

# **Explanations:**

The contents in n registers starting from the device designated by S will be moved to n registers starting from the device designated by **D**. If n exceeds the actual number of available source devices, only the devices that fall within the valid range will be used.

# **Program Example:**

When X10 = On, K10 will be moved to the 5 consecutive registers starting from D10.



N	Iner	non	ic			Оре	eran	ds		Function						
	XCH D							2		Exc	han	ge				
	В	Bit De	evice	s	Word Devices											16-bit instruction (5 Steps)
	х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	XCH Continuous
D <sub>1</sub>								*	*	*	*	*	*	*	*	
D <sub>2</sub>								*	*	*	*	*	*	*	*	<u>32-bit instruction (9 Steps)</u> DXCU Continuous
•	• Note:														DXCH execution	
	1. li	f D₁ a	and D	$P_2$ are	e use	d in d	evice	e F, o	nly 1	6-bit	instru	uctior	n is a	pplica	able.	Flags: None

D1: Data to be exchanged 1 D2:	: Data to be exchanged 2
--------------------------------	--------------------------

## **Explanations:**

The contents in the devices designated by  $D_1$  and  $D_2$  will exchange.

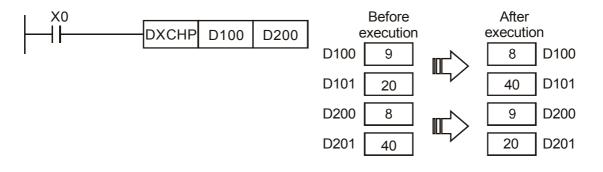
## Program Example 1:

When X0 = Off $\rightarrow$ On, the contents in D20 and D40 exchange with each other.



## Program Example 2:

When X0 = Off  $\rightarrow$  On, the contents in D100 and D200 exchange with each other.



N	Mnemonic						eran	ds		Function							
	BCD							D		Bina	ary (	Code	ed D	ecir	nal		
	Bit Devices								Wor	d Dev	vices	;				16-bit instruction (5 Steps)	
	х	Υ	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	BCD Continuous execution	
S							*	*	*	*	*	*	*	*	*	32-bit instruction (9 Steps)	
D								*	*	*	*	*	*	*	*	DBCD Continuous	
• •	• Note:														execution     execution     Flags: M1067 (Calculation error)		
	1. ľ	f S ar	nd D :	are ι	used i	in de	vice I	F, onl	ly 16∙	-bit in	struc	tion	is ap	plical	ble.	M1068 (Calculation error locked)	

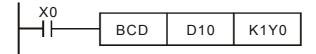
S: Source of data D: Conversion result

## **Explanations:**

- 1. The content in **S** (BIN value) is converted into BCD value and stored in **D**.
- As a 16-bit instruction, when the conversion result exceeds the range of 0 ~ 9,999, M1067 and M1068 will be On.
- 3. As a 32-bit instruction, when the conversion result exceeds the range of 0 ~ 99,999,999, M1067 and M1068 will be On.
- 4. The four arithmetic operations and applications in DOP-EXIO series and the execution of INC and DEC instructions are performed in BIN format. Therefore, if the user needs to see the decimal value display, simply use this instruction to convert the BIN value into BCD value.

## **Program Example:**

When X0 = On, the binary value of D10 will be converted into BCD value, and the 1s digit of the conversion result will be stored in K1Y0 (Y0 ~ Y3, the 4 bit devices).



N	Mnemonic						eran	ds		Function							
	BIN			D		S	$) \subset$	D		Bina	ary						
	E	Bit De	evice	s	Word Devices										16-bit instruction (5 Steps)		
	х	Y	М	S	к	н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	BIN Continuous execution	
S							*	*	*	*	*	*	*	*	*	32-bit instruction (9 Steps)	
D								*	*	*	*	*	*	*	*	DBIN Continuous	
•	Note:															execution	
	1. ľ	f S ai	nd D	are ı	used	in de	vice	F, on	ly 16	-bit in	struc	tion	is ap	plical	ble.	Flags: M1067 (Calculation error)	
																M1068 (Calculation error locked)	

S: Source of data D: Conversion result

## **Explanations:**

- 1. The content in **S** (BCD value) is converted into BIN value and stored in **D**.
- 2. Valid range of **S** : BCD (0 ~ 9,999), DBCD (0 ~ 99,999,999)
- 3. Provided the content in S is not a BCD value (in hex and any one of its digits does not fall in the range of  $0 \sim 9$ ), an operation error will occur, and M1067 and M1068 will be On.
- 4. Constant K and H will automatically be converted into BIN format. Thus, they do not need to adopt this instruction.

## Program Example:

When X0 = On, the BCD value of K1M0 will be converted to BIN value and stored in D10.

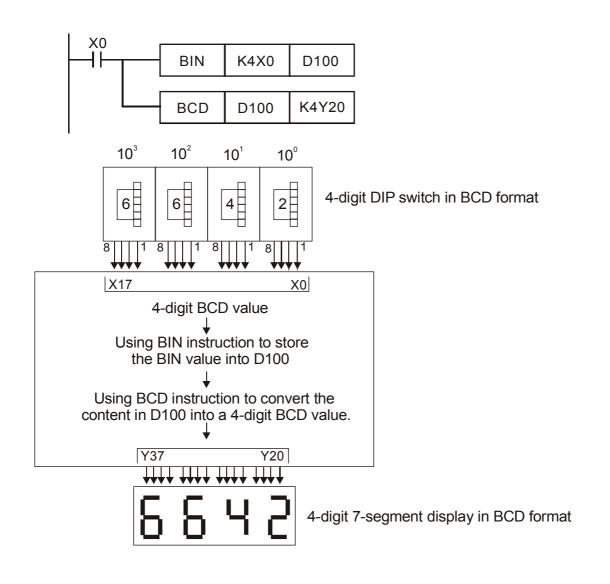


#### **Remarks:**

Explanations on BCD and BIN instructions:

- 1. When DOP-EXIO series needs to read an external DIP switch in BCD format, BIN instruction has to be first adopted to convert the read data into BIN value and store the data in DOP-EXIO series.
- 2. When DOP-EXIO series needs to display its stored data by a 7-segment display in BCD format, BCD instruction has to be first adopted to convert the data into BCD value and send the data to the 7-segment display.
- 3. When X0 = On, the BCD value of K4X0 is converted into BIN value and sent it to D100. The BIN value of D100 will then be converted into BCD value and sent to K4Y20.

#### Appendix D Use of Application Instructions | DOP-EXIO Series



N	Iner	non	ic			Оре	eran	ds								Function
	ADD	)		D	S		<b>S</b> 2		D	Add	itior	۱				
	E	Bit De	evice	S					Wor	d Dev	/ices	5				16-bit instruction (7 Steps)
	Х	Y	М	S	К	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	ADD Continuous execution
S <sub>1</sub>					*	*	*	*	*	*	*	*	*	*	*	32-bit instruction (13 Steps)
S <sub>2</sub>					*	*	*	*	*	*	*	*	*	*	*	Continuous
D								*	*	*	*	*	*	*	*	DADD execution
1 •	Note:	1	1	1	1		1							1		• Flags: M1020 (Zero flag)
	1. l <del>i</del>	fS₁.	S₂ ar	nd D a	are used in device F, only 16-bit instruction is M1021 (Barrow flag)											
			able.											-		M1022 (Carry flag)

SD: Summand	S2: Addend	D: Sum
-------------	------------	--------

## **Explanations:**

- 1. This instruction adds  $S_1$  and  $S_2$  in BIN format and store the result in **D**.
- The highest bit is symbolic bit 0 (+) and 1 (-), which is suitable for algebraic addition, e.g. 3 + (-9) = -6.
- 3. Flag changes in binary addition

In 16-bit BIN addition,

- a) If the operation result = 0, zero flag M1020 = On.
- b) If the operation result < -32,768, borrow flag M1021 = On.
- c) If the operation result > 32,767, carry flag M1022 = On.

In 32-bit BIN addition,

- a) If the operation result = 0, zero flag M1020 = On.
- b) If the operation result < -2,147,483,648, borrow flag M1021 = On.
- c) If the operation result > 2,147,483,647, carry flag M1022 = On.

# Program Example 1:

In 16-bit BIN addition:

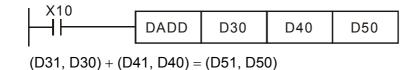
When X0 = On, the content in D0 will plus the content in D10 and the sum will be stored in D20.



### Program Example 2:

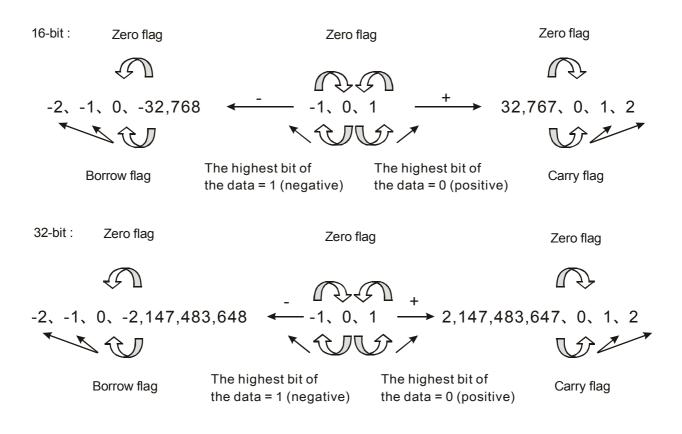
In 32-bit BIN addition:

When X0 = On, the content in (D31, D30) will plus the content in (D41, D40) and the sum will be stored in (D51, D50). D30, D40 and D50 are low 16-bit data; D31, D41 and D51 are high 16-bit data.



#### **Remarks:**

Flags and the positive/negative sign of the values:



N	Iner	non	ic			Ор	eran	ds								Function
	SUE	3		D	S	(S1) (S2) (D) Subtraction										
	E	Bit De	evice	S					Wor	d Dev	/ices	;				16-bit instruction (7 Steps)
	Х	Y	М	S	К	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	SUB Continuous execution
S <sub>1</sub>					*	*	*	*	*	*	*	*	*	*	*	32-bit instruction (13 Steps)
S <sub>2</sub>					*	*	*	*	*	*	*	*	*	*	*	Continuous
D								*	*	*	*	*	*	*	*	DSUB execution
• 1	Note:		1	1	1		1									<ul> <li>Flags: M1020 (Zero flag)</li> </ul>
			S. 01		aro u	cod i	n day	vico I		v 16	hit in	otruo	tion i	<u> </u>		M1021 (Barrow flag)
			s <sub>2</sub> al		are u	used in device F, only 16-bit instruction is								3		M1022 (Carry flag)

(S1): Minuend (S2): Subtrahend (D): Remainder

## **Explanations:**

- 1. This instruction subtracts  $S_1$  and  $S_2$  in BIN format and stores the result in **D**.
- 2. The highest bit is symbolic bit 0 (+) and 1 (-), which is suitable for algebraic subtraction.
- 3. Flag changes in binary subtraction
  - In 16-bit instruction:
    - a) If the operation result = 0, zero flag M1020 = On.
    - b) If the operation result < -32,768, borrow flag M1021 = On.
    - c) If the operation result > 32,767, carry flag M1022 = On.
  - In 32-bit instruction:
    - a) If the operation result = 0, zero flag M1020 = On.
    - b) If the operation result < -2,147,483,648, borrow flag M1021 = On.
    - c) If the operation result > 2,147,483,647, carry flag M1022 = On.
- 4. For flag operations of SUB instruction and the positive/negative sign of the value, see the explanations in ADD instruction on the previous page.

### Program Example 1:

In 16-bit BIN subtraction:

When X0 = On, the content in D0 will minus the content in D10 and the remainder will be stored in D20.

I X0			-	-
	SUB	D0	D10	D20

### Program Example 2:

In 32-bit BIN subtraction:

```
When X10 = On, the content in (D31, D30) will minus the content in (D41, D40) and the remainder will be stored in (D51, D50). D30, D40 and D50 are low 16-bit data; D31, D41 and D51 are high 16-bit data.
```



(D31, D30) - (D41, D40) = (D51, D50)

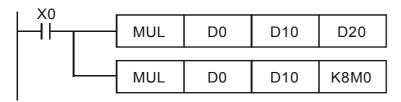
Ν	Iner	non	ic			Оре	eran	ds								Function	
	MUL			D	S		<b>S</b> 2		D	Mul	tiplic	catio	n				
	E	Bit De	evice	S					Wor	d Dev	vices	5				16-bit instruction (7 Steps)	
	х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	MUL Continuous execution	
S <sub>1</sub>					*	*	*	*	*	*	*	*	*	*	*	32-bit instruction (13 Steps)	
S <sub>2</sub>					*	*	*	*	*	*	*	*	*	*	*	DMUL Continuous execution	
D								*	*	*	*	*	*	*		Flags: None	
•	Note:																
									-	16-bit instruction is applicable.							
	2. li	f D is	useo	d in d	evice	e E, c	nly 1	6-bit	instr	struction is applicable.							
Oper	perands:																
SD:	SD: Multiplicand SD: Multiplicator D: Product																
Expl	anat	tion	s:														
-	-																
	positive/negative signs of $S_1$ , $S_2$ and $D$ when doing 16-bit and 32-bit operations.																
2.	In 16	6-bit	BIN	l mu	ltipli	catio	on,										
		ł	<b>S</b> 1	)				3	52					D	)+1	D	
	b15	j	<u> </u>		 b00	b	15		~	b	00	b	31			b16 b15b00	
						х[						= [					
	b15	ō is a	a syr	nbo	bit	I	o15	is a	sym	npol	bit	b	31 i	sas	symt	pol bit (b15 of D+1)	
	Syn	nbol	bit	= 0 r	efer	's to	a po	ositi	vev	alue	Э.						
	Symbol bit = 0 refers to a positive value. Symbol bit = 1 refers to a negative value.																
	When D serves as a bit device, it can designate K1 ~ K8 and construct a 32-bit result.																
3.	32-b	oit Bl	IN m	nultip	olica	tion,											
	C	<u>S1</u> +	-1	( <b>S</b> 1	)			(	<b>S</b> <sub>2</sub>	)+1	3	2			(	<b>D</b> +3 <b>D</b> +2 <b>D</b> +1 <b>D</b>	
	b31	lb1	16 b	151	000			b	31	b16	b15	b0	0		be	63. b48 b47. b32 b31. b16 b15. b00	
							Х							=			
	b3′	1 is a	asyr	nbol	bit			b	31 is	sas	ymb	ol bi	it			b63 is a symbol bit (b15 of D+3)	
	Symbol bit = 0 refers to a positive value.																

Symbol bit = 0 refers to a positive value. Symbol bit = 1 refers to a negative value.

When D serves as a bit device, it can designate K1 ~ K8 and construct a 32-bit result, but only stores low 32-bit data.

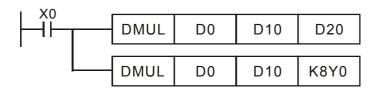
## Program Example 1:

The 16-bit D0 is multiplied by the 16-bit D10 and stores the result in a 32-bit data(D21, D20). The higher 16-bit data is stored in D21 and the lower 16-bit data is stored in D20. On/Off of the most left bit indicates the positive/negative status of the result value.



## Program Example 2:

The 32-bit (D1, D0) is multiplied by the 32-bit (D11, D10) and stores the result in a 64-bit data (D23, D22, D21, D20). On/Off of the most left bit indicates the positive/negative status of the result value.



M	Iner	non	ic			Ор	erar	nds								Function
	DIV	7		D	S	5D (	<b>S</b> 2		D	Divi	sion	1				
	E	Bit De	evice	s					Wor	d Dev	/ices	5				16-bit instruction (7 Steps)
	х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	DIV Continuous execution
S <sub>1</sub>					*	*	*	*	*	*	*	*	*	*	*	32-bit instruction (13 Steps)
S <sub>2</sub>					*	*	*	*	*	*	*	*	*	*	*	DDIV Continuous
D								*	*	*	*	*	*	*		execution
• 1	Note:		1		• Flags: None											
	1. ľ	fS₁a	and S	<sub>2</sub> are	used	used in device F, only 16-bit instruction is applicable.										
2	2. ľ	f D is	use	d in d	evice	vice E, only 16-bit instruction is applicable.										

<b>Operands:</b>
------------------

<b>S</b> 1:1	Dividend
--------------	----------

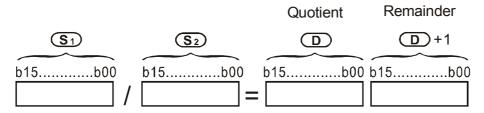
D: Quotient and remainder

### **Explanations:**

- 1. This instruction divides  $S_1$  and  $S_2$  in BIN format and stores the result in **D**. Be careful with the positive/negative signs of  $S_1$ ,  $S_2$  and **D** when doing 16-bit and 32-bit operations.
- 2. This instruction will not be executed when the divisor is 0.

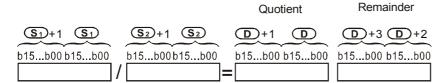
S2: Divisor

3. In 16-bit BIN division,



When D serves as a bit device, it can designate  $K1 \sim K8$  and construct a 32-bit result, and bringing forth the quotient and remainder.

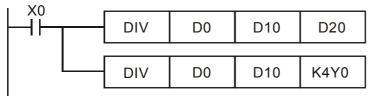
4. In 32-bit BIN division,



When D serves as a bit device, it can designate  $K1 \sim K8$  and construct a 32-bit result, and bringing forth only quotient without the remainder.

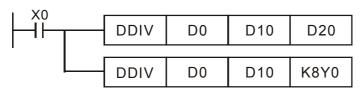
### Program Example 1:

When X0 = On, D0 will be divided by D10 and the quotient will be stored in D20 and remainder in D21. On/Off of the highest bit indicates the positive/negative status of the result value.



### Program Example 2:

When X0 = On, (D1, D0) will be divided by (D11, D10) and the quotient will be stored in (D21, D20) and remainder in (D23, D22). On/Off of the highest bit indicates the positive/negative status of the result value.



М	Inen	non	ic			Оре	eran	ds								Function
	INC	,		D		D Increment										
	B	Bit De	evice	S					Word	d Dev	vices	;				16-bit instruction (3 Steps)
	Х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	INC Continuous
D								*	*	*	*	*	*	*	*	32-bit instruction (5 Steps)
• N 1	Note: 1. If D is used in device F, only 16-bit instruction is applicable.										DINC Continuous execution     Flags: None					

D: Destination device

#### **Explanations:**

- 1. If the instruction is not a pulse execution one, the content in the designated device D will plus "1" in every scan period whenever the instruction is executed.
- 2. In 16-bit operation, 32,767 pluses 1 and obtains -32,768. In 32-bit operation, 2,147,483,647 pluses 1 and obtains -2,147,483,648.
- 3. The operation results will not affect any flags.

#### **Program Example:**

When X0 = Off $\rightarrow$ On, the content in D0 pluses 1 automatically.



N	Iner	non	ic			Ор	eran	ds								Function	
	DE	5		D		(	D			BIN	減−	-					
	E	Bit De	evice	s		Word Devices										16-bit instruction (3 Steps)	
	х	Y	М	S	К	Н	KnX	KnY	KnM	KnS	Т	С	C D E F DEC Continuous execution				
D						* * * * * * *								*	32-bit instruction (5 Steps)		
•	Note	:														DDEC Continuous execution	
1. If D is used in device F, only 16-bit instruction is applicable.												• Flags: None					

D: Destination device

## **Explanations:**

- 1. If the instruction is not a pulse execution one, the content in the designated device D will minus "1" in every scan period whenever the instruction is executed.
- 2. In 16-bit operation, -32,768 minuses 1 and obtains 32,767. In 32-bit operation, -2,147,483,648 minuses 1 and obtains 2,147,483,647.
- 3. The operation results will not affect any flags.

### Program Example:

When  $X0 = Off \rightarrow On$ , the content in D0 minuses 1 automatically.



N	Iner	non	ic			Ор	erar	ıds								Function
	ANC	)		D	S	(S1) (S2) (D) Logical Word AND										
	B	Bit De	evice	S					Word	d Dev	/ices	;				16-bit instruction (7 Steps)
	Х	Y	М	S	К	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	WAND Continuous execution
S <sub>1</sub>					*	*	*	*	*	*	*	*	*	*	*	32-bit instruction (13 Steps)
S <sub>2</sub>					*	*	*	*	*	*	*	*	*	*	*	Continuous
D								*	*	*	*	*	*	*	*	execution
•	Note:															Flags: None
			S₂ ar	nd D	are u	are used in device F, only 16-bit instruction is										
			cable													

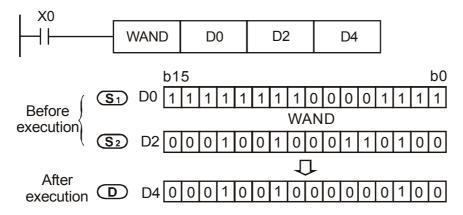
(S): Source data device 1	S2: Source data device 2	D: Operation result
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## **Explanations:**

- 1. This instruction conducts logical AND operation of  $S_1$  and  $S_2$  and stores the result in **D**.
- 2. Operation rule: The corresponding bit of the operation result in **D** will be "0" if any of the bits in  $S_1$  or  $S_2$  is "0".

# Program Example 1:

When X0 = On, the 16-bit D0 and D2 will perform WAND, logical AND operation, and the result will be stored in D4.

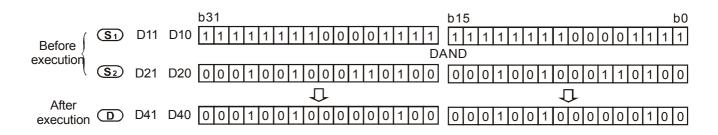


# Program Example 2:

When X1 = On, the 32-bit (D11, D10) and (D21, D20) will perform DAND, logical AND operation, and the result will be stored in (D41, D40).



#### Appendix D Use of Application Instructions | DOP-EXIO Series



M	Inemonic Operands									Function								
	OR			D	S		<b>S</b> 2		D	Logi	ical	Wor	rd O	R				
$\sum_{i=1}^{n}$	В	Bit De	evice	s	Word Devices											16-bit instruction (7 Steps)		
	х	Y	М	S	K H KnX KnY KnM KnS T C								D	Е	F	WOR Continuous execution		
S <sub>1</sub>					*	*	*	*	*	*	*	*	*	*	*			
S <sub>2</sub>					*	*	*	*	*	*	*	*	*	*	*	32-bit instruction (13 Steps) Continuous		
D								*	*	*	*	*	*	*	*	DOR execution		
• 1	Note:				1											Flags: None		
	<ol> <li>If S<sub>1</sub>, S<sub>2</sub> and D are used in device F, only 16-bit instruction is applicable.</li> </ol>																	

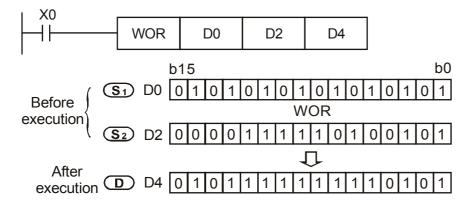
(S): Source data device 1	(S2): Source data device 2	D: Operation result
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## **Explanations:**

- 1. This instruction conducts logical OR operation of  $S_1$  and  $S_2$  and stores the result in **D**.
- 2. Operation rule: The corresponding bit of the operation result in **D** will be "1" if any of the bits in  $S_1$  or  $S_2$  is "1".

## Program Example 1:

When X0 = On, the 16-bit D0 and D2 will perform WOR, logical OR operation, and the result will be stored in D4.

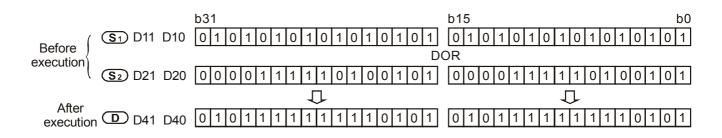


# Program Example 2:

When X1 = On, the 32-bit (D11, D10) and (D21, D20) will perform DOR, logical OR operation, and the result will be stored in (D41, D40).

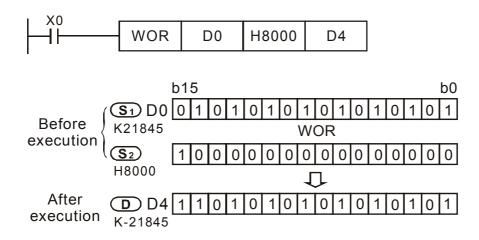


#### Appendix D Use of Application Instructions | DOP-EXIO Series



#### **Program Example 3:**

Positive value becomes negative value.



М	Mnemonic Operands							Function								
	XOR	R		D	S		<b>S</b> 2		D	Logi	cal	Exc	lusiv	ve O	R	
	В	lit De	vice	s	Word Devices										16-bit instruction (7 Steps)	
	Х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	WXOR Continuous execution
S <sub>1</sub>					*	*	*	*	*	*	*	*	*	*	*	
S <sub>2</sub>					*	*	*	*	*	*	*	*	*	*	*	32-bit instruction (13 Steps)
D								*	*	*	*	*	*	*	*	DXOR execution
• •	lote:															Flags: None
	<ul> <li>Note:</li> <li>1. If S<sub>1</sub>, S<sub>2</sub> and D are used in device F, only 16-bit instruction is applicable.</li> </ul>															

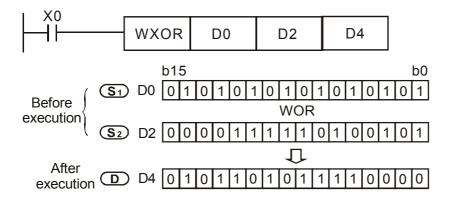
SD: Source data device 1	(S2): Source data device 2	D: Operation result
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## **Explanations:**

- 1. This instruction conducts logical XOR operation of  $S_1$  and  $S_2$  and stores the result in **D**.
- Operation rule: If the bits in S<sub>1</sub> and S<sub>2</sub> are the same, the corresponding bit of the operation result in D will be "0"; if the bits in S<sub>1</sub> and S<sub>2</sub> are different, the corresponding bit of the operation result in D will be "1".

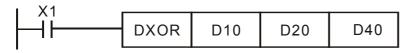
# Program Example 1:

When X0 = On, the 16-bit D0 and D2 will perform WXOR, logical XOR operation, and the result will be stored in D4.

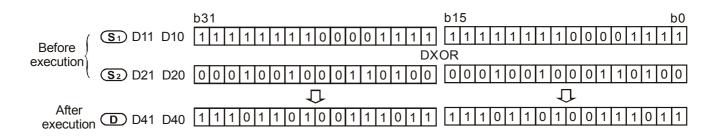


# Program Example 2:

When X1 = On, the 32-bit (D11, D10) and (D21, D20) will perform DXOR, logical XOR operation, and the result will be stored in (D41, D40).



#### Appendix D Use of Application Instructions | DOP-EXIO Series



М	nen	nemonic Operands									Function								
	NEG D D									2's (	Corr	plei	men	t (N	egat	ive)			
	B	Bit De	evice	S		Word Devices										16-bit instruction (3 Steps)			
	Х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	NEG Continuous			
D	* *								*	*	*	*	*	*	*				
	<ul> <li>Note:         <ul> <li>1. If D is used in device F, only 16-bit instruction is applicable.</li> </ul> </li> <li>Flags: None</li> </ul>																		

D: Device to store 2's complement

#### **Explanations:**

- 1. This instruction converts a negative BIN value into an absolute value.
- 2. This instruction can convert a negative binary value into its absolute value.

#### Program Example 1:

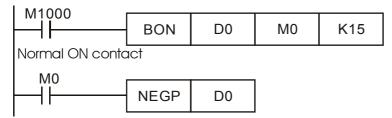
When X0 = Off $\rightarrow$ On, the phase of every bit of the content in D10 will be reversed (0 $\rightarrow$ 1, 1 $\rightarrow$ 0) and pluses 1. The result will then be stored in D10.



#### Program Example 2:

Obtaining the absolute value of a negative value:

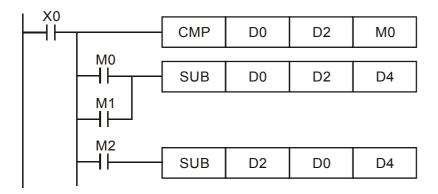
- a) When the 15<sup>th</sup> bit of D0 is "1", M0 = On. (D0 is a negative value).
- b) When M0 = Off→On, NEG instruction will obtain 2's complement of D0 and further its absolute value.



#### Program Example 3:

Obtaining the absolute value by the remainder of the subtraction. When X0 = On,

- a) If D0 > D2, M0 = On.
- b) If D0 = D2, M1 = On.
- c) If D0 < D2, M2 = On.
- d) D4 is then able to remain positive.



## Remarks:

Negative value and its absolute value

- a) The sign of a value is indicated by the highest (most left) bit in the register. 0 indicates that the value is a positive one and 1 indicates that the value is a negative one.
- b) NEG instruction is able to convert a negative value into its absolute value.

Struction is able to convert a negative v	
(D0=2)	
(D0=1) 00000000000000000001	
(D0=0) 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
(D0=-1)	(D0)+1=1 → 0000000000000000000000
(D0=-2)	(D0)+1=2 → 0000000000000000010
(D0=-3)	(D0)+1=3 → 0000000000000011
(D0=-4)	(D0)+1=4 → 00000000000000100
(D0=-5)	(D0)+1=5 → 000000000000000101
(D0=-32,765) 1000000000000000111	(D0)+1=32,765 → 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
(D0=-32,766) 1 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0	(D0)+1=32,766 → 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 0
(D0=-32,767)	(D0)+1=32,767 → 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
(D0=-32,768)	(D0)+1=-32,768 → 1000000000000000000000000
	Max. absolute value is 32,767

Ν	Iner	non	ic			Ор	eran	ds		Function									
	RO	R		D		D	)	n		Rota	atior	n Rig	ght						
	E	Bit De	vice	S					Word	d Dev	vices	;				16-bit instruction (5 Steps)			
	х	Υ	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	ROR Continuous execution			
D								*	*	*	*	*	*	*	*	<u>32-bit instruction (9 Steps)</u>			
n					*	* *										Continuous			
•	Note:															DROR execution			
	1. ľ	f D is	use	d in c	levice	e F, o	nly 1	6-bit	instru	uctior	ı is a	pplic	able.			Flags: M1022 (Carry flag)			
	2. ľ	f D is	s des	signa	ted a	is Kn	Y, Kr	nM, a	and K	(nS, o	only	K4 (	16-bi	t) an	d K8				
	<ol> <li>If D is designated as KnY, KnM, and KnS, only K4 (16-bit) and K8 (32-bit) are valid.</li> </ol>																		
	3. F	Rang	e of r	י: 1 ~	· 16 (	16-bi	t); 1 -	~ 32	(32-b	it)									

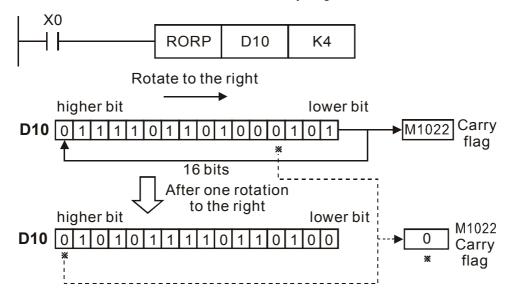
D: Device to be rotated **n**: Number of bits to be rotated in 1 rotation

### **Explanations:**

This instruction rotates the device content designated by  $\mathbf{D}$  to the right for  $\mathbf{n}$  bits.

## Program Example:

When X0 = Off $\rightarrow$ On, the 16 bits (4 bits as a group) in D10 will rotate to the right, as shown in the figure below. The bit marked with  $\approx$  will be sent to carry flag M1022.



Ν	Iner	nemonic Operands														Function
	ROI			D		D	$) \bigcirc$	n		Rota	atior	n Le	ft			
	E	Bit De	vice	S					Wor	d Dev	vices	5				16-bit instruction (5 Steps)
	X	Υ	М	S	К	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	ROL Continuous execution
D								*	*	*	*	*	*	*	*	
n			*     *     *     Steps)													
•	Note:															DROL execution
	1. ľ	f D is	used	d in d	evice	e F, o	nly 1	6-bit	instru	uctior	n is a	pplic	able.			<ul> <li>Flags: M1022 (Carry flag)</li> </ul>
	2. ľ	f D is	des	ignat	ted a	s Kn	Y, Kr	nM, a	and k	(nS,	only	K4 (	16-bi	t) an	d K8	
	<ol> <li>If D is designated as KnY, KnM, and KnS, only K4 (16-bit) and Kt (32-bit) are valid.</li> </ol>															
	3. F	Range	e of n	n: 1 ~	16 (	16-bi	t); 1 -	~ 32	(32-b	oit)						

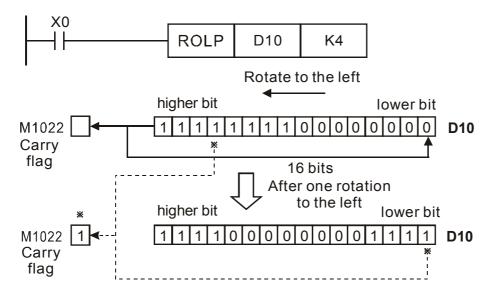
D: Device to be rotated **n**: Number of bits to be rotated in 1 rotation

## **Explanations:**

This instruction rotates the device content designated by **D** to the left for **n** bits.

## Program Example:

When X0 = Off $\rightarrow$ On, the 16 bits (4 bits as a group) in D10 will rotate to the left, as shown in the figure below. The bit marked with  $\approx$  will be sent to carry flag M1022.



N	Iner	nemonic Operands														Function
	RCF	२		D		D	)	n		Rot	atio	n R	ight	wit	h Ca	arry
	E	Bit De	evice	s					Wor	d Dev	vices	;				16-bit instruction (5 Steps)
	Х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	RCR Continuous execution
D		* * * * * * * * *														
n		*     *     *     Sector     Sect														
•	Note:															execution
	1. ľ	f D is	use	d in c	levice	e F, o	nly 1	6-bit	instru	uctior	n is a	pplic	able.			<ul> <li>Flags: M1022 (Carry flag)</li> </ul>
	2. ľ	f D is	s des	signa	ted a	s Kn	Y, Kr	nM, a	and k	KnS,	only	K4 (	16-bi	t) an	d K8	
	(32-bit) are valid.															
:	3. F	Range	e of r	n: 1 ~	· 16 (	16-bi	t); 1 -	~ 32	(32-b	oit)						

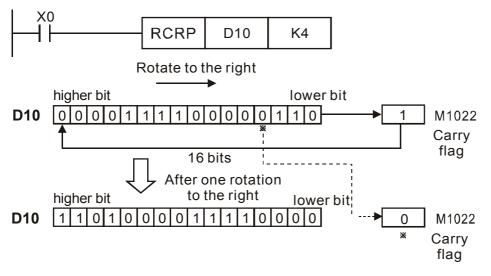
**D**: Device to be rotated **n**: Number of bits to be rotated in 1 rotation

## **Explanations:**

This instruction rotates the device content designated by **D** together with carry flag M1022 to the right for **n** bits.

# Program Example:

When X0 = Off $\rightarrow$ On, the 16 bits (4 bits as a group) in D10 together with carry flag M1022 (total 17 bits) will rotate to the right, as shown in the figure below. The bit marked with  $\approx$  will be sent to carry flag M1022.



N	Iner	Inemonic Operands														Function
	RC	L		D		D	$) \bigcirc$	n		Rot	atio	n Lo	eft v	vith	Car	ry
	E	Bit De	evice	s					Word	d Dev	/ices	;				16-bit instruction (5 Steps)
	Х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	RCL Continuous execution
D																32-bit instruction (9 Steps)
n				* * * Continuous												
•	Note															execution
	1. I	f D is	use	d in d	levice	e F, o	nly 1	6-bit	instru	uctior	n is a	pplic	able.			<ul> <li>Flags: M1022 (Carry flag)</li> </ul>
	2. I	f D is	s des	signa	ted a	s Kn	Y, Kr	nM, a	and k	(nS,	only	K4 (	16-bi	t) an	d K8	
	(32-bit) are valid.															
	3. F	Rang	e of r	ר: 1 <b>~</b>	· 16 (	16-bi	t); 1 -	~ 32	(32-b	it)						

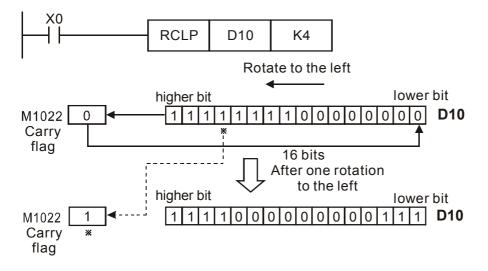
D: Device to be rotated **n**: Number of bits to be rotated in 1 rotation

## **Explanations:**

This instruction rotates the device content designated by **D** together with carry flag M1022 to the left for **n** bits.

## Program Example:

When X0 = Off $\rightarrow$ On, the 16 bits (4 bits as a group) in D10 together with carry flag M1022 (total 17 bits) will rotate to the left, as shown in the figure below. The bit marked with  $\approx$  will be sent to carry flag M1022.



N	Iner	non	ic			0	pera	ands	S							Function
	SFT	R			S	) <	D	<b>n</b> 1		2	Bit S	Shift	Rig	ht		
	E	Bit De	evice	s	Word Devices										16-bit instruction (9 Steps)	
	Х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	E	F	SFTR Continuous execution
S	*	*	*	*												32-bit instruction
D		*	*	*												
n <sub>1</sub>					*	*										
n <sub>2</sub>					*	*										Flags: None
• 1																
	1. Range of n <sub>1</sub> : 1~ 1,024															
	2. Range of $n_2$ : 1~ $n_1$															

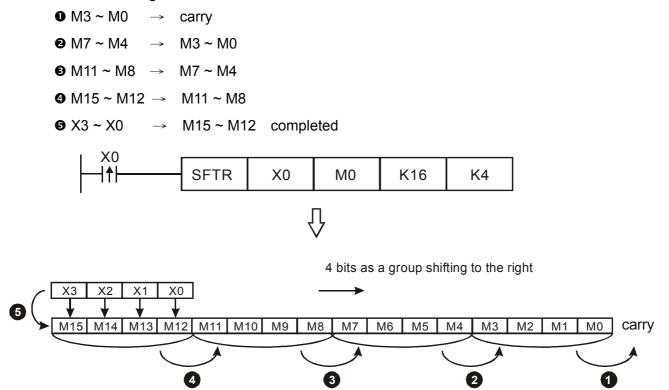
S: Start No. of the shifted device	D: Start No. of the device to be shifted
(n): Length of data to be shifted	(n2): Number of bits to be shifted in 1 shift

### **Explanations:**

This instruction shifts the bit device of  $n_1$  bits (desired length for shifted register) starting from **D** to the right for  $n_2$  bits. **S** is shifted into **D** for  $n_2$  bits to supplement empty bits.

### Program Example:

When X0 = Off $\rightarrow$ On, M0 ~M15 will form 16 bits and shifts to the right (4 bits as a group). The figure below illustrates the right shift of the bits in one scan.



N	Iner	non	ic			0	pera	and	S							Function
	SFTL S D (n1 (n2) Bit Shift Left											t				
$\backslash$	Bit Devices Word Devices											16-bit instruction (9 Steps)				
	X Y M S K H KnX KnY KnM KnS T C D E F											F	SFTL Continuous execution			
S	S * * * *													32-bit instruction		
D	>     *     *     *  <															
n <sub>1</sub>					*	*										
n <sub>2</sub>					*	*										Flags: None
• Note:																
	1. Range of n <sub>1</sub> : 1~ 1,024															
	2. I	Rang	e of r	₁ <sub>2</sub> : 1-	~ n <sub>1</sub>											

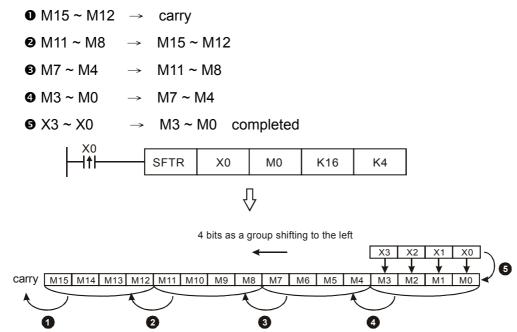
S: Start No. of the shifted device	D: Start No. of the device to be shifted
(n): Length of data to be shifted	(n2): Number of bits to be shifted in 1 shift

### **Explanations:**

This instruction shifts the bit device of  $n_1$  bits (desired length for shifted register) starting from **D** to the left for  $n_2$  bits. **S** is shifted into **D** for  $n_2$  bits to supplement empty bits.

### Program Example:

When X0 = Off $\rightarrow$ On, M0 ~M15 will form 16 bits and shifts to the left (4 bits as a group). The figure below illustrates the left shift of the bits in one scan.



N	Iner	non	ic			Ор	eran	Ids								Function
Z	ZRS	Т						<b>D</b> 2		Zero	o Re	eset				
	Bit Devices Word Devices													16-bit instruction (5 Steps)		
	Х	X Y M S K H KnX KnY KnM KnS T C D E F														ZRST Continuous execution
D <sub>1</sub>		* * * * * * * * * *														
D <sub>2</sub>															32-bit instruction	
1 •	Note:															
	<ol> <li>Number of operand D1 ≤ Number of operand D2.</li> </ol>															Flags: None
	2. C	D₁ an	d D <sub>2</sub>	have	e to d	esign	ate c	levic	es of	the s	ame	type				

(D1): Start device of the range to be reset (D2): End device of the range to be reset

### **Explanations:**

- 1. When the instruction is executed, area from  $D_1$  to  $D_2$  will be cleared.
- 2. 16-bit counter and 32-bit counter cannot use ZRST instruction together.
- 3. When  $D_1 > D_2$ , only operands designated by  $D_2$  will be reset.

## Program Example:

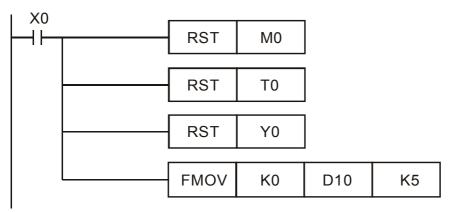
- 1. When X0 = On, auxiliary relays M300 ~ M399 will be reset to Off.
- 2. When X1 = On, 16 counters C0 ~ C127 will all be reset (writing in 0; contact and coil being reset to Off).
- 3. When X2 = On, steps S0 ~ S127 will be reset to Off.
- 4. When X3 = On, data registers  $D0 \sim D100$  will be reset to 0.
- 5. When X4 = On, 32-bit counters C235 ~ C254 will all be reset. (writing in 0; contact and coil being reset to Off)

I X0			
	ZRST	M300	M399
X1	ZRST	C0	C127
X10	ZRST	Т0	T127
X2	ZRST	S0	S127
X3	ZRST	D0	D100
X4 ──┤├────	ZRST	C235	C254

#### Appendix D Use of Application Instructions | DOP-EXIO Series

#### **Remarks:**

- 1. Devices, e.g. bit devices Y, M, S and word devices T, C, D, can use RST instruction.
- 2. FMOV instruction can be also used to send K0 to word devices T, C, D or bit registers KnY, KnM, KnS for reset.



N	/Iner	non	ic			Оре	eran	ds								Function
	SUM D S D									Sun	۱ of	Acti	ve E	Bits		
	Bit Devices Word Device										/ices	;				16-bit instruction (5 Steps)
	X Y M S K H KnX KnY KnM KnS T C D E F										F	SUM Continuous execution				
S	*     * <td>*</td> <td>22 bit instruction (0 Store)</td>										*	22 bit instruction (0 Store)				
D	D											*	<u>32-bit instruction (9 Steps)</u> DSUM			
•	<ul> <li>Note:</li> <li>1. If S and D is used in device F, only 16-bit instruction is applicable.</li> </ul>													e.	Flags: M1020 (Zero flag)	

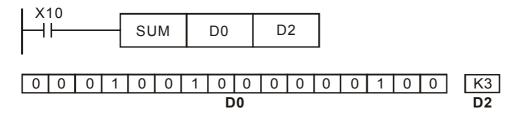
S: Source device D: Destination device for storing counted value

#### **Explanations:**

- 1. Among the bits of **S**, the total of bits whose content is "1" will be stored in **D**.
- 2. When all the 16 bits of **S** are "0", zero flag M1020 = On.
- 3. When 32- instruction is in use, **D** will occupy 2 registers.

#### **Program Example:**

When X10 = On, among the 16 bits of D0, the total of bits whose content is "1" will be stored in D2.



N	Iner	non	ic			Ор	eran	ds								Function
	BON   D   S   D   n   Check Specified Bit												Sta	tus		
	Bit Devices Word Devices													16-bit instruction (7 Steps)		
	X Y M S K H KnX KnY KnM KnS T C D E F											F	BON Continuous execution			
S				* * * * * * * * * * * *												
D	D * * *														32-bit instruction (13 Steps) Continuous	
n					*	*										DBON execution
• 1	Note:					•	•		•			•	•			• Flags: None
	1. If S is used in device F, only 16-bit instruction is applicable.															
:	2. F	Rang	e of r	n: 0 ~	· 15 (	16-bi	it inst	ructio	on); 0	~ 31	(32-	bit in	struc	tion)		

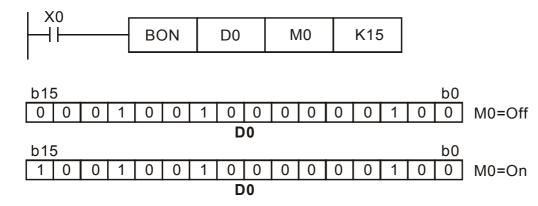
S: Source device D: Device for storing check result D: Bits specified for check

# **Explanations:**

When the  $\mathbf{n}^{\text{th}}$  bit of **S** is "1", D = On; when the  $\mathbf{n}^{\text{th}}$  bit of **S** is "0", D = Off.

## Program Example:

- 1. When X0 = On, assume the  $15^{th}$  bit of D0 is "1", and M0 = On. Assume the  $15^{th}$  bit of D0 is "0", and M0 = Off.
- 2. When X0 goes Off, M0 will remains in its previous status.



N	Inen	non	ic			Ор	eran	ds								Function
Ν	/IEA	Ν		D	G	<b>)</b>	D		$\supset$	Mea	an					
	Bit Devices Word									d Dev	/ices	5				16-bit instruction (7 Steps)
	X Y M S K H KnX KnY KnM KnS T C D E F										F	MEAN Continuous execution				
S							*	*	*	*	*	*	*			
D	D * * * * * * * * * * *												*	32-bit instruction (13 Steps)		
n					*	*										DMEAN execution
1 •															Flags: None	
	<ol> <li>If D is used in device F, only 16-bit instruction is applicable.</li> </ol>															
2	2. F	Range	e of r	n: 1 ~	<sup>,</sup> 64											

S: Start device to obtain mean value D: Destination device for storing mean value

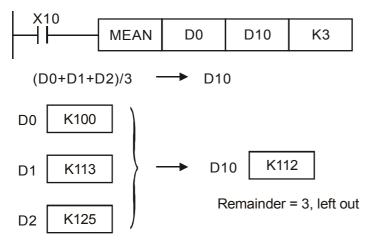
n: The number of consecutive source devices used

#### **Explanations:**

- After the content of n devices starting from S are added up, the mean value of the result will be stored in D.
- 2. Remainders in the operation will be left out.
- 3. Provided the No. of designated device exceeds its normal range, only the No. within the normal range can be processed.
- 4. If **n** falls without the range of 1 ~ 64, DOP-EXIO series will determine it as an "instruction operation error".

### **Program Example:**

When X10 = On, the contents in 3 (n = 3) registers starting from D0 will be summed and then divided by 3. The obtained mean value will be stored in D10 and the remainder will be left out.



N	Iner	non	ic			Ор	erar	ıds								Function
	RE						> <	n		Refi	resh	1				
	Bit Devices Word Devices												16-bit instruction (5 Steps)			
	X Y M S K H KnX KnY KnM KnS T C D E F													F	REF Continuous execution	
D	*	* *														
n	n * * 1														32-bit instruction	
	<ul> <li>Note:</li> <li>1. D must designate X0, X10, Y0, Y10the points whose 1s digit is "0". See remarks for more details.</li> </ul>													Flags: None		
	2. F	Rang	e of r	n: 8 ~	256	(has	to be	e the	multi	iple o	f 8).					

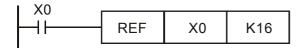
D: Start device to be I/O refreshed n: Number of items to be I/O refreshed

## **Explanations:**

- 1. The status of all input/output terminals of DOP-EXIO series will be updated after the program scans to END. When the program starts to scan, the status of the external input terminal is read and stored into the memory of the input point. The output terminal will send the content in the output memory to the output device after END instruction is executed. Therefore, this instruction is applicable when the latest input/output data are needed for the operation.
- 2. REF command can be used between FOR and NEXT instruction, and between CJ instructions. If there is an interrupt occurs in the period of time when input/output terminals is working, REF command can also be used. It can be also used to interrupt the subroutine program.
- 3. The operand **D** should always be a multiple of 10, i.e. 00, 10, 20, 30... etc., so it should be X0, X10, Y0, Y10... etc. The operand **n** hould always be a multiple of 8, i.e. 8, 16, 24, 32...etc. and its available range is 8~256. If the value of **n** is out of the stated range (8~256) or not a multiple of 8, an "operation error" will be generated.

### Program Example 1:

When X0 = On, DOP-EXIO series will read the status of input points X0 ~ X7 immediately and refresh the input signals without any input delay.



# Program Example 2:

When X0 = On, the 8 output signal from Y0  $\sim$  Y7 will be sent to output terminals and refreshed. But there is 10ms input delay occurred on the input signals.

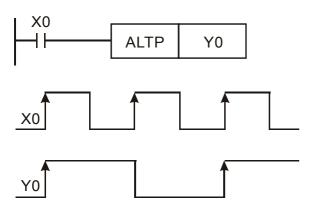
I X0			
	REF	Y0	K8

N	Iner	non	ic			Оре	əran	ds								Function
	ALT D									Alte	rnat	e St	ate			
	Bit Devices									d Dev	vices					16-bit instruction (3 Steps)
	х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	ALT Continuous execution
D		*	*	* *											32-bit instruction	
																Flags: None

D: Destination device

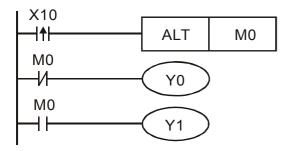
#### Program Example 1:

When X0 goes from Off to On for the first time, Y0 will be On. When X0 goes from Off to On for the second time, Y0 will be Off.



#### **Program Example 2:**

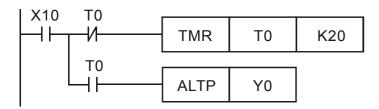
Using a single switch to enable and disable control. At the beginning, M0 = Off, so Y0 = On and Y1 = Off. When X10 switches between On/Off for the first time, M0 will be On, so Y1 = On and Y0 = Off. For the second time of On/Off switching, M0 will be Off, so Y0 = On and Y1 = Off.



#### **Program Example 3:**

Generating flashing. When X10 = On, T0 will generate a pulse every 2 seconds and Y0 output will switch between On and Off following the T0 pulses.

#### Appendix D Use of Application Instructions | DOP-EXIO Series



N	Iner	non	ic			Ор	erar	Ids								Function
	ASCI (SD) (n)									Cor	vert	He	x to	ASC	CII	
	B	Bit De	evice	s					Word	d Dev	vices	;				16-bit instruction (7 Steps)
	X Y M S K H KnX KnY KnM KnS T C D E											F	ASCI Continuous execution			
S												*				
D													<u>32-bit instruction</u>			
n	n * *															
• 1	Note:														• Flags: M1161 (8/16 bit mode switch)	
	1. F	Rang	e of r	า: 1 ~	- 256											

S: Start device for source data D: Start device for storing the converted result

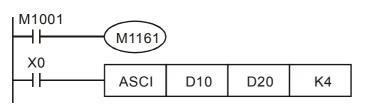
n: Number of bits to be converted

### **Explanations:**

- 16-bit conversion mode: When M1161 = Off, the instruction converts every bit of the hex data in S into ASCII codes and send them to the 8 high bits and 8 low bits of D. n = the converted number of bits.
- 8-bit conversion mode: When M1161 = On, the instruction converts every bit of the hex data in S into ASCII codes and send them to the 8 low bits of D. n = the number of converted bits. (All 8 high bits of D = 0)

# Program Example 1:

- 1. M1161 = Off: The 16-bit conversion mode
- 2. When X0 = On, convert the 4 hex values in D10 into ASCII codes and send the result to registers starting from D20.



3. Assume

(D10) = 0ABC H	'0' = 30H	'1' = 31H	'5' = 35H
(D11) = 1234 H	'A' = 41H	'2' = 32H	'6' = 36H
(D12) = 5678 H	'B' = 42H	'3' = 33H	'7' = 37H
	'C' = 43H	'4' = 34H	'8' = 38H

4. When **n** = 4, the bit structure will be as:

#### Appendix D Use of Application Instructions | DOP-EXIO Series

D10=0ABC H										
0 0 0 0 1 0 1 0	1 0 1 1 1 1 0 0									
0   A	BC									
D20 High Byte	Low Byte									
0 1 0 0 0 0 1	0 0 1 1 0 0 0 0									
"A″ → 41H	"0″ → 30H									
D21 High Byte	Low Byte									
0 1 0 0 0 0 1 1	0 1 0 0 0 0 1 0									
°C″ → 43H	<sup>™</sup> B″ → 42H									

5. When **n** = 6, the bit structure will be as:

b15 D10=H 0123											b0		
0 0 0	0	0	0	0	1	0	0	1	0	0	0	1	1
0			1	1			2	2			3		
b15	b15 D11=H 4567											b0	
0 1 0	0	0	1	0	1	0	1	1	0	0	1	1	1
4	I		Ę	5			6	6			7		I
			(	Cor	ive	rteo	d to						
b15	D	20											b0
0 0 1	1	0	1	1	1	0	0	1	1	0	1	1	0
<i>``7″</i>		•	37H	Η			~	6″		► 3	86H		I
b15	D	21											b0
0 0 1	1	0	0	0	1	0	0	1	1	0	0	0	0
1″		► :	31F	Η			~	`0″		► :	30H		I
b15	D	22											b0
0 0 1	1	0	0	1	1	0	0	1	1	0	0	1	0
``3″		► :	33F	H			~	2″		► :	32H		

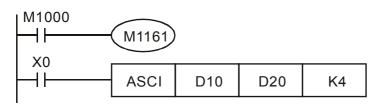
6. When **n** = 1 ~ 16:

n D	K1	K2	K3	K4	K5	K6	K7	K8
D20 Low Byte	"3"	"2"	"1"	"0"	"7"	"6"	"5"	"4"
D20 High Byte		"3"	"2"	"1"	"0"	"7"	"6"	"5"
D21 Low Byte			"3"	"2"	"1"	"0"	"7"	"6"
D21 High Byte				"3"	"2"	"1"	"0"	"7"
D22 Low Byte					"3"	"2"	"1"	"0"
D22 High Byte						"3"	"2"	"1"
D23 Low Byte							"3"	"2"
D23 High Byte								"3"
D24 Low Byte								
D24 High Byte				No				
D25 Low Byte				Change				
D25 High Byte								
D26 Low Byte								
D26 High Byte								
D27 Low Byte								
D27 High Byte								

n D	K9	K10	K11	K12	K13	K14	K15	K16
D20 Low Byte	"B"	"A"	"9"	"8"	"F"	"E"	"D"	"C"
D20 High Byte	"4"	"B"	"A"	"9"	"8"	"F"	"E"	"D"
D21 Low Byte	"5"	"4"	"B"	"A"	"9"	"8"	"F"	"E"
D21 High Byte	"6"	"5"	"4"	"B"	"A"	"9"	"8"	"F"
D22 Low Byte	"7"	"6"	"5"	"4"	"B"	"A"	"9"	"8"
D22 High Byte	"0"	"7"	"6"	"5"	"4"	"B"	"A"	"9"
D23 Low Byte	"1"	"0"	"7"	"6"	"5"	"4"	"B"	"A"
D23 High Byte	"2"	"1"	"0"	"7"	"6"	"5"	"4"	"B"
D24 Low Byte	"3"	"2"	"1"	"0"	"7"	"6"	"5"	"4"
D24 High Byte		"3"	"2"	"1"	"0"	"7"	"6"	"5"
D25 Low Byte			"3"	"2"	"1"	"0"	"7"	"6"
D25 High Byte				"3"	"2"	"1"	"0"	"7"
D26 Low Byte			No		"3"	"2"	"1"	"0"
D26 High Byte			No	"3"	"2"	"1"		
D27 Low Byte			Change				"3"	"2"
D27 High Byte		·			·		·	"3"

### **Program Example 2:**

- 1. M1161 = On: The 8-bit conversion mode
- 2. When X0 = On, convert the 4 hex values in D10 into ASCII codes and send the result to registers starting from D20.



### 3. Assume

(D10) = 0ABC H	'0' = 30H	'1' = 31H	'5' = 35H
(D11) = 1234 H	'A' = 41H	'2' = 32H	'6' = 36H
(D12) = 5678 H	'B' = 42H	'3' = 33H	'7' = 37H
	'C' = 43H	'4' = 34H	'8' = 38H

4. When **n** = 2, the bit structure will be as:

D10=0ABC H												
0 0	0	0	1	0	1	0	1	0	1	1	1	1 0 0
(	)			A	4			E	3			C
D20 High Byte Low Byte								te				
0 1	0	0	0	0	0	1	0	0	1	1	0	0 0 0
Ň	``A″ → 41H \``0″ → 30H								30H			
D21 High Byte Low Byte								te				
0 1	0	0	0	0	1	1	0	1	0	0	0	0 1 0
"C″ → 43H								v	`В″		► 4	42H

D10=0ABC	н									
0 0 0 0	) 1	0 1	0	1	0	1	1	1	1 0	0
0	I	А			E	3	l		С	I
ASCII code	e of D2	20=B	is 4	2H						
0 0 0 0	0 0	0 0	0	0	0	1	1	0	0 0	0
					4	-			2	
ASCII code	e of D2	21=C	is 4	3H						
0 0 0 0	0 0	0 0	0	0	1	0	0	0	0 1	0
					4	ŀ			3	

# 5. When $\mathbf{n} = 4$ , the bit structure will be as:

b1	5					D1(	)= ŀ	H 0'	123						b0
0	0	0	0	0	0	0	1	0	0	1	0	0	0	1	1
Ι	(	)				1			2	2			3	3	

Converted to

b15 0 0 0	D20	0 0 0	b0 0 1 1 0 0 0 0
		I	"0″ <b>→</b> 30H
b15	D21		b0
0 0 0	0 0 0	0 0 0	0 1 1 0 0 1 1
		I	`1″ → 31H
b15	D22		b0
0 0 0	0 0 0	0 0 0	0 1 1 0 0 1 0
			``2″ <b>→</b> 32H
b15	D23		b0

	,		-	20											00	
0	0	0	0	0	0	0	0	0	0	1	1	0	0	1	1	
									"	3″	_	▶ 3	3H			

6. When **n** = 1 ~ 16:

n D	K1	K2	K3	K4	K5	K6	К7	K8
D20	"3"	"2"	"1"	"0"	"7"	"6"	"5"	"4"
D21		"3"	"2"	"1"	"0"	"7"	"6"	"5"
D22			"3"	"2"	"1"	"0"	"7"	"6"
D23				"3"	"2"	"1"	"0"	"7"
D24					"3"	"2"	"1"	"0"
D25						"3"	"2"	"1"
D26							"3"	"2"
D27								"3"
D28								
D29				No				
D30				Change				
D31								
D32								
D33								
D34								
D35								

n D	K9	K10	K11	K12	K13	K14	K15	K16
D20	"B"	"A"	"9"	"8"	"F"	"E"	"D"	"C"
D21	"4"	"B"	"A"	"9"	"8"	"F"	"E"	"D"
D22	"5"	"4"	"B"	"A"	"9"	"8"	"F"	"E"
D23	"6"	"5"	"4"	"B"	"A"	"9"	"8"	"F"
D24	"7"	"6"	"5"	"4"	"B"	"A"	"9"	"8"
D25	"0"	"7"	"6"	"5"	"4"	"B"	"A"	"9"
D26	"1"	"0"	"7"	"6"	"5"	"4"	"B"	"A"
D27	"2"	"1"	"0"	"7"	"6"	"5"	"4"	"B"
D28	"3"	"2"	"1"	"0"	"7"	"6"	"5"	"4"
D29		"3"	"2"	"1"	"0"	"7"	"6"	"5"
D30			"3"	"2"	"1"	"0"	"7"	"6"
D31				"3"	"2"	"1"	"0"	"7"
D32			No		"3"	"2"	"1"	"0"
D33			No			"3"	"2"	"1"
D34			Change				"3"	"2"
D35								"3"

N	Iner	non	ic			Ор	eran	ds		Function						Function
	HE	K			G	5) (	D		D	Convert ASCII to Hex						
	E	Bit De	evice	S					Word	d Dev	vices	5				16-bit instruction (7 Steps)
	х	Υ	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	HEX Continuous execution
S					*	*	*	*	*	*	*	*	*			32-bit instruction
D								*	*	*	*	*	*	*	*	
n					*	*										
• 1	Note:															Flags: M1161 (8/16 bit mode switch)
	1. Range of n: 1 ~ 256															

S: Start device for source data D: Start device for storing the converted result

n: Number of bits to be converted

### **Explanations:**

- 16-bit conversion mode: When M1161 = Off, the instruction is in 16-bit conversion mode. ASCII codes of the 8 high bits and 8 low bits of the hex data in S are converted into hex value and sent to D (every 4 bits as a group). n = the number of bits converted into ASCII codes.
- 8-bit conversion mode: When M1161 = On, the instruction is in 8-bit conversion mode. Every bit of the hex data in S are converted into ASCII codes and sent to the 8 low bits of D. n = the number of converted bits. (All 8 high bits of D = 0)

# Program Example 1:

- 1. M1161 = Off: The 16-bit conversion mode
- When X0 = On, convert the ASCII codes stored in the registers starting from D20 into hex value and send the result (every 4 bits as a group) to registers starting from D10. n = 4.



3. Assume

S	ASCII code	Converted to hex	S	ASCII code	Converted to hex
D20 low byte	H 43	"C"	D24 low byte	H 34	"4"
D20 high byte	H 44	"D"	D24 high byte	H 35	"5"
D21 low byte	H 45	"E"	D25 low byte	H 36	"6"
D21 high byte	H 46	"F"	D25 high byte	H 37	"7"
D22 low byte	H 38	"8"	D26 low byte	H 30	"0"
D22 high byte	H 39	"9"	D26 high byte	H 31	"1"
D23 low byte	H 41	"A"	D27 low byte	H 32	"2"
D23 high byte	H 42	"B"	D27 high byte	H 33	"3"

4. When **n** = 4, the bit structure will be as:

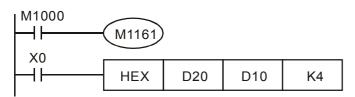
D20	0	1			-	-		1			1	1	0	0 0	0
		41				`A′					30	_	->	`0′	
D21	0	1						1				-	0		0
		43		$\rightarrow$		Ċ					42	-	<b>→</b>	`В′	I
D10	0	0	0	0	1	0	1	0	1	0	1	1	1	1 0	0
		0	)			-	À			E	3			С	

5. When **n** = 1 ~ 16:

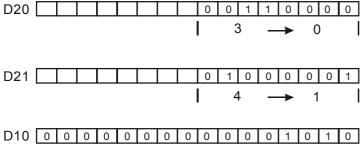
D	D13	D12	D11	D10
1				***C H
2				**CD H
3				*CDE H
4				CDEF H
5	The		***C H	DEF8 H
6	undesignated		**CD H	EF89 H
7	parts in the registers in use		*CDE H	F89A H
8	are all 0.		CDEF H	89AB H
9		***C H	DEF8 H	9AB4 H
10		**CD H	EF89 H	AB45 H
11		*CDE H	F89A H	B456 H
12		CDEF H	89AB H	4567 H
13	***C H	DEF8 H	9AB4 H	5670 H
14	**CD H	EF89 H	AB45 H	6701 H
15	*CDE H	F89A H	B456 H	7012 H
16	CDEF H	89AB H	4567 H	0123 H

### Program Example 2:

1. M1161 = On: The 8-bit converstion mode



2. When **n** = 4, the bit structure will be as:



3. Assume

S	ASCII code	Converted to hex	S	ASCII code	Converted to hex
D20	H 43	"C"	D28	H 34	"4"
D21	H 44	"D"	D29	H 35	"5"
D22	H 45	"E"	D30	H 36	"6"
D23	H 46	"F"	D31	H 37	"7"
D24	H 38	"8"	D32	H 30	"0"
D25	H 39	"9"	D33	H 31	"1"
D26	H 41	"A"	D34	H 32	"2"
D27	H 42	"B"	D35	H 33	"3"

L

4. When **n** = 1 ~ 16:

D n	D13	D12	D11	D10
1				***C H
2				**CD H
3				*CDE H
4				CDEF H
5	The		***C H	DEF8 H
6	undesignated		**CD H	EF89 H
7	parts in the registers in use		*CDE H	F89A H
8	are all 0.		CDEF H	89AB H
9		***C H	DEF8 H	9AB4 H
10		**CD H	EF89 H	AB45 H
11		*CDE H	F89A H	B456 H
12		CDEF H	89AB H	4567 H
13	***C H	DEF8 H	9AB4 H	5670 H
14	**CD H	EF89 H	AB45 H	6701 H
15	*CDE H	F89A H	B456 H	7012 H
16	CDEF H	89AB H	4567 H	0123 H

	Mnemonic Operands								Function								
	ABS D D						Absolute Value										
	Bit Devices					Word Devices											16-bit instruction (3 Steps)
	X Y M S K H KnX KnY KnM					KnS	Т	С	D	Е	F	ABS Continuous execution					
D	D * * * * * *				*	*	*	*	*	*	*	32-bit instruction (5 Steps)					
										DABS Continuous execution							
																	Flags: None

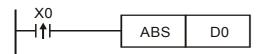
D: Device of the absolute value

#### **Explanations:**

This instruction obtains the absolute value of the content in the designated in **D**.

#### **Program Example:**

When X0 = Off $\rightarrow$ On, obtain the absolute value of the content in D0.



N	Mnemonic						eran	ds		Function								
S	SWAP D					S						/ap						
	Bit Devices V							Word	d Dev	vices					16-bit instruction (5 Steps)			
	X Y M S K H KnX KnY Kn1						KnM	KnS	Т	С	D	Е	F	SWAP Continuous				
S	S S * * * * * * * * * *						*	32-bit instruction (9 Steps)										
• •	• Note:												DSWAP Continuous execution					
	1. ľ	f D is	use	d in c	levice	e F, o	nly 1	6-bit	instru	uctior	is a	pplic	able.			• Flags: None		

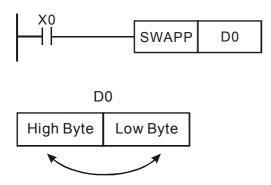
S: Device for swapping 8 high/low byte.

# **Explanations:**

- 1. As 16-bit instruction: the contents in the 8 high bytes and 8 low bytes are swapped.
- 2. As 32-bit instruction: the 8 high bytes and 8 low bytes in the two registers swap with each other respectively.

# Program Example 1:

When X0 = On, the high 8 bytes and low 8 bytes in D0 will swap with each other.



### **Program Example 2:**

When X0 = On, the high 8 bytes and low 8 bytes in D11 will swap with each other and the high 8 bytes and low 8 bytes in D10 will swap with each other.



N	Mnemonic Operands							Function										
	LD% D S1 S2								Con	itact	Log	gical	Ope	erati	on LD※			
	Bit Devices								Wor	d Dev	/ices	;		16-bit instruction (5 Steps)				
	Х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	LD × execution		
<b>S</b> <sub>1</sub>					*	*	*	*	*	*	*	*	*	*	*	32-bit instruction (9 Steps)		
S <sub>2</sub>					*	*	*	*	*	*	*	*	*	*	*	Continuous		
• N	• Note: ※: =, >, <, <>, ≦, ≧												DLD * execution					
													Flags: None					

**D**LD>

**D**LD<

DLD <>

DLD < =

DLD > =

# **Explanations:**

LD>

LD <

LD <>

LD < =

LD > =

1. This instruction compares the content in  $S_1$  and  $S_2$ . If the result is not "equal", the continuity of the instruction is enabled. If the result is "equal", the continuity of the instruction is disabled.

 $(S_1)$ 

 $(S_1 < S_2)$ 

**S**1<sub>≠</sub>**S**2

 $S1 \leq S2$ 

 $s_2$ 

**S**1≤**S**2

**S**1≥**S**2

 $(S_1) = (S_2)$ 

 $(S_1) > (S_2)$ 

S1 < S2

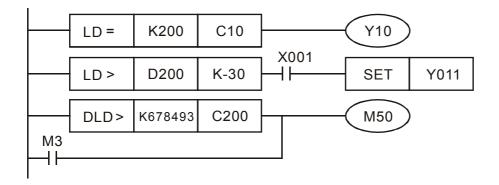
Ζ.	$LD \And (=, ?, \langle, \langle ?, \rangle \ge,$	$\leq$ ) instruction is used		/itil B03.
	16 -bit instruction	32 -bit instruction	Continuity condition	No-continuity condition
	LD=	<b>D</b> LD=	<b>S</b> 1= <b>S</b> 2	<b>S</b> 1 <sub>≠</sub> <b>S</b> 2

2. LD% (=, >, <, <>,  $\leq$ ,  $\geq$ ) instruction is used for direct connection with BUS.

- 3. If the most left bit of  $S_1$  and  $S_2$  (16-bit instruction: b15  $\cdot$  32-bit instruction: b31) is "1", the compare value will be regarded as the negative value for comparison.
- When 32-bit counters (C200 ~) are used in this instruction for comparison, make sure to adopt 32-bit instruction (DLD%). If 16-bit instructions (LD%) is adopted, a "program error" will occur and the ERROR indicator on the panel will flash and the connecting controller can not run..

### **Program Example:**

- 1. When the value of C0 is equal to the value of K200, Y10 = On.
- 2. When the value of D200 is higher than -29 and X1 = On, Y11 = On will be retained.
- 3. When the value of C200 is lower than 678,493 and M3 = On, M50 = On.



Ν	Mnemonic					Ор	erar	ıds			Function								
AND% D S1 S						52)		Con	ntact	Log	gical	Ope	erati	on AND※					
	Bit Devices								Word	d Dev	/ices	16-bit instruction (5 Steps)							
	X Y M S K H KnX KnY KnM Ki				KnS	Т	С	D	Е	F	AND Continuous								
S <sub>1</sub>					*	*	*	*	*	*	*	*	*	*	*	32-bit instruction (9 Steps)			
S <sub>2</sub>	S2       *						*	DAND Continuous * execution											
													Flags: None						

(S1): Data source device 1	S2: Data source device 2
----------------------------	--------------------------

# **Explanations:**

1. This instruction compares the content in  $S_1$  and  $S_2$ . If the result is not "equal", the continuity of the instruction is enabled. If the result is "equal", the continuity of the instruction is disabled.

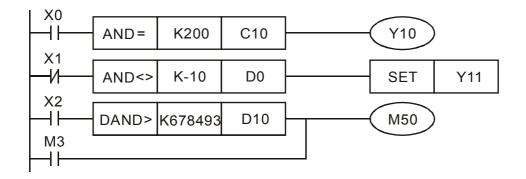
16 -bit instruction	32 -bit instruction	Continuity condition	No-continuity condition
AND=	DAND=	<b>S</b> 1= <b>S</b> 2	<b>S</b> 1 <b>≠S</b> 2
AND>	DAND>	<b>S</b> 1> <b>S</b> 2	<b>S</b> 1 ≤ <b>S</b> 2
AND<	DAND<	<b>S</b> 1< <b>S</b> 2	<b>S</b> 1≥ <b>S</b> 2
AND<>	DAND<>	<b>S</b> 1≠ <b>S</b> 2	<b>S</b> 1= <b>S</b> 2
AND<=	DAND <=	<b>S</b> 1≦ <b>S</b> 2	<b>S</b> 1> <b>S</b> 2
AND>=	DAND>=	<b>S</b> 1≥ <b>S</b> 2	<b>S</b> 1< <b>S</b> 2

2. AND (=, >, <, <>,  $\leq$ ,  $\geq$ ) instruction is used for direct connection with BUS.

- 3. If the most left bit of  $S_1$  and  $S_2$  (16-bit instruction: b15  $\cdot$  32-bit instruction: b31) is "1", the compare value will be regarded as the negative value for comparison.
- 4. When 32-bit counters (C200 ~) are used in this instruction for comparison, make sure to adopt 32-bit instruction (DAND<sup>\*</sup>). If 16-bit instructions (AND<sup>\*</sup>) is adopted, a "program error" will occur and the ERROR indicator on the panel will flash and the connecting controller can not run..

# Program Example:

- 1. When X0 = On and the value of C0 is equal to the value of K200, Y10 = On.
- 2. When X0 = Off and the value of D0 is not equal to -10 and X1 = On, Y11 = On will be retained.
- 3. When X2 = On and the value of (D11, D10) is lower than 678,493 and M3 = On, M50 = On.



N	Mnemonic Operands														Function		
	OR** D (S1) (S2)							Con	tact	Log	jical	on OR※					
	E	Bit De	evice	s					Wor	d Dev	/ices	i				16-bit instruction (5 Steps)	
	Х	Y	М	S	к	Н	KnX	KnY	KnM	KnS	Т	С	D	Е	F	OR Continuous	
S <sub>1</sub>					*	*	*	*	*	*	*	*	*	*	*	32-bit instruction (9 Steps)	
S <sub>2</sub>	S <sub>2</sub> * * * * * * * * * * * * *							*	Continuous								
• N	• Note: ※: =, >, <, <>, ≦, ≧												DOR * execution				
													Flags: None				

S1: Data source device 1	(S2): Data source device 2

### **Explanations:**

1. This instruction compares the content in  $S_1$  and  $S_2$ . If the result is not "equal", the continuity of the instruction is enabled. If the result is "equal", the continuity of the instruction is disabled.

16 -bit instruction	32 -bit instruction	Continuity condition	No-continuity condition
OR=	DOR=	<b>S</b> 1= <b>S</b> 2	<b>S</b> 1≠ <b>S</b> 2
OR>	DOR>	<b>S</b> 1> <b>S</b> 2	<b>S</b> 1 ≤ <b>S</b> 2
OR<	DOR<	<b>S</b> 1< <b>S</b> 2	<b>S</b> 1≥ <b>S</b> 2
OR<>	DOR<>	<b>S</b> 1≠ <b>S</b> 2	<b>S</b> 1= <b>S</b> 2
OR<=	DOR<=	<b>S</b> 1≦ <b>S</b> 2	<b>S</b> 1> <b>S</b> 2
OR>=	DOR>=	<b>S</b> 1≥ <b>S</b> 2	<b>S</b> 1< <b>S</b> 2

2. OR % (=, >, <, <>,  $\leq$ ,  $\geq$ ) instruction is used for direct connection with BUS.

- 3. If the most left bit of  $S_1$  and  $S_2$  (16-bit instruction: b15  $\cdot$  32-bit instruction: b31) is "1", the compare value will be regarded as the negative value for comparison.
- 4. When 32-bit counters (C200 ~) are used in this instruction for comparison, make sure to adopt 32-bit instruction (DOR<sup>\*</sup>). If 16-bit instructions (OR<sup>\*</sup>) is adopted, a "program error" will occur and the ERROR indicator on the panel will flash and the connecting controller can not run..

### **Program Example:**

- 1. When X1 = On, or the value of C0 is equal to the value of K200, Y10 = On.
- 2. When X2 and M30 are both, or the value of 32-bit data (D101, D100) is equal to or higher than K100,000, M60 = On.

