



2007-07-19  
5011628404-BM04

## VFDB Series Braking Modules Instruction Sheet

### 1 Preface

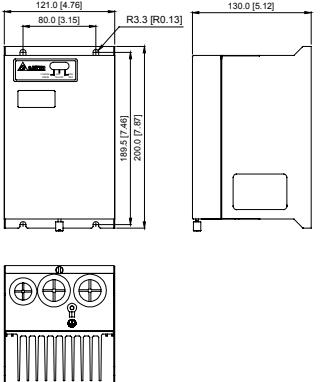
Thank you for choosing DELTA's braking module. VFDB braking units are applied to absorb the motor regeneration energy when the three-phase induction motor stops by deceleration. With VFDB braking unit, the regeneration energy will be dissipated in dedicated braking resistors. To prevent mechanical or human injury, please refer to this instruction sheet before wiring. VFDB braking units are suitable for DELTA AC Motor Drives VFD Series 230V/460V/575V. VFDB braking units need to be used in conjunction with BR series braking resistors to provide the optimum braking characteristics. VFDB braking units (2015, 2022, 4030, 4045 and 5055) are approved by Underwriters Laboratories, Inc. (UL) and Canadian Underwriters Laboratories (cUL). The content of this instruction sheet may be revised without prior notice. Please consult our distributors or download the most updated version at <http://www.delta.com.tw/industrialautomation/>.

### 2 Specifications

#### VFDB Braking Units

Specification	230V Series	460V Series	575V Series
Model VFDB-	2015	2022	4030
Max. Motor Capacity (kW)	15	22	30
Max. Discharge Current (A) 10%ED	40	60	40
Continuous Discharge Current (A)	15	20	15
Braking Start-up Voltage (DC)	330/345/360/380/400/ 415±3V	660/690/720/760/800/ 830±6V	950±8V
DC Voltage	200—400VDC	400—800VDC	607—1000VDC
Min. Equivalent Resistor for Each Braking Unit	10Ω	6.8Ω	20Ω
Heat Sink Overheat	Temperature over +95°C (203°F)		
Alarm Output	Relay contact 5A120VAC/28VDC (RA, RB, RC)		
Power Charge Display	Blackout until bus (+—) voltage is below 50VDC		
Installation Location	Indoor (no corrosive gases, metallic dust)		
Operating Temperature	-10°C~+50°C (14°F to 122°F)		
Storage Temperature	-20°C~+60°C (-4°F to 140°F)		
Humidity	90% Non-condensing		
Vibration	9.8m/s² (1G) under 20Hz 2m/s² (0.2G) at 20~50Hz		
Mechanical Configuration	Wall-mounted enclosed type IP50		

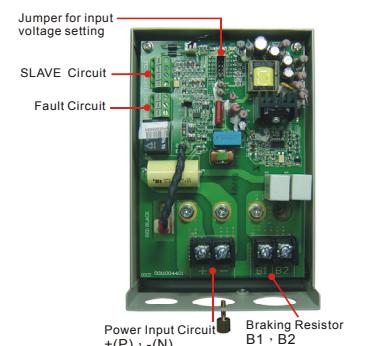
### 3 Dimensions - VFDB Braking Units



Terminal Wire Gauge

Circuit	Terminal Mark	Wire Gauge AWG (mm²)	Screw	Torque
Power Input Circuit	+ (P), - (N)	10—12AWG (3.5—5.5mm²)	M4	18 kgf-cm (15.6 in-lbf)
Braking Resistor	B1, B2	10—12AWG (3.5—5.5mm²)	M4	18 kgf-cm (15.6 in-lbf)
SLAVE Circuit	Output M1, M2 Input S1, S2	20—18AWG (0.25—0.75mm²) (with shielded wires)	M2	4 kgf-cm (3 in-lbf)
Fault Circuit	RA, RB, RC	20—18AWG (0.25—0.75mm²)	M2	4 kgf-cm (3 in-lbf)

### 4 Individual Parts and Function Explanation



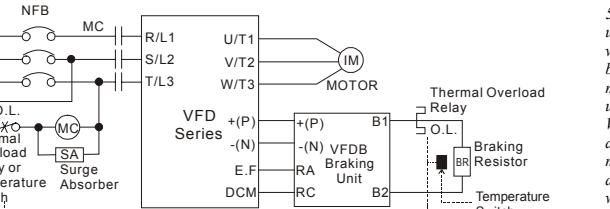
Power Input Circuit  
+ (P) - (N)

Jumper for input voltage setting

SLAVE Circuit

Fault Circuit

Braking Resistor B1, B2



Note1: When using the AC drive with DC reactor, please refer to wiring diagram in the AC drive user manual for the wiring of terminal +(P) of Braking unit.

Note2: Do NOT wire terminal -(N) to the neutral point of power system.

6. Besides using thermal overload relay to be the protection system and braking resistor, temperature switch can be installed on braking resistor side as the protection. The temperature switch must comply with the braking resistor specification or contact your dealer.

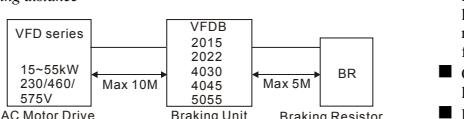
### 6 Wiring Notice



#### WARNING

- Do not proceed with wiring while power is applied to the circuit.
- The wiring gauge and distance must comply with the electrical code.
- The +(P), -(N) terminals of the AC motor drive (VFD Series), connected to the braking unit (VFDB), must be confirmed for correct polarity lest the drive and the braking unit be damaged when power on.
- When the braking unit performs braking, the wires connected to +(P), -(N), B1 and B2 would generate a powerful electromagnetic field for a moment due to high current passing through. These wires should be wired separately from other low voltage control circuits lest they make interference or mis-operation.

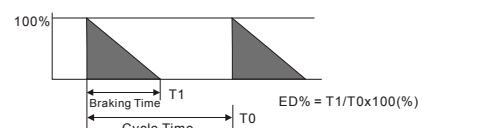
#### ■ Wiring distance



- To prevent personal injury, do not connect/disconnect wires or regulate the setting of the braking unit while power on. Do not touch the terminals of related wiring and any component on PCB lest users be damaged by extreme dangerous DC high voltage.

5. The AC Motor Drive and braking unit will be electrified at the same time while turning on the NFB (No-fuse breaker). For the operation/stop method of the motor, please refer to the user manual of the AC Motor Drives VFD Series. The braking unit will detect the inner DC voltage of the AC motor drive when it stops the motor deceleration. The extra regeneration will be dissipated away rapidly by the braking resistor in the form of heat. It can ensure the stable deceleration characteristic.

### 7 Definition for Braking Usage ED%



**Explanation:** The definition of the braking usage ED(%) is for assurance of enough time for the braking unit and braking resistor to dissipate away heat generated by braking. When the braking resistor heats up, the resistance would increase with temperature, and braking torque would decrease accordingly.

### NOTE

- Before regulating the power voltage, make sure the power has been turned off. Please set power voltage as the possible highest voltage for unstable power system. Take 380VAC power system for example. If the voltage may be up to 410Vac, 415VAC should be regulated.
- For DELTA's AC motor drive VFD Series, please set parameter (Over Voltage Stall Prevention) as "close" to disable over-voltage stall prevention, to ensure stable deceleration characteristic. For VFDB 5055, the jumper can only be put on the position as shown in the following figure. Do NOT remove the jumper to other place.

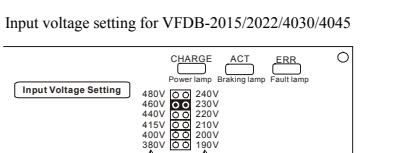
### 8 The Voltage Settings

- Regulation of power voltage: the power source of the braking unit is DC voltage from +(P), -(N) terminals of the AC motor drive. It is very important to set the power voltage of the braking unit based on the input power of the AC motor drive before operation. The setting has a great influence on the potential of the operation voltage for the braking unit. Please refer to the table below.

Table 1: The Selection of Power Voltage and Operation Potential of PN DC Voltage

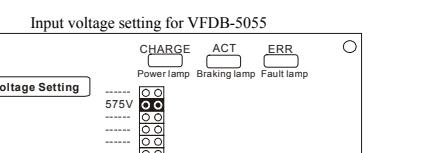
230V Model AC Power Voltage	Braking Start-up voltage DC Bus +(P), -(N) Voltage	460V Model AC Power Voltage DC Bus +(P), -(N) Voltage	575V Model AC Power Voltage DC Bus +(P), -(N) Voltage
190Vac	330Vdc	380Vac	660Vdc
200Vac	345Vdc	400Vac	690Vdc
210Vac	360Vdc	415Vac	720Vdc
220vac	380Vdc	440Vac	760Vdc
230Vac	400Vdc	460Vac	800Vdc
240Vac	415Vdc	480Vac	830Vdc

NOTE: Input Power With Tolerance ±10%



For VFDB-4030/4045 Factory setting: 460V

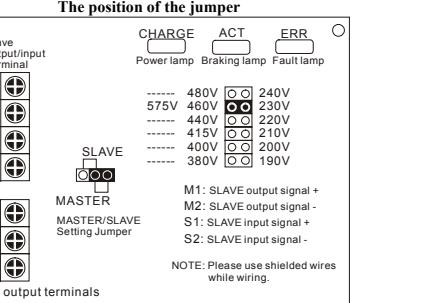
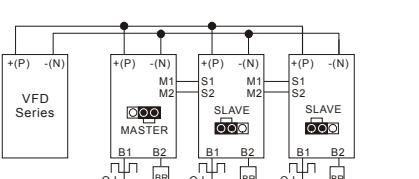
For VFDB-2015/2022 Factory setting: 230V



For VFDB-5055 Factory setting: 575V

- MASTER/SLAVE setting: The MASTER/SLAVE jumper is set "MASTER" as factory setting. The "SLAVE" setting is applied to two or more braking units in parallel, making these braking units be enabled/disabled synchronously. Then the power dissipation of each unit will be equivalent so that they can perform the braking function completely.

The SLAVE braking application of three braking units is shown as the above diagram. After wiring, the jumper of first unit shall be set as "MASTER" and that of others must be set as "SLAVE" to complete the system installation.



### 5 Basic Wiring Diagram

- Operation Explanation:**
- For safety consideration, install an overload relay between the braking unit and the braking resistor. In conjunction with the magnetic contactor (MC) prior to the drive, it can perform complete protection against abnormality.
  - The purpose of installing the thermal overload relay is to protect the braking resistor from damage due to frequent braking, or due to braking unit keeping operating resulted from unusual high input voltage. Under such circumstance, just turn off the power to prevent damaging the braking resistor.
  - Please refer to the specification of the thermal overload relay.
  - The alarm output terminals (RC, RA, RB) of the braking unit will be activated when the temperature of the heat sink exceeds 95°C. It means that the temperature of the installation environment may exceed 50°C, or the braking %ED may exceed 10%ED. With this kind of alarm, please install a fan to force air-cooling or reduce the environment temperature. If the condition not due to the temperature, the control circuit or the temperature sensor may have been damaged. At this time, please send the braking unit back to the manufacturer or agency for repair.

### 9 All Braking Resistors & Braking Units Use in the AC Drives

Voltage	Applicable Motor	Full-load Torque kg·M	Resistor Value Spec for Each AC Motor Drive	Braking Unit Model VFDB No. of Units Used	Braking Resistors		Braking Torque 10%ED	Min. Equivalent Resistor Value for Each AC Motor Drive	Typical Thermal Overload Relay Value
					HP	kW			
230V	20	15	8.248	3000W 10Ω	2015	1	BR1K5W005	2	125
	25	18.5	10.281	4800W 8Ω	2022	1	BR1K2W008	4	125
	30	22	12.338	4800W 6.8Ω	2022	1	BR1K2W6P8	4	125
	40	30	16.497	6000W 5Ω	2015	2	BR1K5W005	4	125
	50	37	20.6	9600W 4Ω	2015	2	BR1K2W008	8	125
	20	15	8.248	1500W 40Ω	4030	1	BR1K5W040	1	125
	25	18.5	10.281	4800W 32Ω	4030	1	BR1K2W008	4	125
	30	22	12.338	4800W 20Ω	4030	1	BR1K5W005	4	125
	50	37	20.6	9600W 16Ω	4045	1	BR1K2W008	8	125
	60	45	24.75	9600W 13.6Ω	4045	1	BR1K2W6P8	8	125
460V	75	55	31.11	12000W 10Ω	4055	2	BR1K5W005	8	125

# VFDB 系列煞車模組說明書

## 1 一般注意事項

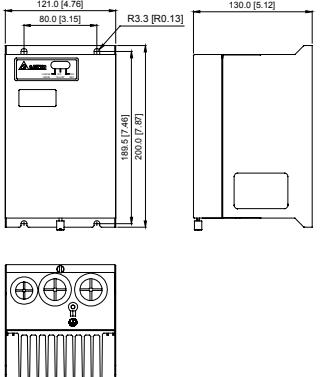
感謝您選用台達 VFDB 動力制動煞車模組。本產品主要應用於當三相感應馬達由交流馬達驅動器所驅動，在減速停止時用以吸收由馬達側所回生的能量。藉由 VFDB 制動單元將此能量以熱能的方式消耗在煞車電阻上。本產品在安裝使用前，請詳細參閱本說明書再進行施工配線，以免造成機械或人員的傷害。VFDB 動力制動煞車模組適用於本公司 VFD 所有系列的交流馬達驅動器。VFDB 制動單元需搭配煞車電阻 BR 系列，才能發揮優異的制動特性，詳細的規格及使用方法請繼續參閱本說明書。由於產品精益求精，當內容規格有所修正時，請洽詢代理商或至台達網站 (<http://www.delta.com.tw/industrialautomation/>) 下載最新版本。

## 2 規格

### VFDB 制動單元規格

使用電壓等級	230V 級	460V 級	575V 級
型號	VFDB-□□□□	2015	2022
最大適用馬達容量 (kW)	15	22	30
輸出額定	最大放電電流 (A peak) 10%ED	40	60
續放電電流 (A)	15	20	15
制動起始電壓 (DC)	330/345/360/380/400/415±3V	660/690/720/760/800/830±6V	950±8V
電源	直流電壓	200~400VDC	400~800VDC
保護	每台等效最小電阻	10Ω	6.8Ω
散熱片過熱	溫度超過 +95°C (203°F)		
故障輸出	RELAY 接點 5A 120Vac/28Vdc(RA.RB.RC)		
充電中顯示	主回路 (P-N) 電壓在 50VDC 以下熄滅		
安裝場所	屋內 (無腐蝕性氣體、金屬粉塵)		
環境溫度	-10°C ~ +50°C (14°F to 122°F)		
儲存溫度	-20°C ~ +60°C (-4°F to 140°F)		
濕度	90%RH 以下不結露		
振動	20Hz 以下 9.8m/S <sup>2</sup> (1G) ~ 20~50Hz 2m/S <sup>2</sup> (0.2G)		
機構構造	壁掛型 IP50		

## 3 尺寸- 制動單元

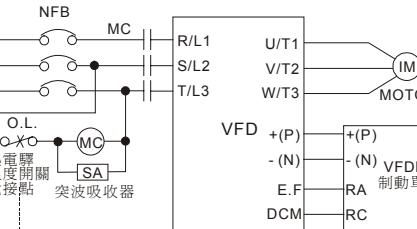


各端子使用線徑

回路名稱	端子記號	導線線徑 AWG (mm <sup>2</sup> )	螺絲規格	扭力
電源輸入回路	+ (P) - (N)	10~12AWG (3.5~5.5mm <sup>2</sup> )	M4	18 kgf-cm (15.6 in-lbf)
煞車電阻回路	B1、B2	10~12AWG (3.5~5.5mm <sup>2</sup> )	M4	18 kgf-cm (15.6 in-lbf)
運動回路	輸入 M1、M2 輸出 S1、S2	20~18AWG (0.25~0.75mm <sup>2</sup> ) (需用隔離線)	M2	4 kgf-cm (3 in-lbf)
故障回路	RA、RB、RC	20~18AWG (0.25~0.75mm <sup>2</sup> )	M2	4 kgf-cm (3 in-lbf)

## 5 基本配線圖

- 動作說明：**1. 在安裝制動單元的應用中為了安全的考量，在制動單元與煞車電阻之間加裝一積熱電驛 (O.L.)；並與交流馬達驅動器前端的電磁接觸器 (MC) 作一連鎖的異常保護。  
 2. 加裝積熱電驛的主要目的是為了保護煞車電阻不因煞車頻繁過熱而燒毀，或是因輸入電源電壓異常過高導致制動單元連續導通燒毀煞車電阻。此時只有將交流馬達驅動器的電源關閉才可避免煞車電阻燒毀。  
 3. 積熱電驛規格的選用請參考制動單元與放電電阻適用一覽表。  
 4. 制動單元中的故障輸出端子 (RC、RA、RB) 在散熱裝置溫度高於 95°C 時會動作，表示安裝環境溫度可能超過 50°C 以上，或是煞車制動 ED% 超過 10ED%；若是此類的故障請自行加裝風扇強制風冷或改善環境溫度。若非溫度原因，可能控制電路受損或溫度感測器故障，此時請送廠維修。

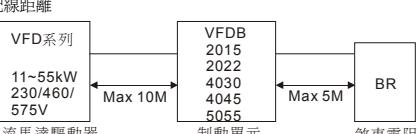


5. 本配線路在電源開關 (NFB) 開啓時交流馬達驅動器與制動單元便同時上電源，馬達的運轉／停止的方式請參考 VFD 系列的使用手冊；制動單元會在交流馬達驅動器對馬達作減速煞車時自動偵測交流馬達驅動器內部的直流通電壓，自動將過多的回生能量藉由煞車電阻以熱能的方式迅速消耗以達平穩的減速特性。

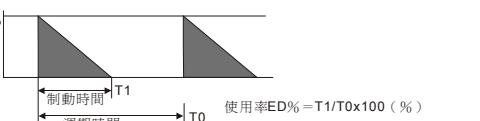
- 當交流馬達驅動器有加裝直流電抗器 (DC Reactor) 時，其煞車模組之電源輸入迴路 + (P) 端的配線方法，可參考交流馬達驅動器手冊。  
 ■ 請勿將電源輸入迴路 - (N) 端，接至電力系統之中性點。

## 6 配線注意事項

- WARNING**  
 ■ 進行配線施工時務必確認相關回路電源均為關閉狀態；配線的線徑及距離亦務必按照規定選用及施工。  
 ■ 交流馬達驅動器 (VFD) 連接至制動單元 (VFDB) 的 + (P) 、- (N) 端子有極性之分，千萬要確認再確認，否則電源一開啟制動單元立即炸毀，請務必注意。  
 ■ 制動單元在執行煞車時，+ (P) 、- (N) 、B1、B2 因有大電流通過所連接的導線瞬間將產生能量很大的電磁場；故在初期配線施工規劃時，應與其它低電壓的控制線路分離配線，以免造成不必要的干擾或誤動作。

- 配線距離  
  
 ■ 累積電阻安裝的場所不能有任何易燃性的物體、氣體、液體，最好能安裝在獨立的金屬箱內並加以風扇散熱。  
 ■ 制動單元的接地工程 230V 級請依第三種接地施工，460V 級請依特別第三種接地施工。  
 ■ 在減速煞車頻繁的場合 (超過 10ED%) 累積電阻請加裝風扇強制風冷或其它冷卻設備。  
 ■ 在通電中嚴禁修改任何配線及制動單元內部設定，更嚴禁在通電中碰觸相關配線的端子及 PCB 板中的任一元件，以免因通電中遭極度危險的直流通電造成人員傷害。

## 7 紅車使用率 ED% 的定義



說明：制定煞車使用率 ED%，主要是為了能讓制動單元及煞車電阻有充分的時間來散除因制動而產生的熱量；當煞車電阻發熱時，電阻值將會隨溫度的上升而變高，制動轉矩亦隨之減少。

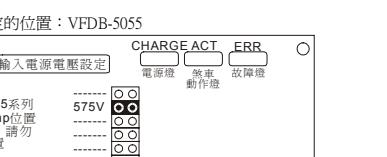
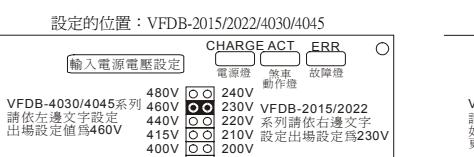
## 8 設定與調整

1. 電源電壓的調整：制動單元的電力來源是接受接交流馬達驅動器 + (P) 、- (N) 兩端供應的直流電源。因此，在配線完成準備運轉時，依交流馬達驅動器的輸入電源來設定制動單元的電源電壓是非常重要的步驟；此設定將會影響制動單元動作電壓的準位，下表為各個電壓動作準位。

表一：電源電壓的選擇與 PN 直流電壓的動作準位

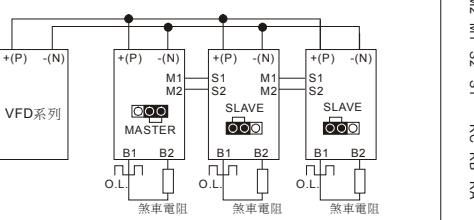
230V 級 AC 電源電壓	制動開始電壓 + (P) 、- (N) 母線 DC 電壓	460V 級 AC 電源電壓	575V 級 AC 電源電壓	制動開始電壓 + (P) 、- (N) 母線 DC 電壓
190Vac	330Vdc	380Vac	660Vdc	575Vac
200vac	345Vdc	400Vac	690Vdc	-
210vac	360Vdc	415Vac	720Vdc	-
220vac	380Vdc	440Vac	760Vdc	-
230vac	400Vdc	460Vac	800Vdc	-
240vac	415Vdc	480Vac	830Vdc	-

註：容許輸入電源有±10%的變動



2. 主動／運動的設定：制動單元在出廠時均設定在 “MASTER” 主動煞車的位置。“SLAVE” 運動位置的功能主要是應用於兩台以上制動單元並連組合的應用，可使每一台制動單元同時動作同時截止，如此每一台的消耗功率均為相等充份發揮每台的制動功能。

如下圖所示為三台制動單元連動制動的應用：當配線完成後將第一台設為 “MASTER” 主動的設定，其餘的一定要將插梢設定在 “SLAVE” 運動的位置上，如此即可完成動力制動系統的配線。



## 9 制動單元與放電電阻適用一覽表

電壓	適用馬達	全載輸出轉矩 kg·M	每台交流馬達驅動器等效煞車電阻規格	制動單元		制動電阻料號	用量	制動轉矩 10%ED	每台交流馬達驅動器等效最小電阻值	積熱電驛規格中心值	
				型式	用						
230V 系列	20	15	8.248	VFDB	2015	1	BR1K5W005	2	125	10Ω	30
	25	18.5	10.281	VFDB	2022	1	BR1K2W008	4	125	8Ω	35
	30	22	12.338	VFDB	4045	1	BR1K2W6P8	4	125	6.8Ω	40
	40	30	16.497	VFDB	5055	2	BR1K5W005	4	125	5Ω	30
	50	37	20.6	VFDB	9600W 4Ω	2	BR1K2W008	8	125	4Ω	30
	20	15	8.248	VFDB	1500W 40	1	BR1K5W040	1	125	40Ω	15
	25	18.5	10.281	VFDB	1500W 32	1	BR1K2W008	4	125	32Ω	15
	30										